

Digital Color Doppler Ultrasound System

Model

EBit 10/EBit 20/EBit 30/EBit 40/EBit 50/EBit 60/EBit 70/ EBit 80/EBit 90

V2.1

Feb 16, 2024

CHUM EBit Series-001

User Manual

CHISON Medical Imaging Co., Ltd.

We reserve the rights to make changes to this manual without prior notice.

Regulatory Requirement

This product conforms to the essential requirements of the Medical Device Regulation (EU) 2017/745. Accessories without the CE mark are not guaranteed to meet the Essential Requirements of the Medical Device Regulation This manual is a reference for the EBit series. Please verify that you are using the latest revision of this document. If you need the latest revision, contact your distributor.

△NOTE:

Important

- 1.No part of this manual may be reduced, modified, copied or reprinted, in whole or in part, without written permission from CHISON.
- 2. The contents of this manual are subject to change without prior notice and without our legal obligation.
- 3.Before operating the system, please read and understand this manual. After reading, keep this manual in an easily accessible place. If you have any question or doubt, please contact CHISON's authorized service engineer.
- 4.CHISON's Warranty only cover material and parts costs for repair, but do not cover any labor cost or onsite service cost at end user's side.
- 5. A notice to the user and/or patient that any serious incident that has occurred in relation to the device should be reported to the manufacturer and the competent authority of the Member State in which the user and/or patient is establishe.

⚠NOTE:

Important information

- 1.It is the customer's responsibility to maintain and manage the system after delivery.
- 2. The warranty does not cover the following items, even during the warranty period:
 - a)Damage or loss due to misuse or abuse with system and probes, for example, drop the probe, the liquid or the metal part fall into the system.
 - b)Damage or loss caused by Acts of God such as fires, earthquakes, floods, lightning, etc.
 - c)Damage or loss caused by failure to meet the specified conditions for this system, such as inadequate power supply, improper installation or environmental conditions.
 - d)Damage or loss caused by non-approved transportation by CHISON.
 - e)Damage or loss due to use the system outside the region where the system was originally sold.
 - f)Damage or loss involving the system purchased from a source other than CHISON or its authorized agents.
- 3.Do not make changes or modifications to the software or hardware of this system and probes.
- 4.During operate the system, if user has any doubt, difficulty or any unclear, please contact CHISON's authorized service engineer immediately. Please describe the situation clearly to solve the question in time. Before solve the question, please don't operate the system.
- 5. This system shall not be used by persons other than fully qualified and certified medical personnel.
- 6.It is prohibited to use the device for fetal sex examination, except for necessary medical needs. The device can only be sold to qualified medical institutions or doctors. The users shall fully understand and master the devices before operating. The users shall have got the qualification, and shall comply with the local laws and regulations, the local religion and customs, etc.
- 7.The System modified or repaired by people other than CHISON's qualified service engineers, CHISON shall not be liable for the system.
- 8. The purpose of this system is to provide physicians with data for clinical diagnosis. It is the physician's responsibility for diagnostic procedures. CHISON shall not be liable for the results of diagnostic procedures
- 9. This manual contains warnings regarding foreseeable potential dangers, but user shall always be alert to dangers other than those indicated as well. CHISON shall not be liable for damage or loss that results from negligence or from ignoring the precautions and operating instructions described in this operation manual.
- 10.Due to negligence not following operation manual, CHISON shall not be liable for the results.
- 11.Each time before and after ultrasound examination, please check the probe surface, probe cable and sheath whether they are abnormal, such as cracking, peeling and

deformation. Also check whether the lens is strongly fixed. Abnormal probes may cause electric shock and injure the patient. Once any abnormal, user must stop using and contact CHISON's authorized service engineer.

12.If the probe is dropped or scratched by hard part, please stop using the probe immediately. And contact CHISON's authorized service engineer to make sure the safety and effectiveness is in good condition before use.

13.If there is any liquid or metal to enter to the system, please power off the system and stop using it immediately. Please first contact CHISON's authorized service engineer to make sure it's safe before restart using it.

14.Please don't use solvents (such as paint thinner, benzine, or alcohol) or abrasive cleansers for cleaning the system (including monitor and probes, etc.). It may corrode the system and probes.

15. While the system or probe is over life time, please refer to operation manual section 9.4

16.Important data must be backed up on external memory media. CHISON shall not be liable for loss of data stored in the memory of this system caused by operator error or accidents.

17.Please put this operation manual with the system to ensure operator and manager can reach it at any time.

18.LCD display screen may have some dark or light dots, it is normal for the LCD. It does not mean that LCD screen is defective.

Caution: It is prohibited to use the device for fetal sex examination, except for necessary medical needs. The device can only be sold to qualified medical institutions or doctors. The users shall fully understand and master the devices before operating. The users shall have got the qualification, and shall comply with the local laws and regulations, the local religion and customs, etc.

Caution: The users should read the operation manual carefully before operating the devices. Turning on the device means the users have read the operation manual and accept the listed cautions, warnings, and notes in the manuals. If the users disagree and cannot accept the cautions, the users can ask for returning the device.

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Chapter 1 Introduction

This manual contains necessary information for safe system operation.

Read and understand all instructions in this manual before operating the system. Always keep this manual with the equipment, and periodically review the procedures for operation and safety precautions.

1.1 System Overview

Indications for Use

The device is a general-purpose ultrasonic imaging instrument intended for use by a qualified physician for evaluation of Fetal , Abdominal , Pediatric , Small Organ (breast,thyroid,testes) , Neonatal Cephalic , Adult Cephalic, Cardiac (adult, pediatric), Musculo-skeletal (Conventional, Superficial), Peripheral Vascular, Transesophageal, Transrectal, Transvaginal, Urology.

Contraindication

The system is NOT intended for ophthalmic use or any use that causes the acoustic beam to pass through the eye.

1.2 Contact Information

For additional information or assistance, please contact your local distributor or the appropriate support resource shown below:

CHISON website www.chison.com

Service Support CHISON Medical Imaging Co., Ltd.

Tel:0086-0510-85311707 Fax: 0086-0510-85310726 E-mail: service@chison.com.cn

Placing an Order CHISON Medical Imaging Co., Ltd.

Tel: 0086-0510-8531-0593/0937 Fax: 0086-0510-85310726 Email: export@chison.com.cn

Manufacturer CHISON Medical Imaging Co., Ltd.

No.3 Changjiang South Road, Xinwu District, Wuxi, 214028 Jiangsu, P.R. China

US Agent MR. NANPING WU, 3040 Edenberry Street, Madison, WI 53711 USA

Phone: 608-277-9432 Fax: 920-648-1584

Email: nanpingwu@yahoo.com

Caution: Federal law restricts the device to sale by or on the order of a licensed practitioner or therapist.

1.3 Configuration of the EBit series

Configuration of the System

Configuration	of the Sys	stem							
Model	EBit 10	EBit 20	EBit30	EBit 40	EBit 50	EBit 60	EBit 70	EBit 80	EBit 90
B mode	standard	standard	standard	standard	standard	standard	standard	standard	standard
B/M mode	option	standard							
M mode	option	option	standard						
Dual mode	option	option	option	standard	standard	standard	standard	standard	standard
Quad mode	option	option	option	option	standard	standard	standard	standard	standard
CFM mode	option	option	option	option	option	standard	standard	standard	standard
CPA mode	option	option	option	option	option	option	standard	standard	standard
DPD mode	option	option	option	option	option	option	option	standard	standard
PW mode	option	option	option	option	option	option	option	option	standard
B/BC mode	option	option	option	option	option	option	option	option	option
2D Steer	option	option	option	option	option	option	option	option	option
Triplex mode	option	option	option	option	option	option	option	option	option
Quadplex	option	option	option	option	option	option	option	option	option
CW mode	option	option	option	option	option	option	option	option	option
Free Steering M mode	option	option	option	option	option	option	option	option	option
HPRF	option	option	option	option	option	option	option	option	option
B-Flow	option	option	option	option	option	option	option	option	option
AutoTGC	option	option	option	option	option	option	option	option	option
Free Hand 3D	option	option	option	option	option	option	option	option	option
Stress Echo	option	option	option	option	option	option	option	option	option
Zoom	option	option	option	option	option	option	option	option	option
DICOM 3.0	option	option	option	option	option	option	option	option	option
Remote Desk	option	option	option	option	option	option	option	option	option
TDI	option	option	option	option	option	option	option	option	option
Color M mode	option	option	option	option	option	option	option	option	option
Curved Panoramic	option	option	option	option	option	option	option	option	option
Trapezoidal mode	option	option	option	option	option	option	option	option	option
Compound	option	option	option	option	option	option	option	option	option
SRA	option	option	option	option	option	option	option	option	option
Chroma	option	option	option	option	option	option	option	option	option
Elastography	option	option	option	option	option	option	option	option	option
ECG	option	option	option	option	option	option	option	option	option
integrated hard disk	option	option	option	option	option	option	option	option	option
Bodymark	standard	standard	standard	standard	standard	standard	standard	standard	standard

					DD# E	ngiiai Coi	or Boppier	C tti tibotiii	ee System
Model	EBit 10	EBit 20	EBit30	EBit 40	EBit 50	EBit 60	EBit 70	EBit 80	EBit 90
Auto IMT	option	option	option	option	option	option	option	option	option
Auto NT	option	option	option	option	option	option	option	option	option
Biopsy	option	option	option	option	option	option	option	option	option
Super Needle	option	option	option	option	option	option	option	option	option
General									
measurement	option	option	option	option	option	option	option	option	option
package									
OB									
measurement	option	option	option	option	option	option	option	option	option
package									
GYN									
measurement	option	option	option	option	option	option	option	option	option
package									
URO									
measurement	option	option	option	option	option	option	option	option	option
package									
Cardiac									
measurement	option	option	option	option	option	option	option	option	option
package									
Vascular									
measurement	option	option	option	option	option	option	option	option	option
package									
Small parts			.•		.•	.•	.•	.•	
measurement	option	option	option	option	option	option	option	option	option
package									
Pediatric	4		4	4	4	4	4	4	
measurement	option	option	option	option	option	option	option	option	option
package 4D software									
package	option	option	option	option	option	option	option	option	option
Virtual HD	option	option	option	option	option	option	option	option	option
X-Contrast	option	option	option	option	option	option	option	option	option
FHI	option	option	option	option	option	option	option	option	option
Q-Image	option	option	option	option	option	option	option	option	option
Q-flow	option	option	option	option	option	option	option	option	option
Q-beam	option	option	option	option	option	option	option	option	option
AIO	option	option	option	option	option	option	option	option	option
Standby	option	option	option	option	option	option	option	option	option
Screen Saver	option	option	option	option	option	option	option	option	option
С3-Е	option	option	option	option	option	option	option	option	option
C3S-E	option	option	option	option	option	option	option	option	option
L7-E	option	option	option	option	option	option	option	option	option
בוע	орион	option	option	option	option	option	option	option	option

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Model	EBit 10	EBit 20	EBit30	EBit 40	EBit 50	EBit 60	EBit 70	EBit 80	EBit 90
L7W-E	option	option	option	option	option	option	option	option	option
L12-E	option	option	option	option	option	option	option	option	option
Р2-Е	option	option	option	option	option	option	option	option	option
Р3-Е	option	option	option	option	option	option	option	option	option
Р6-Е	option	option	option	option	option	option	option	option	option
V6-E	option	option	option	option	option	option	option	option	option
V7W-E	option	option	option	option	option	option	option	option	option
V7-E	option	option	option	option	option	option	option	option	option
L7R-E	option	option	option	option	option	option	option	option	option
V4-EV	option	option	option	option	option	option	option	option	option
V6-EV	option	option	option	option	option	option	option	option	option
МС3-Е	option	option	option	option	option	option	option	option	option
МС5-Е	option	option	option	option	option	option	option	option	option
МС6-Е	option	option	option	option	option	option	option	option	option
C3S-D	option	option	option	option	option	option	option	option	option
L12-D	option	option	option	option	option	option	option	option	option
V7-D	option	option	option	option	option	option	option	option	option
L7-ES	option	option	option	option	option	option	option	option	option
C3S-ES	option	option	option	option	option	option	option	option	option
P2-ES	option	option	option	option	option	option	option	option	option
V7-ES	option	option	option	option	option	option	option	option	option
7B8-E	option	option	option	option	option	option	option	option	option
Т5-Е	option	option	option	option	option	option	option	option	option
МТ5-Е	option	option	option	option	option	option	option	option	option
CW2-E	option	option	option	option	option	option	option	option	option
L18-E	option	option	option	option	option	option	option	option	option
i7L-E	option	option	option	option	option	option	option	option	option
Probe	2	2	2	2	2	2	2	2	2
connector				<i>L</i>	<i>L</i>			2	2
Integrated	option	option	option	option	option	option	option	option	option
battery	option	орион	орион	орион	орион	option	орион	option	option
Footswitch	option	option	option	option	option	option	option	option	option
LCD 15 inch	standard	standard	standard	standard	standard	standard	standard	standard	standard
Trolley	option	option	option	option	option	option	option	option	option

Chapter 2 System Safety

2.1 Safety Overview

This section discusses measures to ensure the safety of both the operator and patient. To ensure the safety of both operator and patient, please read the relevant details in this chapter carefully before operating this system.

Disregarding the warnings or violation of relevant rules may result in personal injury or even loss of life for operator or patient.

Users should observe the following precautions:

- This system complies with Type BF general equipment, and the IEC standard.
- ➤Do not modify this system in any way. Necessary modifications must be made only by the manufacturer or its designated agents.
- This system has been fully adjusted at the factory. Do not adjust any fixed adjustable parts.
- ➤In the event of a malfunction, turn off the system immediately and inform the manufacturer or its designated agents.
- The power cable of the system should only be connected to a grounded power socket. Do not remove the ground cable for any reason.
- ➤Only connect this system, either electronically or mechanically, with devices that comply with the EN60601-1 standard. Recheck the leakage current and other safety performance indices of the entire system to avoid potential system damage caused by leakage from a current superposition.
- The system does not incorporate any specialized protective measures in the event it is configured with high-frequency operation devices. The operator should use caution in these types of applications.
- The system should be installed only by personnel authorized by the manufacturer. Do not attempt to install the system by yourself.
- ➤Only an authorized service engineer may perform maintenance.
- ➤Only a qualified operator, or someone under qualified supervision, should use the system.
- >Do not use this system in the presence of flammable substances, otherwise an explosion may occur.
- >Do not continuously scan the same part of a patient or expose the patient to prolonged scanning; otherwise it may harm the patient.
- ➤ When using the system for ultrasound testing, use only qualified ultrasound gel that complies with system standards.
- >Do not unplug probe when the system is in active operation. Always go to EXAM screen when need to remove the probe.
- To prevent from arm or neck injury, the operator should not stay at the same position for too long during patient scanning without taking break.
- ➤ Do not put liquid on top of the main unit.



*The system has built-in screen saver to avoid the tic mark on the display. It is not recommended to constantly turn on and off the unit.

*To dispose of this product properly, please call your local service department.

2.2 Electrical Safety

Type of protection against electric shock

●Class I Equipment

CLASS I EQUIPMENT in which protection against electric shock does not rely on BASIC INSULATION only, but includes a protective earth ground. This additional safety precaution prevents exposed metal parts from becoming LIVE in the event of an insulation failure.

NOTE: The mains supply shall be cut off after disconnecting the power line and the net power.

Degree of protection against electric shock

● Type BF Applied part (for Probes marked with BF symbol)

TYPE BF APPLIED PART providing a specified degree of protection against electric shock, with particular regard to allowable LEAKAGE CURRENT.

Level of protection against harmful ingress of water

•Parts of probe likely to come into contact with operator or patient meet the requirements of drip-proof equipment (IPX1)

Parts of probe intended to be immersed in normal use meet the requirements of watertight equipment (IPX7).

● The IP Classification of System is Ordinary Equipment (IPX0)

Safety level when used in the presence of FLAMMABLE ANAESTHETIC

MIXED WITH AIR (or WITH OXYGEN or WITH NITROUS OXIDE):

The Equipment is not suitable for use in the environment with FLAMMABLE ANAESTHETIC MIXED WITH AIR (or WITH OXYGEN or WITH NITROUS OXIDE).

Mode of operation

Continuous Operation

For maximum safety, always follow these guidelines:

- ➤ Proper grounding of the system is critical to avoid electrical shock. For protection, ground the chassis with a three-wire cable and plug, and plug the system into a hospital-grade, three-hole outlet.
- ➤Do not remove or circumvent the grounding wire.
- >Do not remove the protective covers on the system. These covers protect users from hazardous voltages. Cabinet panels must remain in place while the system is in use. A qualified electronic technician must make all internal replacements.
- ➤Do not operate this system in the presence of flammable gases or anesthetics.
- All peripheral devices (unless certified as medical grade) that are connected to the system must be powered through the electrical outlet through an optional isolation transformer.

Notice upon Installation of Product

Separation distance and effect from fixed radio communications equipment: field strengths from fixed transmitters, such as base stations for radio (cellular/cordless) telephones and land mobile radios, amateur radio, AM and FM radio broadcast, and TV broadcast transmitter cannot be predicted theoretically with accuracy. To assess the electromagnetic environment due to fixed RF transmitters, an electromagnetic site survey should be considered. If the measured field strength in the location in which the ultrasound system is used exceeds the applicable RF compliance level as stated in the immunity declaration, the ultrasound system should be observed to verify normal operation. If abnormal operation is observed, additional measures may be necessary, such as re-orienting or relocating the ultrasound system or using an RF shielded examination room may be necessary.

- •Use either power supply cords provided by or designated by CHISON. Products equipped with a power source plug should be plugged into the fixed power socket which has the protective grounding conductor. Never use any adaptor or converter to connect with a power source plug (e.g. three-prong-to-two-prong converter).
- •Locate the equipment as far away as possible from other electronic equipment.
- •Be sure to use only the cables provided by or designated by CHISON. Connect these cables following the installation procedures (e.g. wire power cables separately from signal cables).
- •Lay out the main equipment and other peripherals following the installation procedures described in this manual.

Notice against User Modification

The user should never modify this product.

User modifications may cause degradation in Electrical Safety. Modification of the product includes changes in:

- Cables (length, material, wiring, etc.)
- System configuration/components

User modifications may cause degradation in EMC performance. Modification of the product includes changes in:

- Cables (length, material, wiring, etc.)
- System installation/layout
- System configuration/components
- Securing system parts (cover open/close, cover screwing)

2.3 Label



Fig. 1 Rear panel label

2.3.1 Warning Symbols



Caution, consult accompanying documents.

This symbol advises the reader to consult the accompanying documents for important safety related information such as warnings and pre-cautions that cannot be presented on the device itself.



This mark indicates that this product contains a limited amount of hazardous substances in the Chinese Standard GB/T 26572-2011 "Limited Requirements for Restricted Substances in Electrical and Electronic Products". The numbers in the logo are the environmental protection use period of the product, indicating that under the normal use

	anditions the harmful substances will not look on he
	conditions, the harmful substances will not leak or be
	abrupt. The use of the product will not c ause serious
	pollution to the environment or cause personal or
	property serious damage, the term unit is year
Do not use the following devices near this equipment: cellular phone, radio receiver, and mobile radio transmitter, radio controlled toy, etc. Use of these devices near this equipment could cause this equipment to perform outside the published specifications. Keep power to these devices turned off when near this equipment.	This symbol indicates the item is a medical device
WASTE OF ELECTRICAL AND	The CE mark of Conformity indicates this
ELECTRONIC EQUIPMENT (WEEE): This symbol is used for Environment Protection, it indicates that	equipment conforms with the Medical Device Regulation 2017/745 [MDR]
the waste of electrical and electronic equipment must	
not be disposed as unsorted waste and must be	
collected separately. Please contact your local	
Authority or distributor of the manufacturer for	
information concerning the decommissioning of your	
equipment.	
AUTHORIZED REPRESENTATIVE IN THE EUROPEAN COMMUNITY: This symbol is accompanied by the name and the address of the authorized representative in the European Community.	Type-BF applied part
This symbol is followed by the serial number of the device.	MANUFACTURER: This symbol is accompanied by the name and the address of the manufacturer.
b Power On/off.	This symbol signifies that the user manual must
CAUTION: This Power Switch cannot isolate Mains Supply completely.	be read.
	Rx only
The "Alternating current" symbol indicates	This symbol indicates that in the united states of
that the equipment is suitable for alternating current	America, Federal law restricts the device to sale by or
only.	on the order of a licensed practitioner or therapist.
IPX7	IPX0
Protection against the effects of immersion	No protection against ingress of water (system)
(probes)	



of manufacture of products is china, and this symbol is followed by the manufacturing date of the device in the form YYYY-MM.



CORRECT: The correct connection of the battery connector

WRONG: The wrong connection of the battery connector



This symbol is accompanied by the name and the address of the importing entity



(01)069451214XXXXX (11)XXXXXX (21)XXXXXXXXX

This symbol indicates the UDI of the device, (01) is followed by the UDI-DI code of the device, (11) is followed by the manufacturing date of the device, (21) is followed by the serial number of the device.

2.4 Patient Environmental Devices

Left side:

- ♦1 LAN port
- ♦1 S-VIDEO port
- ◆2 USB ports
- ◆1 Footswitch port
- ◆1 Power in port

Rear panel:

- ◆2 Probe ports
- ♦2 USB ports
- ♦1 VIDEO OUT port
- ♦1 DVI port
- ◆1 VGA port
- ◆1 Remote port
- ◆1 ECG port

Acceptable Devices

The Patient Environmental devices shown above are specified to be suitable for use within the PATIENT ENVIRONMENT.



- ●DO NOT connect any probes or accessories without approval by CHISON within the PATIENT ENVIRONMENT.
- ●DO NOT touch patient and devices without IEC/EN 60601-1 approval to avoid the leakage current risk within the PATIENT ENVIRONMENT.

Unapproved Devices

ACAUTION:

- •DO NOT use unapproved devices.
- If devices are connected without the approval of CHISON, the warranty will be INVALID.
- The system can't be used with HF surgical equipment; otherwise the burns to patient may occur.

Any device connected to this system must conform to one or more of the requirements listed below:

- •IEC standard or equivalent standards appropriate to devices.
- The devices shall be connected to PROTECTIVE EARTH (GROUND).

ACAUTION:

Unsafe operation or malfunction may result. Use only the accessories, options and supplies approved or recommended in these instructions for use.

Peripheral used in the patient environment

The system has been verified for overall safety, compatibility and compliance with the following on-board image recording devices:

B/W video printer: SONY UP-D898MD

The system may also be used safely while connected to devices other than those recommended above if the devices and their specifications, installation, and interconnection with the system conform to the requirements of IEC/EN 60601-1.

Adapter is considered as a part of ME equipment

The connection of equipment or transmission networks other than as specified in the user instructions can result in an electric shock hazard or equipment malfunction. Substitute or alternate equipment and connections require verification of compatibility and conformity to IEC/EN 60601-1 by the installer. Equipment modifications and possible resulting malfunctions and electromagnetic interference are the responsibility of the owner.

General precautions for installing an alternate off-board, remote device or a network would include:

- The added device(s) must have appropriate safety standard conformance and CE Marking.
- There must be adequate mechanical mounting of the device and stability of the combination.
- •Risk and leakage current of the combination must comply with IEC/EN 60601-1.
- Electromagnetic emissions and immunity of the combination must conform to IEC/EN 60601-1-2.

Peripheral used in the non-patient environment

The system has been verified for compatibility, and compliance for connection to a local area network (LAN) via a wire LAN, provided the LAN components are IEC/EN 60601-1 compliant.

General precautions for installing an alternate off-board, remote device or a network would include:

- The added device(s) must have appropriate safety standard conformance and CE Marking.
- The added device(s) must be used for their intended purpose having a compatible interface.

CAUTION: Make sure using ONLY the dedicated USB disk or removable media to save or back up data.

Before connecting to the ultrasound system, make sure using the latest antivirus software on the USB disk or removable media to clean any virus. It is user's responsibility to ensure the USB disk or removable media is virus-free. Improper use of USB disk or removable media may cause the virus infections of system and eventually malfunction may occur. Such malfunction may impact the stability, effectiveness and safety of the system and probes, and users should immediately stop using the system and probes until CHISON authorized engineer has checked the system and confirm the effectiveness and safety of the system and probes.

CAUTION: Use only secure Local Area Network connection. Don't connect the ultrasound system to Internet. Make sure your hospital's firewall software is configured correctly, thus blocking incoming connection requests from Internet. Improper use of network connection may cause the virus infections of system and eventually malfunction may occur.

2.5 Biological Safety

This product, as with all diagnostic ultrasound equipment, should be used only for valid reasons and should be used both for the shortest period of time and at the lowest power settings necessary (ALARA - As Low As Reasonably Achievable) to produce diagnostically acceptable images. The AIUM offers the following guidelines:

Clinical Safety Quoted from AIUM

Approved March 26, 1997

Diagnostic ultrasound has been in use since the late 1950s. Given its known benefits and recognized efficacy for medical diagnosis, including use during human pregnancy, the American Institute of Ultrasound in Medicine herein addresses the clinical safety of such use:

There are no confirmed biological effects on patients or instrument operators caused by exposures from present diagnostic ultrasound instruments. Although the possibility exists that such biological effects may be identified in the future, current data indicate that the benefits to patients of the prudent use of diagnostic ultrasound outweigh the risks, if any that may be present.

<u>Heating</u>: Elevating tissue temperature during obstetrical examinations creates medical concerns. At the embryo development stage, the rise in temperature and the length of time exposed to heat combine to determine potential detrimental effects. Exercise caution particularly during Doppler/Color exams. The Thermal Index (TI) provides a statistical estimate of the potential temperature elevation (in centigrade) of tissue temperature. Three forms of TI are available: Soft Tissue Thermal Index (TIS), Bone Thermal Index (TIB) and Cranial Bone Thermal Index (TIC).

Soft Tissue Thermal Index (TIS). Used when imaging soft tissue only, it provides an estimate of potential

temperature increase in soft tissue.

Bone Thermal Index (TIB). Used when bone is near the focus of the image as in the third trimester OB examination, it provides an estimate of potential temperature increase in the bone or adjacent soft tissue.

Cranial Bone Thermal Index (TIC). Used when bone is near the skin surface as in transcranial examination, it provides an estimate of potential temperature increase in the bone or adjacent soft tissue.

<u>Cavitations:</u> Cavitations may occur when sound passes through an area that contains a cavity, such as a gas bubble or air pocket (in the lung or intestine, for example). During the process of cavitations, the sound wave may cause the bubble to contract or resonate. This oscillation may cause the bubbles to explode and damage the tissue. The Mechanical Index (MI) has been created to help users accurately evaluate the likelihood of cavitations and the related adverse effects.

MI recognizes the importance of non-thermal processes, cavitations in particular, and the Index is an attempt to indicate the probability that they might occur within the tissue.

2.6 Scanning Patients and Education

The Track-3 or IEC60601-2-37 output display standard allows users to share the responsibility for the safe use of this ultrasound system. Follow these usage guidelines for safe operation:

- ➤ In order to maintain proper cleanliness of the probes, always clean them between patients.
- Always use a disinfected sheath on all EV/ER probes during every exam.
- Continuously move the probe, rather than staying in a single spot, to avoid elevated temperatures in one part of the patient's body.
- Move probe away from the patient when not actively scanning.
- ➤ Understand the meaning of the TI, TIS, TIB, TIC and MI output display, as well as the relationship between these parameters and the thermal/cavitation bio effect to the tissue.
- Expose the patient to only the very lowest practical transmit power levels for the shortest possible time to achieve a satisfactory diagnosis (ALARA As Low As Reasonably Achievable).

2.6.1 Safe Scanning Guidelines

- •Ultrasound should only be used for medical diagnosis and only by trained medical personnel.
- •Diagnostic ultrasound procedures should be done only by personnel fully trained in the use of the equipment, in the interpretation of the results and images, and in the safe use of ultrasound (including education as to potential hazards).
- •Operators should understand the likely influence of the machine controls, the operating mode (e.g. B mode) and probe frequency on thermal and cavitation hazards.
- •Select a low setting for each new patient. Output should only be increased during the examination if penetration is still required to achieve a satisfactory result, and after the Gain control has been moved to its maximum value.
- Maintain the shortest examination time necessary to produce a useful diagnostic result.

- •Do not hold the probe in a fixed position for any longer than is necessary. The frozen frame and Cine loop capabilities allow images to be reviewed and discussed without exposing the patient to continuous scanning.
- •Do not use endo-cavitary probes if there is noticeable self heating of the probe when operating in the air. Although applicable to any probe, take particular care during trans- vaginal exams during the first eight weeks of gestation.
- Take particular care to reduce output and minimize exposure time of an embryo or fetus when the temperature of the mother is already elevated.
- Take particular care to reduce the risk of thermal hazard during diagnostic ultrasound when exposing: an embryo less than eight weeks after gestation; or the head, brain or spine of any fetus or neonate.
- •Operators should continually monitor the on-screen thermal index (TI) and mechanical index (MI) values and use control settings that keep these settings as low as possible while still achieving diagnostically useful results. In obstetric examinations, TIS (soft tissue thermal index) should be monitored during scans carried out in the first eight weeks after gestation, and TIB (bone thermal index) thereafter. In applications where the probe is very close to bone (e.g. trans-cranial applications), TIC (cranial bone thermal index) should be monitored.

MI> 0.3 there is a possibility of minor damage to neonatal lung or intestine. If such exposure is necessary, reduce the exposure time as much as possible.

MI> 0.7 there is a risk of cavitations if an ultrasound contrast agent containing gas micro-spheres is being used. There is a theoretical risk of cavitations without the presence of ultrasound contrast agents. The risk increases with MI values above this threshold.

TI> 0.7 the overall exposure time of an embryo or fetus should be restricted in accordance with Table 2-2 below as a reference:

TI	Maximum exposure time (minutes)
0.7	60
1.0	30
1.5	15
2.0	4
2.5	1

Maximum recommended exposure times for an embryo or fetus

•Non-diagnostic use of ultrasound equipment is not generally recommended. Examples of non-diagnostic uses of ultrasound equipment include repeated scans for operator training, equipment demonstration using normal subjects, and the production of souvenir pictures or videos of a fetus. For equipment of which the safety indices are displayed over their full range of values, the TI should always be less than 0.5 and the MI should always be less than 0.3. Avoid frequent repeated exposure of any subject. Scans in the first trimester of pregnancy should not be carried out for the sole purpose of producing souvenir videos or photographs, nor should their production involve increasing the exposure levels or extending the scan times beyond those

needed for clinical purposes.

•Diagnostic ultrasound has the potential for both false positive and false negative results. Misdiagnosis is far more dangerous than any effect that might result from the ultrasound exposure. Therefore, diagnostic ultrasound system should be performed only by those with sufficient training and education.

2.6.2 Understanding the MI/TI Display

Track-3 follows the Output Display Standard for systems that include fetal Doppler applications. The acoustic output will not be evaluated on an application-specific basis, but the global maximum de-rated Ispta must be \leq 720 mW/cm² and either the global maximum MI must be \leq 1.9 or the global maximum de-rated Isppa must be \leq 190 W/cm². An exception is for ophthalmic use, in which case the TI = max (TIS_as, TIC) is not to exceed 1.0; Ispta.3 \leq 50mW/cm², and MI \leq 0.23. Track-3 gives the user the freedom to increase the output acoustic power for a specific exam, and still limit output acoustic power within the global maximum de-rated Ispta \leq 720 mW/cm² under an Output Display Standard.

For any diagnostic ultrasonic systems, Track-3 provides an Output Indices Display Standard. The diagnostic ultrasound systems and its operation manual contain the information regarding an ALARA (As Low As Reasonably Achievable) education program for the clinical end-user and the acoustic output indices, MI and TI. The MI describes the likelihood of cavitations, and the TI offers the predicted maximum temperature rise in tissue as a result of the diagnostic examination. In general, a temperature increase of 2.5 °C must be present consistently at one spot for 2 hours to cause fetal abnormalities. Avoiding a local temperature rise above 1 °C should ensure that no thermally induced biologic effect occurs. When referring to the TI for potential thermal effect, a TI equal to 1 does not mean the temperature will rise 1 degree °C. It only means an increased potential for thermal effects can be expected as the TI increases. A high index does not mean that bio effects are occurring, but only that the potential exists and there is no consideration in the TI for the scan duration, so minimizing the overall scan time will reduce the potential for effects. These operator control and display features shift the safety responsibility from the manufacturer to the user. So it is very important to have the Ultrasound systems display the acoustic output indices correctly and the education of the user to interpret the value appropriately.

RF: (De-rating factor)

In Situ intensity and pressure cannot currently be measured. Therefore, the acoustic power measurement is normally done in the water tank, and when soft tissue replaces water along the ultrasound path, a decrease in intensity is expected. The fractional reduction in intensity caused by attenuation is denoted by the de-rating factor (RF),

$$RF = 10 (-0.1 \text{ a f z})$$

Where a is the attenuation coefficient in dB cm-1 MHz-1, f is the transducer center frequency, and z is the distance along the beam axis between the source and the point of interest.

De-rating factor RF for the various distances and frequencies with attenuation coefficient 0.3dB cm-1 MHz-1 in homogeneous soft tissue is listed in the following table. An example is if the user uses 7.5MHz frequency, the power will be attenuated by .0750 at 5cm, or 0.3x7.5x5=-11.25dB. The De- rated Intensity is also referred

to as '.3' at the end (e.g. Ispta.3).

Distance	Frequency (MHz)					
(cm)	1	3	5	7.5		
1	0.9332	0.8128	0.7080	0.5957		
2	0.8710	0.6607	0.5012	0.3548		
3	0.8128	0.5370	0.3548	0.2113		
4	0.7586	0.4365	0.2512	0.1259		
5	0.7080	0.3548	0.1778	0.0750		
6	0.6607	0.2884	0.1259	0.0447		
7	0.6166	0.2344	0.0891	0.0266		
8	0.5754	0.1903	0.0631	0.0158		

I'=I*RF Where I' is the intensity in soft tissue, I is the time-averaged intensity measured in water.

Tissue Model:

Tissue temperature elevation depends on power, tissue type, beam width, and scanning mode. Six models are developed to mimic possible clinical situations.

	Thermal Models	Composition	Mode	Specification	Application
1	TIS	Soft tissue	Unscanned	Large aperture	Liver PW
				(>1cm ²)	
2	TIS	Soft tissue	Unscanned	Small aperture	Pencil Probe
				(<1cm ²)	
3	TIS	Soft tissue	Scanned	Evaluated at	Breast color
				surface	
4	TIB	Soft tissue and bone	Scanned	Soft tissue at	Muscle color
				surface	
5	TIB	Soft tissue and bone	Unscanned	Bone at focus	Fetus head PW
6	TIC	Soft tissue and bone	Unscanned/scanned	Bone at surface	Transcranial

Soft tissue:

Describes low fat content tissue that does not contain calcifications or large gas-filled spaces.

Scanned: (auto-scan)

Refers to the steering of successive burst through the field of view, e.g. B and color mode.

Unscanned:

Emission of ultrasonic pulses occurs along a single line of sight and is unchanged until the transducer is moved to a new position. For instance, the PW, and M mode.

<u>TI:</u>

TI is defined as the ratio of the In Situ acoustic power (W.3) to the acoustic power required to raise tissue temperature by $1 \text{ }^{\circ}\text{C}$ (Wdeg), TI = W.3/Wdeg.

Three TIs corresponding to soft tissue (TIS) for abdominal; bone (TIB) for fetal and neonatal cephalic; and cranial bone (TIC) for pediatric and adult cephalic, have been developed for applications in different exams.

An estimate of the acoustic power in milli-watts necessary to produce a 1° C temperature elevation in soft tissue is:

Wdeg = 210/fc, for model 1 to 4, where fc is the center frequency in MHz.

Wdeg = 40 K Dfor model 5 and 6, where K (beam shape factor) is 1.0, D is the aperture diameter in cm at the depth of interest.

MI:

Cavitation is more likely to occur at high pressures and low frequencies in pulse ultrasound wave in the tissue, which contains the bubble or air pocket (for instance, the lung, intestine, or scan with gas contrast agents). The threshold under optimum conditions of pulsed ultrasound is predicted by the ration of the peak pressure to the square root of the frequency.

MI = Pr' / sqrt(fc)

Pr' is the de-rated (0.3) peak rare-fractional pressure in Mpa at the point where PII is the maximum, and fc is the center frequency in MHz. PII is the Pulse Intensity Integral that the total energy per unit area carried by the wave during the time duration of the pulse. The peak rare- fractional pressure is measured in hydrophone maximum negative voltage normalized by the hydrophone calibration parameter.

Display Guideline:

For different operation modes, different indices must be displayed. However, only one index needs to be shown at a time. Display is not required if maximum MI is less than 1.0 for any setting of the operating mode, or if maximum TI is less than 1.0 for any setting of the operating mode. For TI, if the TIS and TIB are both greater than 1.0, the scanners need not be capable of displaying both indices simultaneously. If the index falls below 0.4, no display is needed. The display increments are no greater than 0.2 for index value less than one and no greater than 1.0 for index values greater than one (e.g. 0.4, 0.6, 0.8, 1, 2, and 3).

Display and Report

Located on the upper middle section of the system display monitor, the acoustic output display provides the operator with real-time indication of acoustic levels being generated by the system.

For Scan

Only display and report MI, and start from 0.4 if maximum MI > 1.0, display in increments of 0.2.

Below is a simple guideline for the user when TI exceeds one limit exposure time to 4(6-TI) minutes based on the 'National Council on Radiation Protection. Exposure Criteria for Medical Diagnostic Ultrasound: I. Criteria Based on Thermal Mechanisms. Report No.113 1992'.

Operator Control Features:

The user should be aware that certain operator controls may affect the acoustic output. It is recommended to

use the default (or lowest) output power setting and compensate using Gain control to acquire an image. Other than the output power setting in the soft-menu, which has the most direct impact on the power; the PRF, image sector size, frame rate, depth, and focal position also slightly affect the output power. The default setting is normally around 70% of the allowable power depending on the exam application mode.

Controls Affecting Acoustic Output

The potential for producing mechanical bio effects (MI) or thermal bio effects (TI) can be influenced by certain controls.

Direct: The Acoustic Output control has the most significant effect on Acoustic Output.

Indirect: Indirect effects may occur when adjusting controls. Controls that can influence MI and TI are detailed under the bio effect portion of each control in the Optimizing the Image chapter.

Always observe the Acoustic Output display for possible effects.

Best practices while scanning

HINTS: Raise the Acoustic Output only after attempting image optimization with controls that have no effect on Acoustic Output, such as Gain and STC.

WARNING: Be sure to have read and understood control explanations for each mode used before attempting to adjust the Acoustic Output control or any control that can affect Acoustic Output.

Use the minimum necessary acoustic output to get the best diagnostic image or measurement during an examination. Begin the exam with the probe that provides an optimum focal depth and penetration.

Acoustic Output Default Levels

In order to assure that an exam does not start at a high output level, the system initiates scanning at a reduced default output level. This reduced level is preset programmable and depends upon the exam icon and probe selected. It takes effect when the system is powered on or New Patient is selected. To modify acoustic output, adjust the Power Output level on the Soft Menu.

2.7 Battery Handling Instructions

Caution: Read and observe the following warnings and precautions to ensure correct and safe use of Li-ion batteries.

- >Do not immerse the battery in water or allow it to get wet.
- ➤Do not use or store the battery near sources of heat such as a fire or heater.
- >Do not use any chargers other than those recommended.
- ➤ Do not reverse the positive (+) and negative (-) terminals.
- Do not connect the battery directly to wall outlets or car cigarette-lighter sockets.
- Do not put the battery into a fire or apply direct heat to it.
- ➤ Do not short-circuit the battery by connecting wires or other metal objects to the positive (+) and negative (-) terminals
- ➤Do not pierce the battery casing with a nail or other sharp object, break it open with a hammer, or step on it.
- Do not strike, throw or subject the battery to sever physical shock.

- ➤Do not directly solder the battery terminals.
- ➤Do not attempt to disassemble or modify the battery in any way.
- >Do not place the battery in a microwave oven or pressurized container.
- >Do not use the battery in combination with primary batteries (such as dry-cell batteries) or batteries of different capacity, type or brand.
- Do not use the battery if it gives off an odor, generates heat, becomes discolored or deformed, or appears abnormal in any way. If the battery is in use or being recharged, remove it from the device or charger immediately and discontinue use.
- >Do not use or store the battery where is exposed to extremely hot, such as under window of a car in direct sunlight in a hot day. Otherwise, the battery may be overheated. This can also reduce battery performance and/or shorten service life.
- ➤ If the battery leaks and electrolyte gets in your eyes, do not rub them. Instead, rinse them with clean running water and immediately seek medical attention. If left as is, electrolyte can cause eye injury.

Chapter 3 System Introduction

3.1 Consol Overview



Fig. 2 Console Overview

3.2 Physical Specification

Dimensions of main unit (approx.): 360mm (Length) $\times 125$ mm (Width) $\times 396$ mm (Height) Net weight of main unit (approx.): 7.5kg

3.3 External Interface View

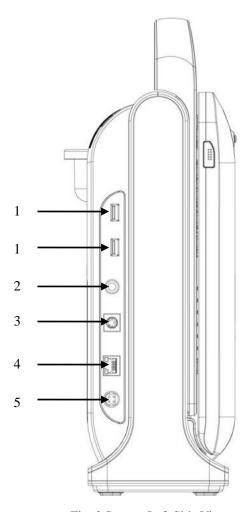


Fig. 3 System Left Side View
1. USB 2.0 2. FOOT SWITCH 3. S-VIDEO 4. Ethernet 5.Power in

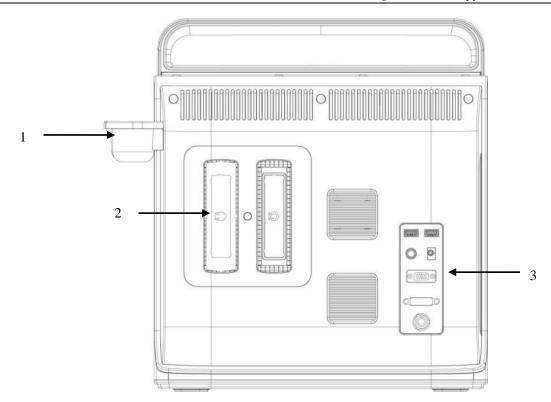


Fig. 4 Rear View

1.Probe Holder 2.Probe Ports 3.Rear External Interface

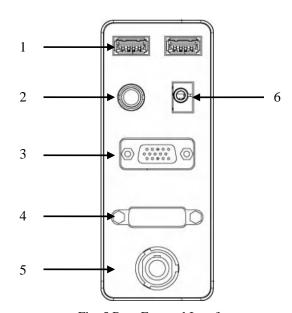


Fig. 5 Rear External Interface

1. USB 2.0 2.VIDEO OUT 3.VGA 4.DVI 5.ECG 6.REMOTE

3.4 Key System Features

1.Display mode: B,B/M,M,B/B,4B,2D Steer, CFM, PD, DPD, PW, B/BC, Triplex, Quadplex, CW, Free Steering M, HPRF, TDI, Color M, Curved Panoramic, FHI, Trapezoid Image, Elastography, 4D, Virtual HD; 2.ECG;

3. Super Needle;

- 4.Zoom and depth adjustment;
- 5.Set the total gain, contrast, frequency band, 8 segments of STC, dynamic range, persistence;
- 6.256 gray-scale image display technology, Q-image technology, stable performance, high resolution;
- 7.Image freezing and storage function; the stored images can be recalled for analysis;
- 8.Scanning direction can be changed and the image can be reversed in left/right, up/down direction;
- 9.Distance, area, circumference, volume, fetal weight, heart rate etc. measurements are available and automatic calculation of OB, cardiology are available. direct display of gestation age and expected date of child delivery; 10.Elliptical method and tracing method are provided for area/circumference measurement;
- 11. Many kinds of body marks can be displayed together with corresponding probe position indication;
- 12. Comment function in image area of the screen, special comment terms for different exam mode can be added according to user's requirement;
- 13. Display of Patient ID, Time and Date display according to real-time clock;
- 14. Trackball available for operation and measurement. Characters can be input directly by keyboard;
- 15. When one function is under operation, the corresponding key on the control panel will be brightly lit. When exiting from the function, the corresponding key on the control panel will be slightly lit;
- 16.Measure the percentage of stenosis, blood flow velocity, velocity ratio, blood flow volume and pressure gradient. Automatically measure the values of maximum velocity, minimum velocity, time interval, pulsatility index and resistance index;
- 17.Possess multi-language interface display User interface change, shear plate, printing, DICOM 3.0, biopsy guided functions;
- 18.It has permanent storage for image and cine and HDD(optional). It can also be connected to removable storage via USB 2.0 port. To realize mass storage ,can recall saved image for analysis;
- 19. Cine loop storage 256 frames real time image;
- 20. Screen rotation function make you adjust screen angle according to users' requirement 0~30 °,
- 21.Output standard PAL or NTSC video signal and VGA/DVI signal;
- 22. Print or export graphic report.

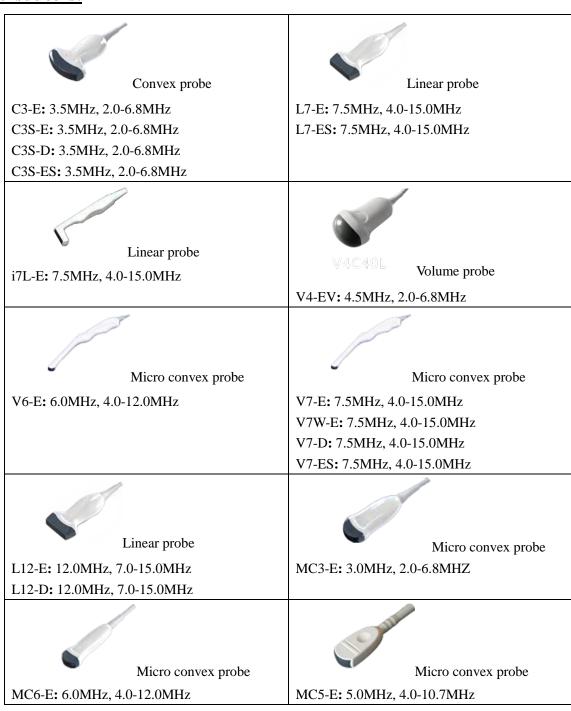
3.4.1 Image Modes

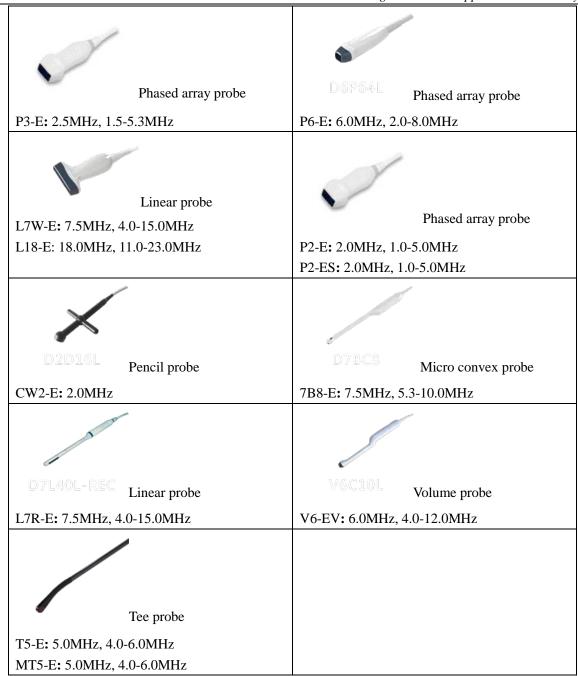
- ●B Mode
- ●B/M Mode
- ●M Mode
- ●2B Mode
- ●4B Mode
- ●2D Steer (option)
- ●CFM Mode
- ●CPA(PD) Mode
- ●DPD Mode
- ●PW Mode
- ●B/BC Mode
- Triplex Mode
- ullet Quadplex Mode
- ●CW Mode (option)
- ●Free Steering M Mode (option)
- ●TDI (option)

- ●Color M Mode (option)
- ●Curved Panoramic (option)
- Trapezoidal Mode
- ●Elastography Mode(option)
- ●ECG (option)
- •Super Needle (option)

3.4.2 Accessories

Transducers:





Peripherals

S-VIDEO, VGA, DVI output for external monitor

VIDEO output for B&W video printer

LAN port output

LAN for DICOM and image review station

USB 2.0 for flash drive

Foot Switch

AC/DC adapter: MENB1150A1949F03

Input: 100-240V~, 50-60Hz, 2.5A(2.5A-1.5A)

Output: +19V==7.8A
SL POWERTM and AULT®

Battery Pack: 18650-9000mAh-14.4V, 9000mAh, DONGGUAN YUNFAN ELECTRONICS TECHNOLOGY CO., LTD

3.5 Installation Procedures

Note: Please do not turn on the power switch until finishing all the installation and necessary preparation.

3.5.1 Environment Condition

The system should be operated under the following environment.

3.5.1.1 Operation Environment Requirement

Ambient Temperature: 10 $^{\circ}$ C $^{\circ}$ 40 $^{\circ}$ C Relative Humidity: 30% $^{\circ}$ 75%RH

Atmospheric Pressure: 700hPa~1060hPa

Strong radiation sources or powerful electromagnetic waves (e.g. electro-magnetic waves from radio broadcasting) may result in image ghosting or noise. The system should be isolated from such radiation sources or electromagnetic waves.

To prevent damage to the system, do not use in the following locations:

- >Exposed to direct sunlight
- ➤ Subject to sudden changes in temperature
- **≻**Dusty
- ➤ Subject to vibration
- ➤ Near heat generators
- ➤ High humidity



This equipment generates, uses and can radiate radio frequency energy. The equipment may cause radio frequency interference to other medical and non-medical devices and radio communications. To provide reasonable protection against such interference, this product complies with emissions limits for a Group 1, Class A Medical Devices Directive as stated in IEC/EN 60601-1-2. However, there is no guarantee that interference will not occur in a particular installation.

If this equipment is found to cause interference (which may be determined by turning the equipment on and off), the user (or qualified service personnel) should attempt to correct the problem by one or more of the following measure(s):

- ■reorient or relocate the affected device(s)
- ■increase the separation between the equipment and the affected device
- ■power the equipment from a source different from that of the affected device.
- ■consult the point of purchase or service representative for further suggestions.

3.5.1.2 Transport and Storage Environmental Requirement

The following environmental transport and storage conditions are within system tolerances:

Temperature: -5 °C ~ 40 °C

Relative Humidity:≤ 80% non-condensing Atmosphere Pressure:700hPa ~ 1060hPa

3.5.1.3 Electrical Requirements

Power Consumption: less than 150 VA

Voltage Fluctuation



Maintain a fluctuation range of less than $\pm 10\%$ of voltage labeling on rear panel of the system, otherwise the system may be damaged.

Grounding

Before connecting the power cable, connect the attached ground protection cable from Equipotentiality terminal on system rear panel to a specialized grounding device.

ANOTE

- •Please follow the outlined power requirements. Only use power cables that meet the system guidelines—failure to follow these procedures may produce system damage.
- •Line power may vary in different geographic locations. Refer to the detailed ratings on the rear panel of the system for detailed information.

● Battery

To avoid the battery bursting, igniting, or fumes from the battery; causing equipment damage, observe the following precautions: Do not immerse the battery in water or allow it to get wet. Do not put the battery into a microwave oven or pressurized container. If the battery leaks or emits an odor, remove it from all possible flammable sources. If the battery emits an odor or heat, is deformed or discolored, or in a way appears abnormal during use, recharging or storage, immediately remove it and stop using it. If you have any questions about the battery, short term (less than one month) storage of battery pack: Store the battery in a temperature range between 0 degrees C (32 degrees F) and 50 degrees C (122 degrees F).

Long term (3 months or more) storage of battery pack: Store the battery in a temperature range between-20 degrees C (-4 degrees F) and 45 degrees C (113 degrees F); Upon receipt of the EBit and before first time usage, it is highly recommended that the customer performs one full discharge/charge cycle. If the battery has not been used for >2 months, the customer is recommended to perform one full discharge/charge cycle. It is also recommended to store the battery in a shady and cool area with FCC (full current capacity). One Full Discharge/Charge Cycle Process:1. Full discharge of battery to let the EBit automatically shut down.2. Charge the EBit to 100% FCC (full current capacity).3. Discharge of Venue 40 for complete shutdown(takes one hour for discharge). When storing packs for more than 6 months, charge the pack at least once during the 6 month timeframe to prevent leakage and deterioration in performance.

3.5.1.4 Operation Space

Please leave enough free space from the back of the system to ensure well ventilation.

Caution: Leave enough free space from the back of the system; otherwise, with the increasing of the temperature inside the unit, malfunction may occur.

3.5.1.5 System Positioning & Transporting

Moving the System

When moving or transporting the system, take the precautions described below to ensure maximum safety for personnel, the system and other equipment.

Before Moving the System



>Press 4 s, system will forced shut down and completely switch off the system.

Disconnect all cables from off-board peripheral devices (external printer, etc.) from the console.

⚠NOTE

- To prevent damage to the power cord, DO NOT pull excessively on the cord or sharply bend the cord while wrapping it.
- >Store all probes in their original cases or wrap them in soft cloth or foam to prevent damage.
- Replace gel and other essential accessories in the appropriate storage case.
- Ensure that no loose items are left on the console.

When Moving the System

Carry the system with handle, or put the system on the cart to move it.



Walk slowly and carefully when moving the system.

Do not let the system strike walls or doorframe.

Transporting the System

Use extra care when transporting the system in a vehicle. After preparing the system as described above, take the following additional precautions:

- Only use vehicles that are suitable for transport of the system.
- ▶ Before transporting, place the system in its original storage carton.
- Load and unload the system to a vehicle parked on a level surface.
- Load the unit abroad the vehicle carefully and over its center of gravity. Keep the unit still and upright.
- Ensure that the transporting vehicle can bear the weight of system plus the passengers.
- >Secure the system firmly with straps or as directed within the vehicle to prevent movement during transport.

Any movement, coupled with the weight of the system, could cause it to break loose.

> Drive carefully to prevent damage from vibration. Avoid unpaved roads, excessive speeds, and erratic stops or starts.

3.5.2 Powering the System

3.5.2.1 Acclimation Time

After being transported, the unit requires one hour for each 2.5 °increment if its temperature is below 10 °C or above 40 ℃.



Please keep at least 20 to 30 cm spare space away from the back of the system to ensure well ventilation. Otherwise, with the increasing of the temperature inside the unit, malfunction may occur.

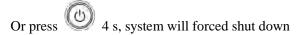
3.5.2.2 Connecting the electric power

After making sure that the AC power supply in hospital is in normal status, and this AC voltage type matches to the power requirements indicated on the label of system, then please connect the plug of power cord to the POWER IN socket at the rear panel of the system, and connect the other end of power cord to the AC power supply socket in hospital.

Please use the power cable provided by the manufacturer, other type of power cable is not allowed.



Press and pop up dialog for shut down. Click the enter key then power off.



ACAUTION

Connecting the system to the wrong AC power supply may cause damage to the system and danger to the operators and animals.

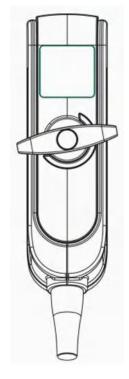
3.5.3 Probe Installment

Caution: Please only use the probes provided by manufacturer for this model, other types of probes are not allowed to use with this system! Otherwise it may cause the damage to the system and the probe.

ACAUTION

Before connecting the probe, please carefully check the probe lens, probe cable and probe connector to see whether there is anything abnormal, such as cracks, falls off. Abnormal probe is not allowed to connect to the system; otherwise there is possibility of electricity shock.

- ▶ Hold the probe connector lock switch, and insert the connector socket vertically.
- Release the probe lock switch.
- > Check the locked probe with one hand to make sure that it's not loose, and it's securely connected.



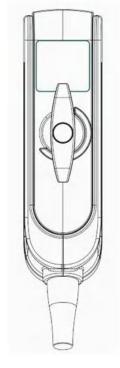


Fig. 6 Probe connector "Unlock" status

Fig. 7 Probe connector "Lock" status

ACAUTION

➤Only power supply at "turn off" state, can install / take-down the probe, otherwise it will damage the machine or the probe.

➤ When installing and disassembling probe, please put the probe head inside the probe holder, it can prevent the probe falling down to the ground.

3.5.3.1 Probe Disassembly

Turn the dead lock switch 90degree in counterclockwise direction, extract probe connector plug vertically.

3.5.4 Accessories Installment

Caution: Please only use the optional parts provided or suggested by manufacturer! Using other types of optional devices may cause the damage to the system and the connected optional devices.

3.5.4.1 Video printer installment

- 1.Put video printer stably.
- 2. Connect cable of video printer to video port in the back of the device. And connect the other side to video signal output port in the rear side.
- 3.Connect the printer line to print control port in the printer rear side, and connect the other side to the print control port in the unit rear side.
- 4. Connect power cable of video printer to power system.
- 5. Adjust printer parameter preset according to the type of printing paper.

Caution: Do not use any other power cable to replace 3-wire power cable manufacturer provides, otherwise there is danger of electric shock.

Video printer sign introduction

: Video signal input port
: Video signal output port
: Print control port
: Video printer switch

3.5.4.2 Graphic & PC printer installment

Put the printer stably; connect printer cable to USB port in the left side of the unit. Connect the power cable of the printer to power system.

ACaution: Please see packing list for fundamental configuration!

Chapter 4 Control Panel

4.1 Keyboard Appearance

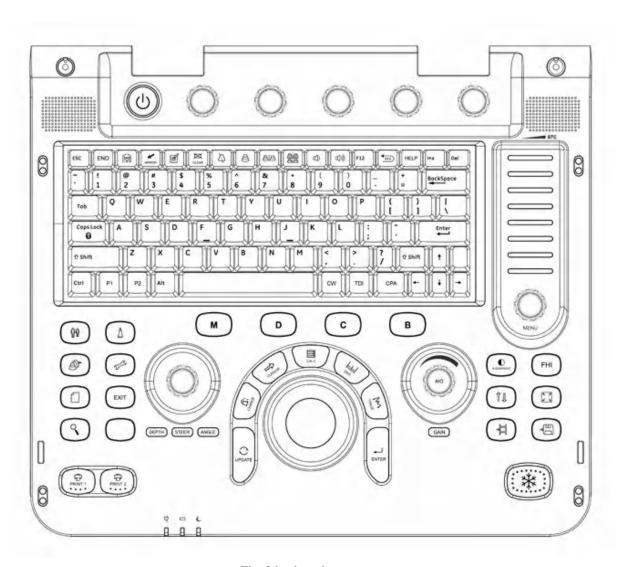


Fig. 8 keyboard appearance

4.2 Alphanumeric Keyboard

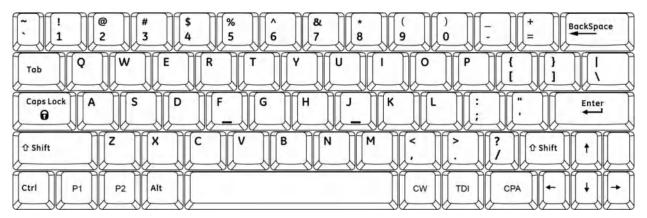


Fig. 9 Alphanumeric Keyboard

The alphanumeric keys are used for inputting patient number, name, character and figure etc.

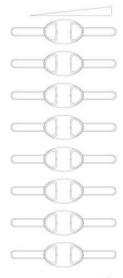
4.3 Function Keys/Knobs

Key/knob Icon	Key/knob's name	Function description
(0)	Switch	Turn on or off the device.
ŶŶ	Patient	Set up a new patient data, input name and other information.
A	Probe	Press this key for selecting probe. It can only select the connected probe.
	Review	File management of system, you can view and edit the patient data.
S	Setup	Press this key to get in or out the system setting page.
	Report	Produce/ Save/ Recall an examination report.
EXIT	Exit	Press this key can exit measurement, dialog, and menu.
9	Zoom	Press this key to enter into image zoom.
PRINT 1 PRINT 2	Print 1 & print 2	PRINT1: print the screen image by video printer connected to the system. PRINT2: print the report by printer connected to the system (Only report page works). Or print the image in the scanning page; Or print the image in the review page.
В	В	Display B mode.
C	С	Display CFM mode.

Key/knob Icon	Key/knob's name	Function description
D	D	Display PW mode.
M	M	Display B/M mode. Press this key to change the mode between B/M and M.
Scolini-ART	X-CONTRAST	Press this key to activate the X-CONTRAST.
FHI	FHI	Press this key to open or close the FHI function.
11	Up and Down Invert	Press this key to invert the image from up and down.
	Full screen	Press this key to enter into or quit full screen display mode.
4	Cine	Press this key to save the current cine loop.
	Save	Press this key to save the current image.
*	Freeze	Press this key to freeze or unfreeze the current image.
MENU	Menu	Press the MENU knob for second time to select the item and adjust the parameters. Press this knob for third time to exit from current item. Rotate the MENU knob to select the item
GAIN	AIO_GAIN	Press the knob to activate AIO, automatic optimization image. Rotate the knob to adjust the gain of current mode.
DEPTH STEER ANGLE	DEPTH_STEER_ANGLE	Press the knob to switch the knob function between depth, steer and angle. Rotate the knob to adjust the activated function.
ESC	ESC	This key's function is the same as key EXIT.
END	END	Press this key to finish the current exam.
	Bodymark	Press this key to enter into body mark working status, select the body mark and confirm the probe scanning position on the screen.
ABROW	Arrow	Press this key to enter into arrow status. Add arrows icon to the image area.

Key/knob Icon	Key/knob's name	Function description
	Comment	Press this key to enter into annotation status, and add
		annotations in the image area on the screen.
CIEAR	Clear	Press this key to clear all the measurement lines, body mark, and annotations.
	Biopsy	Press this key to activate biopsy.
	Single B	This key's function is the same as key B. Display B mode.
	2B	Press this key to enter into 2B mode.
aa aa	4B	Press this key to enter into 4B mode.
(d) (d))	Volume	Press the volume key to adjust PW volume.
318	SYS	Press this key to recovery system.
HELP	Help	Press this key to show tooltips.
P1 P2	P1_P2	The reserved hotkeys.
СРА	СРА	Press this key to enter into CPA mode.
TDI	TDI	Press this key to enter into TDI mode.
cw	CW	Press this key to enter into CW mode.

4.3.1 STC



STC can be used for adjusting gain compensation in different image depth.

4.3.2 Parameter Control Keys/Knobs



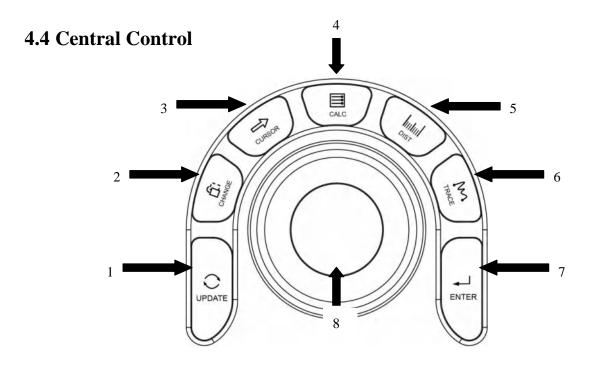








Increase/decrease the corresponding parameters of the screen, or open/close the function.



1. UPDATE 2.CHANGE 3.CURSOR 4.CALC 5. DIST 6.TRACE 7.ENTER 8.Trackball

Key/knob's name	Function description
	This multifunction key is work with trackball. The function switches with the
ENTER	unit status. Such as, set the cursor position, body mark position, comment
	position, toggle trackball function, selected the menu, and confirm the input.
LIDDATE	This multifunction key is work with trackball. The function switches with the
UPDATE	unit status. Such as, call the annotation and back in measuring.
CURSOR	Press this key to show or hide the cursor.
CHANGE	Press this key to change the menu.
DIST	Press this key to enter into distance measurement.
TRACE	Press this key to enter into trace measurement.
CALC	Press this key to enter into measurement software package.
	Trackball is the main operation tool on screen. Position calipers in
Trackball	measurement, the function of the trackball is different under diverse working
	status.

4.5 Indicator Light







From left to right: Adapter Indicator, Charge Indicator, and Sleep Indicator.

- •Adapter Indicator: when the main unit connects to the adapter with power supply, the indicator lights, otherwise extinguishes.
- •Battery Indicator: When the battery is charging, the indicator lights yellow. Once the battery is charged, the indicator lights green. When the battery volume is too low, the light flashes.
- Sleep Indicator: When the main unit is in sleep mode, the indicator lights, otherwise extinguished.

4.6 Information Area Indicating Machine Status



Left-to-Right of the up row: hard disk, cable network, USB

- •Hard disk: press this icon to show the capacity of disc to used save data or USB flash disk in current system
- •Cable network: show the present situation of cable network; press this icon to show the IP address of current system.
- •USB: show whether this system connects USB flash disk or not, press this icon to show USB safely remove interface.

Left-to-Right of the down row: input method, task queue, battery gauge

- •Input method: press this icon to switch between uppercase and lowercase characters.
- Task queue: press this icon to show task and its situation. To terminate the task, delete, and so on.
- •Battery gauge: show the connecting situation of the battery, just press this icon to show the present State of charge and discharge, remaining electric quantity and available time.

Chapter 5 Operation and Exam Mode

This chapter mainly describes the process of the normal operation of the device, including the preparation before examination, how to get the image, optimize the image, add comments, body mark and so on.

5.1 Preparing the System for Use

5.1.1 The Device Inspection

- 1. The device is placed stability;
- 2. The grid voltage AC 100-240V, 50Hz-60Hz;
- 3. Cable is properly connected, firm and ground, the adapter is properly connected to the device;
- 4. Probe is connected and fixed.

5.1.2 Power On

Press to start the machine, wait for the system to enter the user interface, activate the probe into the B mode.

5.2 Choose Exam Mode

5.2.1 The Probe Identification

The system default automatically identifies the current probe type, when the probe is inserted, Press switch the probe.

CAUTION: Please connect or disconnect the probe only after the system is freezing, in order to ensure stability and extend the service life of the probe.

5.2.2 Mode Selection

In probe selection interface, probe and clinical application selection page is displayed, you can choose needed probe and inspection part, and press the default into the B mode, start scan detection.

NOTE: The system has been set clinical application preset before leaving factory, each probe has its own preset.

The detailed operation steps of the clinical application preset of the probe, please refer to the preset section.

5.3 Patient Data Entry

Press the

to display the Patient screen.

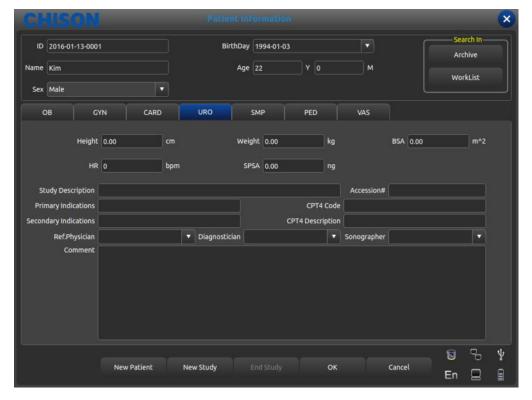


Fig. 10 Patient's Information Screen

Function Buttons on Patient screen:

[Archive]: Operation on the patient information which has already existed;

[Worklist]: Recall patient information in worklist. And need to open the DICOM function;

[New Patient]: Create a new patient information identity;

[New Study]: Choose exam applications (OB, GYN, CARD and so on) for the new patient;

[End Study]: Edit patient's exam item;

[OK]: Save patient information;

[Cancel]: Cancel the operation of new patient information;

Operation Methods:

- 1. Move the Trackball to the position of inputting character, then input patient information by character keyboard.
- 2.Use the Trackball and the **[ENTER]** key to switch between different input options: ID, patient name, doctor's name, birthday (It can be automatically calculated when input age), age (It can be automatically calculated when input birthday), gender.
- 3. Select the exam items, and input the regular inspection information.
- 4. After inputting the required information, click on the **[OK]** button to save the patient information, the system will return to the B mode.
- 5.Recall information of the previous patient, you can use the Archive or Worklist to recall patient information to exam.

CAUTION: Creating a diagnostic record, you should check the accuracy of the patient information

before saving measurement or image; otherwise, it will be stored in the wrong patient records. After checking the patient, press the to save the patient information in the system.

5.4 Image Interface Display



Logo 2, Control menu 3, Image status prompt 4, Image parameter area
 System state prompt 6, Image parameter area 7, Gray-scale strip
 Start point of scanning 9, Image Region 10, Cine loop

5.5 Image Mode

Image mode: B, B/B, 4B, B/M, M, CFM, CPA, DPD, PW, CW, TDI, Free Steering M mode, Color M Mode, Curved Panoramic, Elastography, they can be shifted by the mode key.

5.5.1 B Mode

Press [B] key, and display the single B Mode image, B Mode is the basic mode for two-dimensional scanning and diagnosis.

5.5.2 B/B Mode

Press [2B] key to display double B mode images side by side. One image is in real-time status; the other is in frozen status. The real-time image has start scan marker and ruler marker .Press [2B] key in B/B mode, the original active image is frozen while the original frozen image is activated.

5.5.3 4B Mode

Press [4B] key to enter into 4B mode, the screen will display four B mode images side by side, but only one image is in real-time status. Pressing it again can switch the real-time status among four images.

5.5.4 B/M Mode

Press [M] key, a real time B mode image and a real-time M-mode image will be displayed at the same time. And a sample line will appear in the B mode image area, which indicates the active sample position for M image on the B image area. Click the position on the B image area to fix the position of sampling line.

5.5.5 M Mode

Press [M] key again, B mode image will disappear; M mode image is still active on the whole screen. M mode image stands for the tissue movement status at the sampling line. The M mode image varies with time, so it is mainly used for cardiac applications.

5.5.6 CFM Mode

CFM is a Doppler mode intended to add color-coded qualitative information concerning the relative velocity and direction of fluid motion within the B mode image.

CFM is useful to see flow in a broad area. It allows visualization of flow in the CROI, whereas Doppler mode provides spectral information in a smaller area. CFM is also used a stepping stone to Doppler mode. You can use CFM to locate flow and vessels prior to activating Doppler.

In CFM mode, move the trackball to change the position of sampling box. Activate the **[STEER]** knob and rotate the knob to adjust the angle of color sampling box (if current probe is linear probe). Press **[ENTER]** key to fix the position of color sampling box. At this time adjusts the size of color sampling box through moving trackball. Press **[ENTER]** key again and move trackball to change the color sampling position again.

Press [C] key to enter into CFM mode; after [C] key light is on, rotate the [GAIN] knob for adjusting the gain of CFM.

CFM mode Exam Procedure:

- Follow the same procedure as described under B mode to locate the anatomical area of interest.
- After optimizing the B mode image, add Color Flow.
- Move the color region of interest CROI as close to the center of the image as possible.
- ➤Optimize the color flow parameters so that a high frame rate can be achieved and appropriate flow velocity can be visualized.
- ▶ Press [FREEZE] key to hold the image in cine memory.
- Record color flow image as necessary.

CFM Scanning Hints:

PRF: increase/decrease the PRF on the color bar. Imaging of higher velocity flow requires increased velocity scale values to avoid aliasing

Wall Filter: affect low flow sensitivity versus motion artifact

Color Map: allow you to select a specific color map. It shows the direction of the flow and highlights the

higher velocity flows.

Color Gain: amplify the overall strength of echoes processed in the CROI **Persistence:** affect temporal smoothing and color Doppler 'robustness'.

5.5.7 B/BC Mode

In active color mode, turn the [B/BC] item on to display a real B mode image at the right side of the screen and active Color mode image at the left side of the screen.

5.5.8 CPA(PD) Mode

Power Doppler Imaging (PD) is a color flow mapping technique used to map the strength of the Doppler signal coming from the flow rather than the frequency shift of the signal. Using this technique, the ultrasound system plots color flow based on the number of reflectors that are moving, regardless of their velocity. PD does not map velocity, therefore it is not subject to aliasing.

Press [CPA] key to enter into the CPA mode.

Direction PD mode

In Power Doppler (CPA) mode, press [MENU] knob to pop up the PD Menu . Rotate [MENU] knob to select the DPD Mode and press [MENU] knob to enter into DPD mode.

If you need go back to PD mode from DPD mode, you could press [CPA] key or select the PD mode item in the DPD mode.

5.5.9 PW Mode

Doppler is intended to provide measurement data concerning the velocity of moving tissues and fluids. PW Doppler lets you examine blood flow data selectively from a small region called the Sample Volume.

The X axis represents time while the Y axis represents velocity in either a forward or reverse direction.

PW Doppler is typically used for displaying the speed, direction, and spectral content of blood flow at selected anatomical sites.

PW Doppler can be combined with B mode for quick selection of the anatomical site for PW Doppler examination. The site where PW Doppler data is derived appears graphically on the B mode image (Sample Volume Gate). The Sample Volume Gate can be moved anywhere within B mode image.

PW mode Exam Procedure:

>Get a good B mode image. Press [C] key to help locate the vessel you wish to examine.

▶ Press [**D**] key to display the sample volume cursor and gate.

>Position the sample volume cursor by moving the Trackball left and right. Position or re-size the sample

volume gate by moving the Trackball up and down, then press [ENTER] key.

➤ Press [UPDATE] key to display PW Doppler spectrum and the system will run in combined B+Doppler mode. The Doppler signal can be heard through the speakers.

➤ Optimize the PW Doppler spectrum as necessary.

Ensure that the sample line is parallel to the blood flow.



to hold the trace in cine memory and stop imaging.

➤ Perform measurements and calculations, as necessary.

> Record results with your recording devices.



to resume imaging.

Repeat the above procedure until all relevant flow sites have been examined.

➤ Replace the probe in its respective holder.

When entering Duplex mode for the first time, the Doppler spectrum is not activated. The Doppler Sample Volume appears in the default position, and the B mode image or 2D (either B or Color) mode are active. Moving the Trackball will change the Sample Volume position. Press the [ENTER] key to toggle the Trackball function between Sample Volume Gate position and size. Press the [UPDATE] key after the Sample Volume Gate is defined to activate the Spectral Doppler mode. Press the [UPDATE] key for second time to toggle back to 2D (B or Color) update and deactivate the Spectral Doppler.

Doppler mode Scanning Hints:

The best Doppler data will be got when the scanning direction is parallel to the direction of the blood flow; when the scanning direction is perpendicular to the anatomic target, you can get the best B mode image, so you should keep the balance as you don't usually get both an ideal B mode image and ideal Doppler data simultaneously.

PRF: adjust the velocity scale to accommodate faster/slower blood flow velocity. Velocity scale determines pulse repetition frequency.

Wall Filter: remove the noise caused by vessel or heart wall motion at the expense of low flow sensitivity.

Baseline: adjust the baseline to accommodate faster or slower blood flows to eliminate aliasing.

Angle: optimize the accuracy of the flow velocity. It estimates the flow velocity in a direction at an angle to the Doppler vector by computing the angle between the Doppler vector and the flow to be measured. This is special useful in vascular applications where you need to measure velocity.

Doppler Gain: allow you to control the background information of spectral.

Sweep Speed: control speed of spectral update.

Doppler Sample Volume Gate Position and Size (Trackball and SET)

Move the sample volume on the B mode's Doppler cursor. The gate is positioned over a specific position within the vessel.

To move Doppler cursor position, turn the trackball left or right until positioned over the vessel.

▶To move sample volume gate position, move the trackball up or down until positioned inside the vessel.

➤To size sample volume gate, press [ENTER] key to toggle trackball function from sample volume gate positioning to sizing, then move the trackball to change sample volume gate size.

5.5.10 CW Mode

Continuous Wave Doppler allows examination of blood flow data all along the Doppler cursor rather than from any specific depth. Gather samples along the entire Doppler beam for rapid scanning of the heart. Range gated CW allows information to be gathered at higher velocities.

It works with a phased array or pediatric probe.

If the velocity of the blood flow is even too high for the HPRF mode to detect, you have to try CW mode. Press [CW] key to enter CW mode when the probe supports CW mode.

5.5.11 TDI Mode

TDI mode is tissue Doppler mode, which is intended to provide information of low-velocity tissue motion, specifically for cardiac movement. Only phased array probe is available for TDI function.

5.5.12 Color M Mode

Color M mode is used for fetal cardiac applications. Color flow overlays color on the M mode image using velocity and variance color maps. The color flow wedge overlays the B mode image and M mode timeline. The color flow maps available in M mode are the same as in CFM mode.

Color M mode is a Doppler mode intended to add color coded qualitative information concerning the relative velocity and direction of fluid motion within the M mode image.

If the system is in color mode and the probe supports Color M mode (e.g. phased array probe), press [M] key to enter Color M mode.

5.5.13 2D Steer

2D Steer is available for linear probes. It can steer the beam to obtain the left or right image and enlarge the area without to rotate the probes.

In B mode, press menu knob to pop up B Menu, adjust 2D Steer item to change 2D steer angle.

5.5.14 Trapezoidal Mode

Trapezoidal image is available for linear probes. In B mode, press menu knob to pop up B Menu, turn Trapezoidal Mode menu on to enter to Trapezoidal Mode.

5.5.15 Free Steering M Mode

Free steering M mode is only available on phased array probe. This mode can give you the ability to manipulate the cursor at different angle and position. The M mode display changes as per the M cursor position.

User can activate the Steering M mode using Soft Menu. Turn the item Steering M on, and turn Angle to rotate free steering M line .The system provides maximum 3 free steering M line and you can select either of them with **[ENTER]** key.

Trackball: used to move the free steering M line.

Angle: used to rotate the free steering M line.

5.5.16 Curved Panoramic

Moving the probe to get a series of B mode images, Press and turn the menu on, select panoramic item, turn it on. The system will enter into Curved Panoramic mode.

5.5.17 Elastography Mode

Elastography shows the biological tissue elasticity properties with the ultrasound imaging system. It records the ultrasound signals before and after tissue distortion caused by applying external or internal forces. Based on the recorded signals, it analyses, estimates and displays the strain of biological tissue.

In B mode, turn elastography menu on can enter into elastography mode.

Change the size and the position of the Elastography box by using the trackball.

Change between size and position by using the [ENTER] key.

5.5.18 ECG

The ECG module is a device that provides the 3 lead ECG signal acquisition for cardiac application. It is not intent for the ECG diagnostic purpose as in the 12-lead module. In the cardiac application, the ECG trace is displayed on the bottom of the screen. For echo-stress, the R-wave triggering is used to gate or synchronize the image acquisition. The ECG has 3 leads: LL (left leg, RED), LA (left arm, BLACK), RA (right arm, WHITE). LA is for reference, which usually provides a bias voltage from the ECG module, and the LL, LA are the two signals from the body and going to the differential input of the ECG isolation amplifier.

The ECG control is in the soft-menu available for the cardiac probe, it allows the user to set up the following control:

ECG ON/OFF: turn on/off the ECG trace. ECG Invert: turn on/off the ECG invert.

ECG GAIN: increase or decrease the ECG gain.

ECG POS: set the ECG trace position. **ECG Velocity:** set the ECG Velocity.

5.5.19 Biopsy and Super Needle

1. How to enter into Biopsy

Activate the [Biopsy] and press the [MENU] knob to show or hide biopsy line.

2. How to adjust the biopsy

After the biopsy line shows, press the **[ENTER]** key to activate the adjustment function of biopsy line, horizontal rolling the trackball can translate the biopsy line, vertical rolling the trackball can adjust the line angle, press the **[UPDATE]** key to set the default biopsy line position.

3.Super Needle

Super needle is used for enhance the needle image in the B mode image. After turn on the super needle, super needle and needle angle function will be active and user can adjust the needle angle to optimize the image for needle only (The angle is 5 degree per step.).

5.6 B Image Menu & Parameters

Menu & Parameters	Function description	
Gain	In real status, rotate [GAIN] knob to adjust the Gain, and the range is 0~255, the step	
Gain	is 5.	
	STC curves can be used for adjusting gain compensation in different image depth.	
STC	Drag the slide of STC to adjust the value.	
	STC curve will disappear automatically 1 second later after stopping adjustment.	
Donth	Press [DEPTH_STEER_ANGLE] selection knob until the indicator of [DEPTH] is	
Depth	lit, and then rotate the knob to change the depth of image.	
Zoom	Press to appear the zoom box, press [UPDATE] key and move trackball to change the zoom ratio.	
	B mode image and B/M mode image can be reversed horizontally and vertically.	
	Activate the [L/R Flip] and press the [MENU] knob to invert the image from left and	
	right.	
	iight.	
	Press , the displayed image is reversed in the up-down direction.	
	The horizontal flip status indicators of the upper-left corner of the image window	
Invert	have the following meanings:	
	The meaning of the symbol "O" indicating the probe initiative scanning position "O"	
	situated in the left indicates that the first scanning line in the left of the screen is	
	corresponding to the initiative scanning position of the probe,	
	"Situated in the right indicates that the first scanning line in the right of the screen	
	is corresponding to the initiative scanning position of the probe.	
EIII	FHI	
FHI	Press to turn on or off FHI function.	
AIO	Press the [AIO] knob to activate the AIO function.	
	Full screen the image area. Press to activate the function; Press (EXIT),	
Full Screen Show	or again to exit full screen show.	
	When full screen shows, press [MENU] knob to show the menu of current mode	
	(except bodymark, annotation, measurement).	
Freq	In real status, rotate the corresponding knob of [Freq] to adjust the frequency.	
	Dynamic range is used for adjusting the contrast resolution of B mode image and	
D	mode image, compressing or enlarging the display range of gray scale.	
Dynamic	At the real-time status, rotate the corresponding knob of [Dynamic] to adjust	
	dynamic. The range is 60 to 165.	

Menu & Parameters	Function description
	In B mode, 9 focus points can be selected simultaneously, and the number controlled
Focus Num	by the depth, SRA and Compound.
	Rotate the corresponding knob of [Focus Num] to adjust, and the range is 1~9.
Focus Pos.	Rotate the corresponding knob to change Focus Position.
G 1	In real status, rotate the corresponding knob of [Compound] to turn it on or off.
Compound	The SRA can't be edited after opening the compound.
SRA	In real status, rotate the corresponding knob of [SRA] to turn it on or off.
Q-Image	In real status, rotate the corresponding knob of [Q-Image] to adjust, the range is 0~3.
	In real status, adjust the contrast and resolution.
Persistence	In real status, rotate the corresponding knob of [Persistence] to adjust. The range is
	0~7.
	Scan Line Density function is only valid for the image in B mode, B/B mode, B/M
	mode or 4B mode image. The line density has two types: high density and low
Density	density. High density means better image quality while low density image has higher
-	frame rate.
	Rotate the corresponding knob of [Density] adjust the line density.
4 D	Acoustic power means the acoustic power transmitting from the probe.
A Power	Rotate the corresponding knob of [A power] to adjust, and the range is 0~100%.
G	Rotate the corresponding knob of [Scan Width] to adjust the scan width of the
Scan Width	corresponding size.
	Smoothness function is used for restraining the image noise and performing axial
Smooth	smooth processing to make the image smoother.
	Rotate the corresponding knob of [Smooth] to adjust, and the range is 0~7.
	Edge enhancement is used for enhancing the image outline. In this way the user can
Edge Enhance	view the tissue structure more clearly.
	Rotate the corresponding knob of [Edge Enhance] to adjust, and the range is 0~6.
7 Cf	Adjust the size of the ruler.
Zoom Coef	Rotate the corresponding knob of [Zoom Coef] to adjust; the range is 60%~100%.
Transpaidal Mada	Activate the [Trapezoidal Mode] and press the [MENU] knob to turn on or off the
Trapezoidal Mode	trapezoidal function.
2D Steer	Activate the [2D Steer] and press the [MENU] knob to turn on or off the 2D Steer
2D Steel	function.
Super Needle	Activate the [Super Needle] and press the [MENU] knob to turn on or off the Super
Super Needle	Needle function.
	Show or hide biopsy.
	Activate the [Biopsy] and press the [MENU] knob to show or hide biopsy line.
Biopsy	After the biopsy line shows, press the [ENTER] key to activate the adjustment
	function of biopsy line, horizontal rolling the trackball can translate the biopsy line,
	vertical rolling the trackball can adjust the line angle, press the [UPDATE] key to set
	the default biopsy line position.
Center Line	Show or hide Center Line.
Center Line	Press the [MENU] knob to show or hide Center line.
Q-Beam	Activate the [Q-Beam] and press the [MENU] knob to turn on or off the Q-Beam
Q-Dealli	function.

Menu & Parameters	Function description
Curved Panoramic	Activate the [Curved Panoramic] and press the [MENU] knob to turn on or off the
	Curved Panoramic function.
Elastography	Activate the [Elastography] and press the [MENU] knob to turn on or off the
	Elastography function.
ECG	Activate the [ECG] and press the [MENU] knob to turn on or off the ECG function.
4D	Activate the [4D] and press the [MENU] knob to turn on or off the 4D function.
Virtual HD	Activate the [Virtual HD] and press the [MENU] knob to turn on or off the Virtual
	HD function.

5.6.1 Utility Menu

This function includes post processing, slide show and other items. Press [MENU] knob, then choose Utility selection, it will appear Utility options.

Menu & Parameters	Function description
	Chroma:
	Adjust the type of the chroma.
	Activate [Chroma], and rotate [MENU] knob to select the Chroma type, the range is
	0~31.
	2D Map:
	Select the type of the scale curve.
	Activate [2D Map], and rotate [MENU] knob to select the scale curve type, the range
Post Process	is 0~4.
Post Process	Gamma:
	Adjust image gray value parameters.
	Activate [Gamma], and rotate [MENU] knob to select the B Gamma parameters, the
	range is 0~8.
	B Rejection:
	Adjust image gray scale inhibition parameters
	Activate [B Rejection], and rotate [MENU] knob to adjust B Rejection parameters,
	the range is 0~256.
Brightness	Activate [Brightness], and rotate [MENU] knob to adjust the brightness of screen.
Slide show	Activate the [Slide show] to enter into slide show mode.

5.7 M Image Menu & Parameters

Menu & Parameters	Function description
Gain	In real status, rotate [GAIN] knob to adjust the Gain, and the range is 0~255, the step
	is 5.
STC	STC curves can be used for adjusting gain compensation in different image depth.
	Drag the slide of STC to adjust the value.
	STC curve will disappear automatically 1 second later after stopping adjustment.
Depth	Press [DEPTH_STEER_ANGLE] selection knob until the indicator of [DEPTH] is
	lit, and then rotate the knob to change the depth of image.

Menu & Parameters	Function description	
Wichia & Latameters	B mode image and B/M mode image can be reversed horizontally and vertically.	
	Rotate the corresponding knob of [L/R Flip] to invert the image from left and right.	
	Rotate the corresponding know of [L/R Filp] to invert the image from left and right.	
	Press the Press the Up-down direction.	
	The horizontal flip status indicators of the upper-left corner of the image window	
Invert	have the following meanings:	
	The meaning of the symbol "O" indicating the probe initiative scanning position "O"	
	situated in the left indicates that the first scanning line in the left of the screen is	
	corresponding to the initiative scanning position of the probe,	
	"O" situated in the right indicates that the first scanning line in the right of the screen	
	is corresponding to the initiative scanning position of the probe.	
FHI	Press to turn on or off FHI function.	
AIO	Press the [AIO] knob to activate the AIO function.	
	Full screen the image area. Press to activate the function; Press EXIT,	
Full Screen Show	or again to exit full screen show.	
	When full screen shows, press [MENU] knob to show the menu of current mode	
	(except bodymark, annotation, measurement).	
M 2D Man	Rotate the corresponding knob of [M 2D Map] knob to select the scale curve type,	
M 2D Map	the range is 1~20.	
Speed	Rotate the corresponding knob of [Speed] to adjust M speed, and the range is 1~4.	
M Chroma	Rotate the corresponding knob of [M Chroma] to select the Chroma type, the range	
ivi Ciliollia	is 0~8.	
Layout	Rotate the corresponding knob of [Layout] to select the layout of B/M image.	

5.8 CFM/CPA/DPD Image Menu & Parameters

Menu & Parameters	Function description
Gain	In real status, rotate [GAIN] knob to adjust the Gain, and the range is 0~255, the step
	is 5.
Denth	Press [DEPTH_STEER_ANGLE] selection knob until the indicator of [DEPTH] is
Depth	lit, and then rotate the knob to change the depth of image.
Color Invert	Press the or rotate the corresponding knob of [Color Invert] to invert the
	color of flow. (CFM mode only)
FHI	Press to turn on or off FHI function.
AIO	Press the [AIO] knob to activate the AIO function.
Full Screen Show	Full screen the image area. Press to activate the function; Press or again to exit full screen show.

Menu & Parameters	Function description
	When full screen shows, press [MENU] knob to show the menu of current mode
	(except bodymark, annotation, measurement).
Freq	In real status, rotate the corresponding knob of [Freq] to adjust the frequency.
	Press [DEPTH_STEER_ANGLE] selection knob until the indicator of [STEER] is
Steer	lit, and then rotate the knob to change the steer of linear image ROI. Or rotate the
	corresponding knob of [Steer] to change the steer of linear image ROI.
Wall Filter	Rotate the corresponding knob of [Wall Filter] to adjust wall filter, and the range is
wan rinei	0~3.
Color Man	Rotate the corresponding knob of [Color Map] knob to select the color type, the
Color Map	range is 0~8. (CFM mode only)
PRF	Rotate the corresponding knob of [PRF] to Adjust PRF, adjustment range depends on
rkr	probe.
Persistence	Rotate the corresponding knob of [Persistence] to adjust. The range is 0~7.
Density	Rotate the corresponding knob of [Density] adjust the line density, high or low.
	Adjust the position of baseline.
Base Line	Rotate the corresponding knob of [Baseline] to change position of baseline,
	adjustment range from -3~3.
CF Mode	Activate [CF Mode], and rotate [MENU] knob to adjust CF mode, velocity or
Cr Mode	variance.
Wall Thre.	Activate [Wall Thre.], and rotate [MENU] knob to adjust wall thre., adjustment
wan Tine.	range from 0~14.
Blood Effection	Activate [Blood Effection], and rotate [MENU] knob to adjust blood effection,
Blood Effection	smooth or resolution.
A Power	Activate [A power] and rotate [MENU] knob to adjust, and the range is 0~100%.
B/BC	Activate the [B/BC] and press the [MENU] knob to turn on or off the B/BC mode.
Q-Flow	Activate the [Q-Flow] and press the [MENU] knob to turn on or off the Q-Flow
Q-110W	function.
HPRF	Activate the [HPRF] and press the [MENU] knob to turn on or off the HPRF
III'NI'	function.

5.9 PW/CW Image Menu & Parameters

Menu & Parameters	Function description
Gain	In real status, rotate [GAIN] knob to adjust the Gain, and the range is 0~255, the step
	is 5.
Angle	Press [DEPTH_STEER_ANGLE] selection knob until the indicator of [ANGLE] is
	lit, and then rotate the knob to change the angle of sample gate.
Invert	Press the or rotate the corresponding knob of [Invert] to invert the spectrum.
FHI	Press to turn on or off FHI function.
AIO	Press the [AIO] knob to activate the AIO function.

Menu & Parameters	Function description
Full Screen Show	Full screen the image area. Press to activate the function; Press ,
	or again to exit full screen show.
	When full screen shows, press [MENU] knob to show the menu of current mode (except bodymark, annotation, measurement).
Steer	Press [DEPTH_STEER_ANGLE] selection knob until the indicator of [STEER] is
	lit, and then rotate the knob to change the steer of linear image ROI. Or rotate the
	corresponding knob of [Steer] to change the steer of linear image ROI.
Freq	In real status, rotate the corresponding knob of [Freq] to adjust the frequency.
Chroma	Rotate the corresponding knob of [Chroma] to select the Chroma type, the range is $0\sim28$.
Speed	Rotate the corresponding knob of [Speed] to adjust PW speed, and the range is 0~2.
Audio	Adjust audio volume.
	Rotate the corresponding knob of [Audio] to adjust audio volume, adjustment range from 0~255.
Triplex Mode	Rotate the corresponding knob of [Triplex Mode] to turn on or off triplex mode.
PRF	Rotate the corresponding knob of [PRF] to Adjust PRF, adjustment range depends on probe.
	Adjust the position of baseline.
Base Line	Rotate the corresponding knob of [Baseline] to change position of baseline, adjustment range from 0~6.
D 2D Map	Rotate the corresponding knob of [D 2D Map] knob to select the D 2D map, the range is 1~20.
Wall Filter	Activate [Wall Filter] and rotate [MENU] knob to adjust wall filter, and the range is 0~3.
Spectrum Enhance	Activate [Spectrum Enhance] and rotate [MENU] knob to adjust spectrum enhance, adjustment range from 0~3.
Dynamic Range	Activate [Dynamic Range] and rotate [MENU] knob to adjust dynamic range, adjustment range from 46~67.
A Power	Activate [A power] and rotate [MENU] knob to adjust, and the range is 0~100%.
Quadplex	Activate the [Quadplex] and press the [MENU] knob to turn on or off the Quadplex
	function.

5.10 Image and Cine Disposition

5.10.1 The Principle of Cine Storage

In real image status, the image can be stored in the movie memory in chronological order, maximum frames can be set. The maximum number of frames of the film storage can be set, please refer to preset chapter.

If the movie memory is full, the recent frame saved into memory, the previous frame removed from memory.

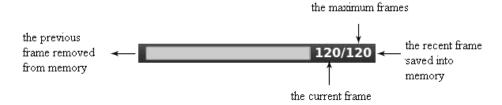


Fig. 11 Cine loop indicate diagram

5.10.2 Manual Loop

Press to freeze image, pop cine playback bar, at this time, move trackball to play by hand.

5.10.3 Automatic Loop

After freezing image, press [Play/Pause] to play, press it again to stop.

Press [ENTER] key to choose the area of automatic playback area needed.

5.10.4 Loop Range Set

Rotate the corresponding knob of [Start Pos] and [End Pos] to set the loop start position and end position, the loop range settled.

Rotate the corresponding knob of [Reset Ranges] to reset the loop range to maximum.

5.10.5 Save and Recall Image

Press to save current image, the image will be displayed below the screen;

If you need to recall images that have been stored, move cursor to needed image, press **[ENTER]** key to recall it; or you can recall archived patient's information to recall image, please refer to archive chapter.

5.10.6 Save and Recall

In freeze status, press to save cine, then it will be displayed below the screen, move cursor to needed cine, press [ENTER] key to recall cine.

5.10.7 Delete image

After recalling the image, press the [Del] key to delete the selected file.

5.10.8 Send image

After recalling the images, rotate the corresponding knob of [Send] to send images to USB flash disk, net storage, DICOM storage and print.

Hint: Activate the DICOM before DICOM storage and print.

5.11 Edit Comment

5.11.1 Overview

The comment is to enter text or symbols on the image.

Enter COMMENT: Press enter into comments status; or input characters with alphanumeric keyboard, the system will enter into comments status too.



Comment means input the words or symbols on images for making explanation. Add comments can through keyboard input directly or using the default comments.

The default comments are classified by examination mode as follows:

Classification	Function Description
Abdomen	Abdomen, general anatomy term
Obstetrics	Anatomy term of Obstetrics
Gynecology	Anatomy term of Gynecology
Heart	Anatomy term of Heart
Small Parts	Anatomy term of Small Parts
Lesion	Lesion term: Abdomen, Obstetrics, Gynecology, Heart, Small
	Parts

NOTE: If you need to custom the default comments, refer to the preset section.

5.11.2 Input Characters

Operation:

- 1.Pressed, then system will go into the comment process; or input characters with alphanumeric keyboard, the system will enter into comments status too.
- 2. Move the cursor to the position where need to comments.
- 3.Input characters at cursor position by keyboard then press [ENTER] key to confirm.



5.11.3 Input Comment Library Characters

- 1.In comment status, move trackball to image area to edit;
- 2.Rotate the corresponding knob of [Font size] to adjust front size of comments, the range is 10~20;
- 3.Rotate [MENU] knob to select needed comments, then press [MENU] knob to exit;

5.11.4 Edit Quick Comments

- 1. Rotate the corresponding knob of [Edit] to pop quick comment edit box;
- 2.Input customized comments;
- 3.Press [Done] to finish edit, press [X] to cancel edit;

5.11.5 Input Quick Comments

- 1.Press [Text] to select needed quick comments;
- 2. Adjust front size of comments;
- 3. Press the corresponding knob of [Input] to place comments in the image area;

5.11.6 Move Comments

- 1.In comment status, move trackball to the comment, press [ENTER] key to activate it;
- 2. Move trackball to place the comment to target area;
- 3.Press [ENTER] key again to confirm the comment;

5.11.7 Edit Comments

- 1.In comment status, move trackball to the comment, press [ENTER] key to activate it
- 2.Press [BACKSPACE] key to delete unnecessary characters;
- 3.Press [ENTER] key to confirm;

5.11.8 Delete Comments

5.11.8.1 Delete Characters

In comment status, activate the comment that need to be deleted, then press the **[ENTER]** key, it will display "|" on the screen, press **[BACKSPACE]** key to delete the character.

5.11.8.2 Delete Single Comment

Activate the comment that needs to be deleted, press [Del] key to delete comment;

5.11.8.3 Delete All Contents of the Comment

Don't activate the single comment; press to delete all characters that has input;

Caution: Press [Del] key, but it will delete the measurement and body mark at the same time;

5.11.9 Set the Position of Default Comment

Operation:

- 1. Press the corresponding knob of [Save Home Pos.] to move cursor to the initial position;
- 2.Press the corresponding knob of [Load Home Pos.] to set the initial position;

5.12 Set Body Mark

5.12.1 General Description

The body mark indicates patient's examination position and the direction of probe scan on the image.

Body marks are divided into: obstetric, abdomen, gynecology, heart and small parts, each has different body mark. Each type of body mark automatically is corresponding to current examination mode.

Icon:

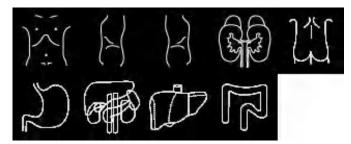


Fig. 12 Abdomen Mark

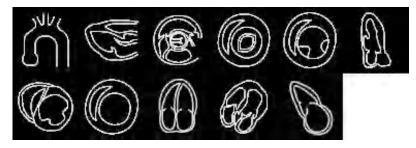


Fig. 13 Cardiac Mark



Fig. 14 Obstetric Mark

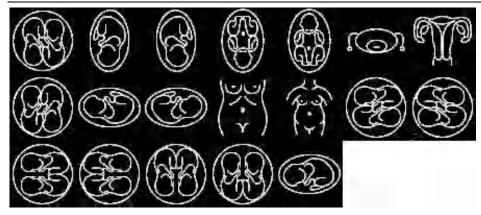


Fig. 15 Gynecology Mark

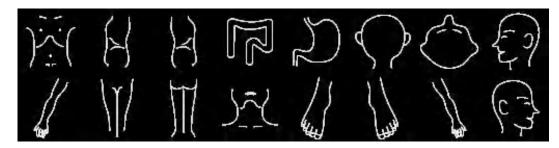


Fig. 16 Pediatric Mark

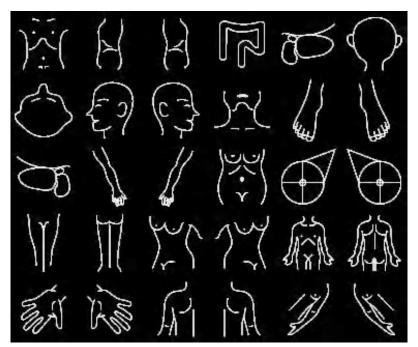


Fig. 17 Small Part Mark



Fig. 18 Urology Mark

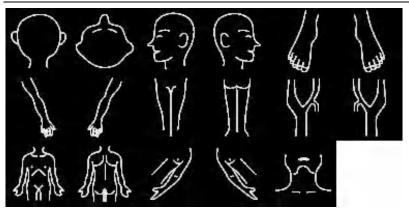


Fig. 19 Vascular Mark

5.12.2 Body Mark Operation

Operation:

- 1.Press to enter into the body status.
- 2. Select the body mark that you need.
- 3.Move trackball after adding the body mark image and then adjust the position of probe. Rotate [MENU] or [ANGLE] knob can adjust the probe direction. Press [ENTER] key to confirm when adjustment was finished.
- 4. Move the Trackball to change the position of the body mark;
- 5. If you want to exit from the body mark function, press again or to exit; 6. Press to exit body status and the body mark is fastened to the screen.
- 7.Press or [**Del**] key to delete the body mark.

5.13 Set the Direction of Arrow

Operation:

- 1.Press to display arrow;
- 2.Press [CHANGE] key to select cursor type: arrow or cross. And change the size of the cursor.
- 3. Adjust the position of probe. Rotate [MENU] or [ANGLE] knob can adjust the probe direction.
- 4.Press [ENTER] key to confirm when adjustment was finished.
- 5.Press to exit the arrow settings.
- 6.Press [Del] key to delete the arrows one by one.
- 7.Press to clear all the arrows inputted.

5.14 Image Browse

Press to enter image information browsing interface. Press [ENTER] key to any function in the image.



Fig. 20 Review interface

- ●**ID:** ID of Current patient.
- •Name: Current patient's name.
- •Information: Enter into current patient's information interface.
- Report: Enter into current patient's report interface;
- •Send images: Send image to USB hard disk, DICOM storage and print;
- •Print images: print the image which be chosen, it will be printed as the arrangement set;
- Delete images: Delete selected image;
- Row* Column: Select image's format;
- ●Pre page: Page up;
- ●Next page: Page back;
- •New Exam: Exit current examination and open a new dialog box.
- Continue Exam: Exit image browsing interface and go on checking current patient;
- Archive: Open up archive management interface;
- Cancel: Turn off image browsing interface;

5.15 Archive Management

Archive management can search for patient's information which has been stored in system. Press [Archive] to

archive management interface, all process can be opened up by moving cursor.

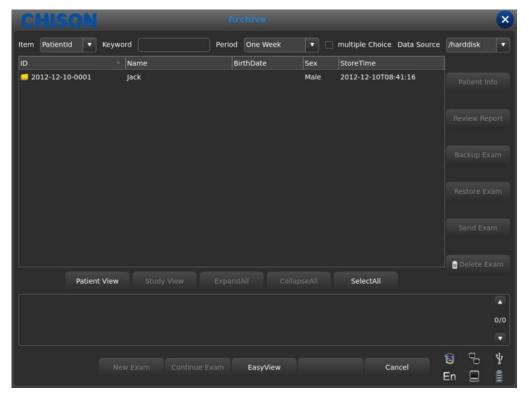


Fig. 21 Archive interface

- Item: Type selection, select Patient's ID or Name;
- **Keyword:** Search for key words;
- •Period: Time filter, select today, one week, one month, three months, six months, recent one year and all;
- Multiple Choice: Multiple choice;
- Dada Source: Path choice, select hard disk or U disk;
- Patient info: Enter into patient's information interface;
- Review Report: Enter into report interface;
- Backup Exam: Select examination information to USB hard disk;
- Restore Exam: Recover examination information from USB hard disk;
- •Send Exam: Send selected examination information remotely to USB hard disk or DICOM Storage/Print (Need to activate the DICOM);
- Delete Exam: Delete selected examination information;
- Patient View: Change display mode of information;
- Expand All: Select Patient View, it will display sub-directory;
- Collapse All: Exit sub-directory;
- Select All: Select all examination information;
- •New Exam: Exit current patient's examination;
- Continue Exam: Exit archive management interface and go on checking current patient;
- Easy View: Exit archive management interface and open up image browsing interface;
- Cancel: Exit archive management interface and go on checking current patient;

5.16 Report

Move cursor to the images and press [ENTER] key to add the image into the report page. The report can be

saved and printed. It is convenient for the doctor to view and edit the patient's information.

Reports contain normal report, abdominal report, cardiac report, small part report etc. Move the cursor to the required report page and press **[ENTER]** key to choose.

Press and the system pop up the report page of the current exam mode. Change the other exam mode report by the drop-down box.



Fig. 22 Report Interface

- Report Title: Report options, different kinds of report can choose, such as Normal, OB/GYN etc.
- **Hosp:** Display the hospital name.
- **Abdomen Report:** Display the kind of report.
- Patient Name: Display the patient name.
- •Age: Display the patient age.
- •Sex: Display the patient sex.
- •Patient ID: Display the patient ID
- **Diagnostic:** Input the diagnostic instructions.
- **Description:** Input the description of symptom.
- **Tips:** Input note information.
- •Send DICOM SR: After activating DICOM, send DICOM structural report to server
- **•Print:** Print the report with image.
- **Export:** Export the PDF report to the U disk.
- •Save: Save the report in system.
- The image on the right side: Press [ENTER] key on the image to add the image into the report.

5.17 DICOM

5.17.1 DICOM Worklist

Press [Worklist] button in Patient Interface, pop up the following dialog box

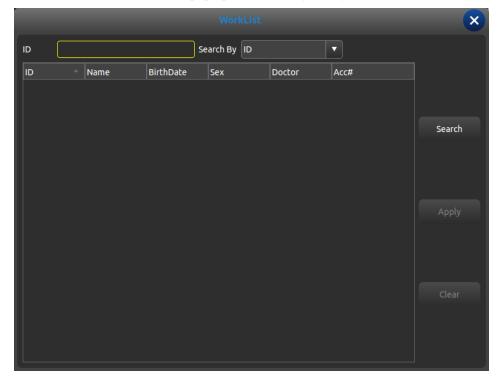


Fig. 23 Worklist Interface

•ID: input ID or some characters, fuzzy query needs server

•Search By: select term , ID or name;

ID: display the ID of patients

Name: display the names of patients

•BirthDate: display the birth date of patients

•Sex: display sex of patients

Doctor: display names of doctorsAcc#: display the NO. of patients

•Search: press this button to do search operation

•Apply: select the searched patient and press this button , input all patient information into the new patient interface

•Clear: clear all searched content.

5.17.2 DICOM Storage

Check the "Send while saving" in setting, then DICOM storage when saving cine and images. Press send button in archive or freeze interface. DICOM Send interface as follows:

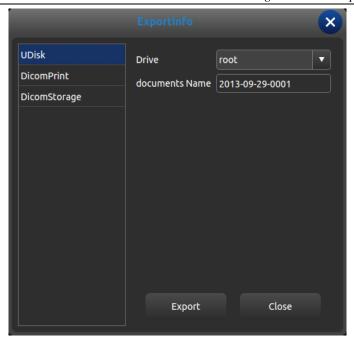


Fig. 24 DICOM Send Interface

Select DICOM Storage in left, choose DICOM server and press Export button to DICOM storage. Enter Task Queue and watch or edit DICOM process.

5.17.3 DICOM Print

DICOM Print operation is the same as DICOM storage

5.17.4 DICOM SR

Press Send DICOM SR button in report interface, this task is added into Task Queue.

Chapter 6 Measurement and Calculation

Main content of this chapter:

Normal calculation and measurement on B mode image and M mode image, OB calculation and Urology measurement etc., system can enter into corresponding measurement mode depend on current exam mode, and enter into the corresponding report depend on the measurement mode.

System has built-in the default measurement according to the exam mode, the change of measurement please refers to the chapter of preset settings.

<u>CAUTION:</u> Please select the most appropriate ultrasound images, measurement tools and measurement methods for measurements according to your diagnosis needs. The final measurement results must be determined and verified by a physician. Measurement accuracies are affected by many non-technical factors, for example operator's experience, patient's status. Please do not only use the ultrasound measurement results as the sole basis for diagnosis, please always use other clinical information to do integrated diagnostics.

6.1 Keyboard for Measurement

6.1.1 Trackball

Trackball is used to move the cursor, main functions are as follows:

- 1. Before starting a measurement, use the trackball to choose the menu options;
- 2.After starting a measurement, move the trackball to move the cursor, during the measurement, the cursor should not be moved out image area;
- 3. During the Ellipse method measurement, use trackball to change the length of short axis.
- 4.Update the moving of the measurement result, move the trackball to change the position of the measurement result.

6.1.2 [ENTER]

During the measurement, the functions of [ENTER] key are as follows:

- 1. When cursor is on the menu, press the key to choose the options and start the measurement.
- 2. During the measurement, press the key to anchor the start point and end point.

6.1.3 [UPDATE]

- 1.Before the measurement, press **[UPDATE]** key to change the measurement method, such as ellipse, trace. The changeable measurement item has "<>".
- 2.During the measurement, **[UPDATE]** key is used to switch the start point and end point, long axis and short axis when the measurement is not finished.
- 3.During the distance measurement, press **[ENTER]** key to fix the start point, when the end point is not fixed, press **[UPDATE]** key to switch the start point and end point.
- 4. During the Ellipse measurement, when fix the long axis, but the short axis is not fixed, press [UPDATE] key

to switch the long axis and short one.

6.1.4 [CLEAR]

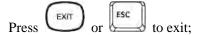
Press to delete all the measurement results, comments and traces.

6.1.5 [Del]

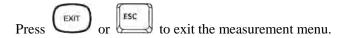
Press [Del] key to roll back the measurements step by step.

6.1.6 [CHANGE]

Press [CHANGE] to switch other menu;



6.1.7 [Exit]



6.1.8 Parameters control key

Press the corresponding key to update the function and use the function.

6.2 B Mode General Measurement Methods

The system B mode contains Distance, Ellipse, and Trace.

6.2.1 Meas. Distance

Measurement steps:

- 1.Press the [CALC] key to enter into measurement. Update the [distance] item in the menu or press the quick measure key [DIST], it will display a segment "+"icon.
- 2.Move the "+"icon by cursor to fit the one point of the line. Press **[ENTER]** key to fix the start point and the cursor can be moved to the next position.
- 3. Press [UPDATE] key can change the activated point, and fit the other point of the line.
- 4. Move the cursor to the end-point, press [ENTER] key again to complete the measurement.
- 5. After the measurement, the result will display in the measurement results area.
- 6.Repeat the steps from 1 to 4 to start next "distance" measurement.



Each group of measurement is limited, if the measurement results beyond, it will begin a new group of measurement automatically.

6.2.2 Ellipse

Measurement steps:

- 1.Press the [CALC] key to enter into measurement. Update the [Ellipse] item in the menu or press the quick measure key [Ellipse], it will display a segment "+"icon.
- 2. Move the "+"icon by cursor, Press **[ENTER]** key to fix the point and the cursor can be moved to form a round.
- 3.Press [UPDATE] key can exchange the activated point and the fixed point.
- 4. Move the cursor to the end-point of the ellipse, press **[ENTER]** key to fix the axis, at the same time, the next axis be updated, and can change the size of the axis by the cursor.
- 5. Now press [UPDATE] key can exit to the step 4.
- 6. After fixing the next axis, can press [ENTER] key to complete the measurement.
- 7. After the measurement, the result will display in the measurement results area.
- 8. Repeat the steps from 1 to 6 to start next "ellipse" measurement.

⚠Note:

Each group of measurement is limited, if the measurement results beyond, it will begin a new group of measurement automatically.

6.2.3 Trace

Measurement steps:

- 1.Press the [CALC] key to enter into measurement. Update the [Trace] item in the menu or press the quick measure key [TRACE], it will display a segment "+"icon.
- 2. Move the "+"icon by cursor, Press [ENTER] key to fix the point and the cursor can be moved to the next position.
- 3.Make the cursor tracing along the edge of required area, the traced line can be not closed.
- 4. Now press [UPDATE] key to cancel the tracing.
- 5.Press [ENTER] key again in the endpoint, the start point and end point of trace line will be closed by a straight line.
- 6. After the measurement, the result will display in the measurement results area.
- 7. Repeat the steps from 1 to 5 to start next "trace" measurement.

⚠Note:

Each group of measurement is limited, if the measurement results beyond, it will begin a new group of measurement automatically.

6.2.4 Histogram

Histogram is used to calculate the gray distribution of the ultrasound echo signals within a specified area. Use the rectangle, ellipse or trace method to draw along the desired measurement area. The result is shown in the form of histogram.

Histogram can be measured only on the frozen image.

◆ Measurement steps by rectangular method:



to freeze the image.

- 2.Press [ENTER] key in [Histogram] menu to enter into measurement status.
- 3.Press [ENTER] key to fix one apex of the rectangle.
- 4. Move the trackball to change the cursor position and fix the diagonal point of the rectangle
- 5. Move the trace ball to change the cursor position, fix the diagonal point of the rectangle, and press [ENTER] key again to confirm the measurement area. The result will display on the measurement result area.
- ◆ Measure the histogram by ellipse or trace method: The method is the same as that to measure ellipse or trace method, press [UPDATE] key to change the measurement between ellipse and trace.

The horizontal axis represents the gray scale of the image ranging from 0 to 255.

The vertical axis represents the distribution ratio of each gray scale. The value shown on the top of vertical axis represents the percentage of the maximally distributed gray in the whole gray distribution.

6.2.5 Cross-section Diagram

Cross-section Diagram is used to measure the gray distribution of the ultrasound signals in the vertical or horizontal direction on a certain profile (section).

This measurement is only available in the frozen mode.

Measurement steps:



to freeze the image.

- 2.Press [CALC] key, and choose [B General Meas.].
- 3.Draw a straight line at the measuring position. The method is the same as that to measure distance.
- 4. The calculated result of the profile will be displayed at the center of the screen.
- 1-The horizontal (or vertical) axis represents the projection of the profile line on the horizontal direction.
- 2-The vertical (or horizontal) axis represents the gray distribution of the corresponding points on the profile line. The range is 0 to 255.

6.3 B Fast Measurement

Press [DIST] key to enter B Fast measurement in B mode. Press the corresponding parameter control key to switch the fast measurement item.

Meas. Menu	Submenu	Unit	Meas. Method/ Meas. Formula	Comment
	Distance	cm	Refer to distance Meas.	
Distance	Ratio(Distance)		Refer to distance Meas.	D1: First Distance D2: Second Distance

Meas. Menu	Submenu	Unit	Meas. Method/	Comment
			Meas. Formula Formula: R=D1/D2	
	Angle	deg	Refer to distance Meas.	Angle Range: 0 °~ 180 °
Area	area/circle	Area cm ² Circle cm	Refer to Ellipse and trace meas.	Ellipse and trace.
	Volume (1straight line)	ml	Refer to distance Meas. Formula: $V = (\pi/6) \times D3$	D means: Depth
	Volume (1ellipse)	ml	Refer to ellipse meas. Formula: $V = (\pi/6) \times A \times B2$	A: Long Axis B: Short Axis
Volume	Volume (2 straight line)	ml	Refer to distance Meas. Formula: $V = (\pi/6) \times D1 \times D22$	D1: the longer distance D2: the shorter distance
	Volume (3 straight line)	ml	Refer to distance Meas. Formula: $V = (\pi/6) \times D1 \times D2 \times D3$	D1, D2, D3: Distance
	Volume(1 straight line 1 ellipse)	ml	Refer to distance and ellipse Meas. Formula: $V = (\pi/6) \times A \times B \times M$	A: Long Axis B: Short Axis M: Distance

6.4 B General Measurement

Click display [B], [B/B] or [4B] to enter into B, B/B or 4B mode, then click [CALC] key to enter into measurement status. Or press [CHANGE] to choose the General measurement.

Meas. Menu	Submenu	Unit	Meas. Method/ Meas. Formula	Comment
	Distance	cm	Refer to distance Meas.	
	area/circle	Area cm ² Circle cm	Refer to Ellipse and trace meas.	Ellipse and trace. Press [UPDATE] key to change.
	Volume (1straight line)	ml	Refer to distance Meas. Formula: $V = (\pi/6) \times D3$	D means: Depth
	Volume	ml	Refer to ellipse	A: Long Axis

Meas. Menu	Submenu	Unit	Meas. Method/	Comment
			Meas. Formula	
	(1ellipse)		meas.	B: Short Axis
			Formula: V =	
			$(\pi/6)\times A\times B2$	
			Refer to distance	D1: the longer distance
	Volume	ml	Meas.	D2: the shorter
	(2 straight line)	1111	Formula: V =	distance
			$(\pi/6) \times D1 \times D22$	distance
			Refer to distance	
	Volume	ml	Meas.	D1 D2 D2 Distance
	(3 straight line)	IIII	Formula: V =	D1, D2, D3: Distance
			$(\pi/6) \times D1 \times D2 \times D3$	
			Refer to distance	A. Long Avis
	Volume(1 straight	ml	and ellipse Meas.	A: Long Axis B: Short Axis
	line 1 ellipse)	mı	Formula: V =	M: Distance
			$(\pi/6) \times A \times B \times M$	M: Distance
			Refer to distance	
	Ratio(distance)		Meas.	D1: First Distance
	Ratio(distance)		Formula:	D2: Second Distance
Ratio			R=D1/D2	
Ratio			Refer to ellipse	
	Datic (area)		Meas.	A1: First Area
	Ratio(area)		Formula:	A2: Second Area
			R=A1/A2	
Anglo		dog	Refer to distance	Angle Range:
Angle		deg	Meas.	0 ° 180 °
History			Refer to	
Histogram			histogram	
Cross-section			Refer to	
diagram			Cross-section	

6.5 ABD Measurement

Choose ABD exam mode. Freeze the required image, then Press [CALC] key to enter into ABD measurement status. Or press [CHANGE] to choose the ABD measurement.

Meas. Menu	Submenu	Unit	Meas. Method/ Meas. Formula	Comment
D'		am.	Refer to distance	
Distance		cm	Meas.	
CBD		cm	Refer to distance	
СВД			Meas.	
CD well		-	Refer to distance	
GB wall		cm	Meas.	
Liver Length		cm	Refer to distance	

Meas. Menu	Submenu	Unit	Meas. Method/ Meas. Formula	Comment
			Meas.	
IMT		cm	Refer to distance Meas.	
	Height	cm	Refer to distance Meas.	
	Width	cm	Refer to distance Meas.	
	StD%	%	Refer to distance Meas. Formula: ((D1-D2)÷D1)×1 00%	D1: Length of Normal D2: Length of Stenosis
Pro Aorta	StA%	%	Refer to ellipse Meas. Formula: ((A1-A2)÷A1)×1 00%	A1: Area of Normal A2: Area of Stenosis
	Vessel Area	cm ²	Refer to ellipse and trace Meas.	Ellipse and trace. Press [UPDATE] key to change.
	Vessel Dis	cm	Refer to distance Meas.	
Mid Aorta	The same as above	The same as above	The same as above	The same as above
Distal Aorta	The same as above	The same as above	The same as above	The same as above
Spleen	Length Height Width Volume	cm cm cm ml	Refer to distance Meas. Formula: V = (\pi/6) \times L \times H \times W	L: Length H: Height W: Width
Renal Vol. (Rt/Lt)	Length Height Width	cm	Refer to distance Meas.	
	Height	cm	Refer to distance Meas.	
	Width	cm	Refer to distance Meas.	
Lliac(Rt/Lt)	StD%	%	Refer to distance Meas. Formula: ((D1-D2)÷D1)×1 00%	D1: Length of Normal D2: Length of Stenosis

Meas. Menu	Submenu	Unit	Meas. Method/ Meas. Formula	Comment
	StA%	%	Refer to ellipse Meas. Formula: ((A1-A2)÷A1)×1 00%	A1: Area of Normal A2: Area of Stenosis
	Vessel Area	cm ²	Refer to ellipse and trace Meas.	Ellipse and trace. Press [UPDATE] key to change.
	Vessel Dis	cm	Refer to distance Meas.	

6.6 OB Measurement

Choose OB exam mode. Freeze the required image, then Press [CALC] key to enter into OB measurement status. Or press [CHANGE] to choose the OB measurement.

Meas. Menu	Submenu	Unit	Meas. Method	Comment
Distance		cm	Refer to distance	
Distance			Meas.	
				Formula to choose:
			Refer to distance	CFEF, Campbell,
GS		cm	Meas.	Hadlock, Hansmann,
			1110451	Korean, Merz,
				Shinozuka
				Formula to choose:
			Refer to distance	Hadlock, Hansmann,
CRL		cm	Meas.	Korean, Nelson, Osaka,
			Titous.	Rempen, Robinson,
				Shinozuka
				Formula to choose:
			Bessis, CFEF, Campbell,	
		cm	Refer to distance Meas.	Chitty, Hadlock,
BPD				Hansmann, Jeanty,
		1110451	Johnsen, Korean, Kurtz,	
				Merz, Osaka, Rempen,
				Sabbagha, Shinozuka
				Formula to choose:
НС		cm	Refer to ellipse and	CFEF, Campbell, Chitty,
			trace Meas.	Hadlock, Hansmann,
				Johnsen, Korean, Merz
				Formula to choose:
AC		cm	Refer to ellipse and	CFEF, Campbell,
			trace Meas.	Hadlock, Hansmann,
				Korean, Merz,

Meas. Menu	Submenu	Unit	Meas. Method	Comment
				Shinozuka
	YS	cm	Refer to distance Meas.	
	OFD	cm	Refer to distance Meas.	Formula to choose: Hansmann, Korean
	APPD	cm	Refer to distance Meas.	Formula: Bessis
	TAD	cm	Refer to distance Meas.	Formula: CFEF
	TCA	cm	Refer to distance Meas.	Formula: Osaka
Fetal Biological	FL	cm	Refer to distance Meas.	Formula to choose: Bessis, CFEF, Campbell, Chitty, Doubilet, Hadlock, Hansmann, Hohler, Jeanty, Johnsen, Korean, Merz, Osaka, Shinozuka
	Spine Long	cm	Refer to distance Meas.	
	APD	cm	Refer to distance Meas.	Formula: Hansmann
	TTD	cm	Refer to distance Meas.	Formula: Hansmann
	TC	cm	Refer to distance Meas.	
	HL	cm	Refer to distance Meas.	Formula to choose: Jeanty, Korean, Merz, Osaka
	Ulna Long	cm	Refer to distance Meas.	Formula: Jeanty
Fetal Long Bones	Tibia Long	cm	Refer to distance Meas.	Formula to choose: Jeanty, Merz
Bolles	Radius Long	cm	Refer to distance Meas.	
	Fibula Long	cm	Refer to distance Meas.	
	Clavicle Long	cm	Refer to distance Meas.	Formula: Yarkoni
Fetal	Cerebellum	cm	Refer to distance Meas.	Formula to choose: Chitty, Hill
Cranium	Posterior Cistern	cm	Refer to distance Meas.	
	NF	cm	Refer to distance	

Meas. Menu	Submenu	Unit	Meas. Method	Comment
			Meas.	
	ND	am	Refer to distance	
	NB	cm	Meas.	
	OOD		Refer to distance	E1 OOD
	OOD	cm	Meas.	Formula: OOD
	IOD		Refer to distance	
	IOD	cm	Meas.	
	NB	am	Refer to distance	
	ND	cm	Meas.	
	Paracele	am	Refer to distance	Formulas Tolzvo
	Paracele	cm	Meas.	Formula: Tokyo
	HC Width	am	Refer to distance	
	ne widii	cm	Meas.	
	LtRenal	am	Refer to distance	
	Likeliai	cm	Meas.	
	RtRenal	cm	Refer to distance	
			Meas.	
	LtRenalAP		Refer to distance	
OB Others	LixellalAl	cm	Meas.	
OB Others	RtRenalAP	cm	Refer to distance	
	KukulaiAi	CIII	Meas.	
	LVWrHEM	cm	Refer to distance	
	LVWIIILWI	CIII	Meas.	
	TAD	cm	Refer to distance	
	TAD	CIII	Meas.	
				Modify the formula
EFBW		σ	Refer to distance	automatically according
LIBW		g	and ellipse Meas.	to EFBW formula in
				setting
AFI		cm	Refer to distance	AFI=AFI1+AFI2+AFI3
		CIII	Meas.	+AFI4
FBP		cm	Refer to distance	
		****	Meas.	
Cervical		cm	Refer to distance	
Length			Meas.	

6.6.1 Twins Measurement

- 1.In the new patient OB page, choose the number of gestations from one to four.
- 2.In the measurement menu, press baby A, and then press **[ENTER]** key to switch babies, which could measure the babies separately.

6.6.2 EDD (estimated date of delivery) Estimation

6.6.2.1 Calculating EDD by LMP (Last menstrual period)

- 1.In the new patient OB page, update the LMP input box.
- 2. Choose the LMP from the date dialog box or input the LMP date directly.
- 3. The calculated EDD value will appear in the result measurement area of OB page.

6.6.2.2 Calculating EDD by BBT (Basal body temperature)

- 1.In the new patient OB page, update the Ovul.Date input box and input the bbt date.
- 2. The method is the same with the LMP method.

6.6.3 Growth curves

Function: Growth curves comparison is used to compare the measured data of the fetus with the normal growth curve in order to judge whether the fetus grows normally.

Measurement steps:

- 1. Finish the measurement of the OB item and get into the report page.
- 2. Choose the growth curve at the right list and press [ENTER] key to display the growth curve.
- 3. Choose the growth curve need to display, and check it to show the growth curve on report.
- 4.Click [x] icon on the dialog box to exit.

Tips: The abscissa of Growth curves is the gestational weeks calculated according to the LMP in patient information.

6.7 Pediatric Measurement

Select OB mode, press [CALC] to enter OB mode, then enter into pediatrics mode. Or press [CHANGE] to switch to pediatrics measurement menu.

6.7.1 HIP Angle

HIP function is used for evaluating the fetal hip growth. In order to make calculation, three lines need to be added on the image, which is to conform to the fetal anatomic structure. The system will calculate and display two angles for doctor's reference.

Measurement steps:

- 1. Choose [HIP Angle] menu item, and click it to enter into measurement.
- 2. Click on the line image region, and appear one line with"+" . Move the line to the target measurement region.
- 3.Rotate [MENU] knob to adjust the line angle, press [ENTER] key to fix the line.
- 4. Then appear the second line, adjust the line according to the step 3, and fix the line.
- 5. Fix the 3 lines; the measurement result of the angle appears in the district.

△Caution:

- D 3 shows bias line between protruding of conjunction and acetabular bone
- D 2 shows direct line between osileum and acetabular bone
- D 1 shows base line between cotyle, joint purse, gristle periosteum and ilium.

 β is the angle between D1 and D2 (acute angle); α is the angle between D1 and D3 (acute angle).

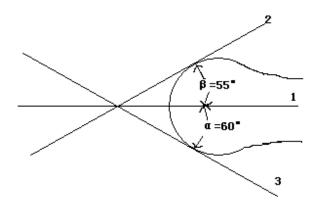


Fig. 25 HIP angel

6.8 GYN Measurement

GYN measurement includes measurement of UT-D (uterus diameter), ENDO (endometrium), CX-L (Uterine cervix length), LEFT OV and RIGHT OV (volume of left and right ovary) and LEFT FO and RIGHT FO (left and right follicle). The result will be calculated and displayed automatically on the screen by measuring relevant parameters.

Freeze the required image under GYN examination, then press [CALC] key to enter into GYN measurement status.

Meas. Menu	Submenu	Unit	Meas. Method	Comment
Distance		cm	Refer to distance	
			Meas.	
	UT_L	cm	Refer to distance	
		CIII	Meas.	
	CUT_L	cm	Refer to distance	
	COT_L	CIII	Meas.	
	UT_W	cm	Refer to distance	
	U1_W	cm	Meas.	
	UT_H	cm	Refer to distance	
UT			Meas.	
01	UT_V	1	Refer to distance	L: UT_L
			Meas.	H: UT_H
		ml	Formula: $V =$	W: UT_W
			$(\pi/6)\times L\times H\times W$	W: U1_W
			Refer to distance	I.IT I
	LIT D		Meas.	L: UT_L
	UT_D	cm	Formula:	H: UT_H
			$UT_D = L + W + H$	W: UT_W
			Refer to distance	L: Cervix _L
Cervix Vol.		ml	Meas.	H: Cervix _H
			Formula: V =	W: Cervix _W

Meas. Menu	Submenu	Unit	Meas. Method	Comment
			$(\pi/6)\times L\times H\times W$	
ENDO		cm	Refer to distance Meas.	
OV Vol.(L/R)		ml	Refer to distance Meas. Formula: $V = (\pi/6) \times L \times H \times W$	L: OV _L H: OV _H W: OV _W
	Follicle width	cm	Refer to distance Meas.	
	Follicle height	cm	Refer to distance Meas.	
FO(L/R)	Follicle Volume	ml	Formula of 2distance $V = (\pi/6) \times A \times B^2$ Formula of 3distance $V = (\pi/6) \times L \times H \times W$	2distance A: the longer distance B: the shorter distance 3distance L: follicle length H: follicle height W: follicle width

6.9 Small Parts Measurement

Freeze the required image under Small parts examination, then press [CALC] key to enter into small parts measurement status.

Meas. Menu	Submenu	Unit	Meas. Method/ Meas. Formula	Comment
Distance		cm	Refer to distance Meas.	
Thyroid(L/R)	Volume	ml	Refer to distance Meas. Formula: $V = (\pi/6) \times L \times H \times W$	L: Thyroid_L H: Thyroid_H W: Thyroid_W
Angle		deg	Refer to distance Meas.	Angle Range: 0 °∼180 °
Ratio			Refer to distance Meas. Formula: R=D1/D2	D1: First Distance D2: Second Distance

6.10 B Mode Vessel Measurement

The same as normal measurement in B mode.

6.11 Urology Measurement

Normally urology measurements are performed in B and B/B mode.

Freeze the required image under Urology examination, then press [CALC] key to enter into Urology measurement status.

Meas. Menu	Submenu	Unit	Meas. Method/ Meas. Formula	Comment
Kidney Vol.(L/R)		ml	Refer to distance Meas. Formula: $V = (\pi/6) \times L \times H \times W$	L: Kidney_L H: Kidney_H W: Kidney_w
Bladder Vil.	V(L*W*H)	ml	Refer to distance Meas. Formula: $V = (\pi/6) \times L \times H \times W$	L: Bladder _L H: Bladder _H W: Bladder _w
	Volume	ml	Refer to distance Meas. Formula: $V = (\pi/6) \times L \times H \times W$	L: Prostate _L H: Prostate _H W: Prostate _w
Prostate	PPSA	ng/ml	Formula: PPSA = $0.12 \times V$	
	PSAD	ng/ml	Formula: PSAD=SPSA/V	SPSA: input the SPSA When create a new Patient
RVU	Volume	ml	Refer to distance Meas. Formula: $V = (\pi/6) \times L \times H \times W$	L: RVU _L H: RVU _H W: RVU _w

6.12 Cardiac Measurement

Normally urology measurements are performed in B and B/B mode.

Freeze the required image under Cardiac examination, then press [CALC] key to enter into Cardiac status.

Meas. Menu	Submenu	Unit	Meas. Method/ Meas. Formula	Comment
Distance		cm	Refer to distance Meas.	
Single Plane		ml	Refer to distance Meas. Formula: $V = (\pi/6) \times L \times D2$	Left ventricular parameter at end diastole: LV long-axis SL; LV short-axis SD; Left ventricular parameter at end systole: LV long-axis DL;

Meas. Menu	Submenu	Unit	Meas. Method/ Meas. Formula	Comment
				LV short-axis DD
Bi-Plane		ml	Refer to distance Meas., ellipse Meas. Formula: $V = (8/3) \times Am \times Ai \div (\pi \times D)$	D: LV short-axis Am: LV area on mitral valve level figure Ai: LV area on apex level figure
Bullet Volume		ml	Refer to distance Meas., ellipse Meas. Formula: V = (5/6)×Am×L	valve short-axis figure
Modi_Simps on		ml	Refer to distance Meas., ellipse Meas. Formula: V=(Am +5×Ap/18)×L	Am: LV area on mitral valve short-axis figure Ap: LV cross sectional on papillary muscle level figure. L: LV long-axis

6.13 Normal Measurement in M, B/M mode

At real-time status, press [M] key twice to enter M mode, press [CALC] key to enter into M mode measurement status.

OR

At real-time status, click [M] key to enter B/M mode, press [CALC] key to enter into M mode measurement status.

6.13.1 Distance

Measurement steps:

- 1.Select menu item-"Distance" to enter into measurement.
- 2.Click on the M image area, it will display a blue dotted line with two horizontal short line. The blue dotted line represents the position need to be measured. The distance between the two short lines is the distance you want to measure. The yellow short line represents it's in active status. Click it and drag the short line to anywhere you want to put.
- 3.Press [UPDATE] key to activate the two short lines in turns and dragon them to change the distance between them. The measurement result will be displayed on the result area.

6.13.2 Time

Measurement steps:

1.Select menu item [Time] to enter into measurement.

- 2.Click on the M image area, it will display two blue straight dotted line. The blue dotted line with one yellow short line on it represents it is in active status. The distance between the two straight lines stands for time you want to measure. You can drag the active straight line to anywhere you want to change the measured time.
- 3.Press [UPDATE] key to activate the two straight lines in turns and dragon them to change the distance between them. The measurement result will be displayed on the result area.

6.13.3 Heart rate

Heart rate is used to calculate the number of heart beats per minute from cardiac image.

Measurement steps:

- 1. Choose [Heart Rate] menu item to enter into measurement.
- 2. The method is the same as Time.
- 3. After the above measurement, the calculated heart rate result is displayed in the measurement result area.
- 4. Repeat the steps form 1 to 3 to start next measurement.

6.13.4 Velocity

Measurement steps:

- 1.Click [Velocity] menu item to enter measurement condition.
- 2.Select the starting point and press **[ENTER]** key, the starting point and the removable cursor display, drag cursor to the end point.
- 3. Press [ENTER] key again, measurement completes, the result displays in the region of measurement
- 4.Repeat 1~3, and enter the next measurement of velocity.

Note: The maximum number of the measurement result on the image area is one. The second measurement result will cover the first one. The measurement result area will list all the measurement values.

6.14 General Measurement in M mode

At real time status, press [M] key twice to enter M mode, click [CALC] key to enter into M mode cardiology measurement status.

Meas. Menu	Submenu	Unit	Meas. Method/ Meas. Formula	Comment
Distance		am	Refer to M distance	
Distance		cm	Meas.	
Time		S	Refer to M time	
Time	Time		Meas.	
Velocity		cm/s	Refer to M velocity	
velocity		CIII/S	Meas.	
	One Cycle	hnm	Refer to M HR	
HR	Olle Cycle	bpm	Meas.	
IIK	Double	bpm	Refer to M HR	
	Cycles	орш	Meas.	

6.15 M Abdomen Measurement

The same as M mode general measurement.

6.16 M OB Measurement

The same as M mode general measurement.

6.17 M GYN Measurement

The same as M mode general measurement.

6.18 M Mode Cardiac Measurement

Normally urology measurements are performed in M and B/M mode.

Freeze the required image under Urology examination, then press [CALC] key to enter into Urology measurement status. Or press [CHANGE] key to choose the cardiac measurement.

Meas. Menu	Submenu	Unit	Meas. Method/ Meas. Formula	Comment
Distance		cm	Refer to M distance Meas.	
ET		S	Refer to M time Meas.	
HR	One Cycle	bpm	Refer to M velocity Meas.	
пк	Double Cycles	bpm	Refer to M velocity Meas.	
	IVSd	cm	Refer to M distance Meas.	Interventricular Septum
	LVIDd	cm	Refer to M distance Meas.	Left Ventricular Diameter at diastole
	LVIDs	cm	Refer to M distance Meas.	Left Ventricular Diameter at systole
LVMM	LVPWd ci	cm	Refer to M distance Meas.	Left Ventricular Posterior Wall at diastole
	IVSs	cm	Refer to M distance Meas.	Interventricular Septal Thickness at Systole
	LVPWs	cm	Refer to M distance Meas.	Left Ventricular Posterior Wall at Systole

		Meas. Method/		
Meas. Menu	Submenu	Unit	Meas. Formula	Comment
	EDV	ml	EDV = 7.0/(2.4+LVIDd)×LVI Dd3	Left Ventricular Volume at end diastole
	ESV	ml	$ESV = 7.0/(2.4+LVIDs) \times LVI$ $Ds3$	Left Ventricular Volume at end Systole
	SV	ml	SV= EDV-ESV	Stroke Volume
	SI		SI=SV/BSA	Stroke Volume, BSA: Body Surface Area, it calculated by input the height and weight.
	EF	%	EF=SV/EDV×100	Ejection Fraction
	SF	%	SF = (LVIDd-LVIDs)/LVI Dd×100	Contraction Fraction
	СО	L/min	CO=SV×HR/1000	Cardiac Output
	CI		CI=CO/BSA	ECG Index, BSA: Body Surface Area, it calculated by input the height and weight.
	LVMW		LVMW = 1.04×[(IVSd+LVIDd +LVPWd)3-LVIDd3]- 13.6	
	LVMWI		LVMWI = LVMW/BSA	BSA: Body Surface Area, it calculated by input the height and weight.
	MVCF		MVCF = (LVIDd-LVIDs)/(LVI Dd×LVET)	Average Reduction of Length
	EF Velocity	cm/s	Refer to M HR Meas.	
	AC Velocity	cm/s	Refer to M HR Meas.	
Mitral Valve	A peak/E peak		Refer to M distance Meas.	
	Mitral Orifice Flow		Refer to M HR and time Meas. QMV = 4 × DEV × DCT	Opening Time
Arota	LAD/AOD		Refer to M distance Meas.	LV and aorta diametrical ratio

Meas. Menu	Submenu	Unit	Meas. Method/ Meas. Formula	Comment
				MAVO1: Aorta
				opening distance at the
	Acutic		ANICNI	beginning.
	Aortic	AVSV = (MAVO1+MAVO2)× LVET×50+AA		MAVO2: Aorta
	Valvular		opening distance at the	
	Orifice Flow		LVEI XXV+AA	end.
				AA: Range of Aorta
				Wall Motion

6.19 M Urology Measurement

Refer to general measurement in M mode.

6.20 M Small Parts Measurement

Refer to general measurement in M mode.

6.21 M Pediatric Measurement

Refer to general measurement in M mode.

6.22 PW mode measurement methods

Press [D] key to enter PW mode, and then press [CALC] key to enter PW mode measurement.



- •In order to get accurate result, the PW image must be clear and high quality.
- •Insure you fix the cursor at the exact place of cardiac systole and diastole.

6.22.1 Velocity

Refer to velocity of M mode general measurement.

6.22.2 Time

Refer to time of M mode general measurement.

6.22.3 HR

Refer to HR of M mode general measurement.

6.22.4 Auto Trace

Measurement steps:

- 1. Move the trackball to select the start point of the one cycle and press [ENTER] key to fix it.
- 2.A second cursor "^" will appear, and move the trackball to the end point of the cycle, press [ENTER] key to fix it.
- 3. The measurement results will be displayed on the monitor and calculate other values of parameters

6.22.5 Manual Trace

Measurement steps:

- 1. Move the trackball to select the start point of the one cycle and press [ENTER] key to fix it.
- 2. Move the trackball along the spectrum and press [ENTER] key to complete.
- 3. The measurement results will be displayed on the monitor and calculate other values of parameters

6.23 PW Fast Measurement

Press [DIST] key to enter PW Fast measurement in PW mode. Press the corresponding parameter control key to switch the fast measurement item.

_			Meas. Method/	
Meas. Menu	Submenu	Unit	Meas.	Comment
			Formula	
	Vs	cm/s	Refer to M	
	VS	CIII/S	speed meas.	
			Formula:	
	Pressure(s)	mmHg	Pressure =	
	Flessule(s)	liming	4×Vs×Vs/1000	
			0	
	Vd	cm/s	Refer to M	
			speed meas.	
Peak	Pressure(d)	mmHg	Formula:	
reak			Pressure =	
			4×Vd×Vd/1000	
			0	
	SD		Formula: SD=	
	3D		Vs/Vd	
	RI		Formula: SD=	
	KI		(Vs-Vd)/Vs	
	Tr'		Refer to M	
	Time	S	time meas.	
HR	Single wave	bpm	Refer to M HR	

			Meas. Method/	
Meas. Menu	Submenu	Unit		Comment
			Formula	
			meas.	
	***	,	Refer to M	
	Vs	cm/s	speed meas.	
			Formula:	
	D (-)		Pressure =	
	Pressure(s)	Unit Meas. Formula meas. Refer t speed me Formula: Pressure 4×Vs×Vs 0 cm/s Formula: Pressure 4×Vd×Vd 0 cm/s Refer t speed me Formula: Pressure 4×Vd×Vd 0 Cm/s Formula: Pressure 4×VMean ean/1000c cm Formula: Vs/Vd Formula: (Vs-Vd)// Formula:	4×Vs×Vs/1000	
			0	
	Vd		Refer to M	
	Va	cm/s	speed meas.	
	Pressure(d)		Formula:	
		mmHg	Pressure =	
			4×Vd×Vd/1000	
			0	
Auto	VMean	cm/s	Refer to M	
Trace/Manua			speed meas.	
1 Trace			Formula:	
	Pressure(VMean)	mmHg	Pressure =	
	Tressure(vivicali)		4×VMean×VM	
			ean/10000	
	TVI	cm		
	SD		Formula: SD=	
	30		Vs/Vd	
	RI		Formula: SD=	
	KI		(Vs-Vd)/Vs	
			Formula: SD=	
	PI		(Vs-Vd)/VMea	
			n	
	HR(Single wave)	bpm		

6.24 PW Genearl Measurement

Press [CALC] to enter PW measurement in PW mode. Press the corresponding parameter control key to switch the general measurement item.

Meas. Menu	Submenu	Unit	Meas. Method/ Meas. Formula	Comment
Velocity		cm/s	Refer to M speed meas.	
Distance		cm	Refer to B distance meas.	
Peak	Vs	cm/s	Refer to M speed meas.	

			Meas. Method/	ar Cotor Doppier Curusount
Meas. Menu	Submenu	Unit	Meas.	Comment
Wieus. Wienu	Businena	Cint	Formula	Comment
			Formula:	
	Pressure(s)	mmHg	Pressure =	
		-	4×Vs×Vs/1000	
			0	
	Vd	cm/s	Refer to M	
			speed meas.	
			Formula:	
	Pressure(d)	mmHg	Pressure =	
	Tressure(u)	Innining	4×Vd×Vd/1000	
			0	
			Formula: SD=	
	SD		Vs/Vd	
			Formula: SD=	
	RI		(Vs-Vd)/Vs	
			Refer to M	
	Time	S	time meas.	
			Refer to M	
	Vs	cm/s	speed meas.	
			Formula:	
	Pressure(s)	mmHg		
			Pressure =	
			$4 \times Vs \times Vs/1000$	
			0	
	Vd	cm/s	Refer to M	
			speed meas.	
			Formula:	
	Pressure(d)	mmHg	Pressure =	
		8	$4\times Vd\times Vd/1000$	
Auto			0	
Trace/Manua	VMean	cm/s	Refer to M	
1 Trace	Vivican	CHI/3	speed meas.	
Titace			Formula:	
	Pressure(VMean)	mama I I c	Pressure =	
	Pressure(viviean)	mmHg	4×VMean×VM	
			ean/10000	
	TVI	cm		
			Formula: SD=	
	SD		Vs/Vd	
			Formula: SD=	
	RI		(Vs-Vd)/Vs	
			Formula: SD=	
	PI		(Vs-Vd)/VMea	
	1 1			
			n	

			Meas. Method/	Doppier Circusount
Meas. Menu	Submenu	Unit	Meas.	Comment
Wicas. Wichu	Submenu	Cint	Formula	Comment
	IID (G: 1	,	rormula	
	HR(Single wave)	bpm	_	
	Distance1	cm	Refer to B	
			distance meas.	
	Distance2	cm	Refer to B	
StD%	Distance2	CIII	distance meas.	
StD 70			Formula: StD%	
	G.Dov	0/	=	D1:Distance1,
	StD%	%	((D1-D2)÷D1)	D2:Distance2
			×100%	
		2	Refer to B	
	Area1	cm ²	ellipse meas.	
			Refer to B	
	Area2	cm ²	ellipse meas.	
StA%			1	
			Formula: StA%	
	StA%	%		A1:Area1,A2:Area2
			((A1-A2)÷A1)	
			×100%	
ICA/CCA	ICA	cm/s	Refer to M	
			speed meas.	
			Formula:	
	Praccura(ICA)	mmHg	Pressure =	
	Pressure(ICA)	Innining	4×ICA×ICA/10	
			000	
	CCA	,	Refer to M	
	CCA	cm/s	speed meas.	
			Formula:	
			Pressure =	
	Pressure(CCA)	mmHg	4×CCA×CCA/	
			10000	
			Formula:	
	ICA/CCA		ICA/CCA	
			Refer to B	
Flow Volume	Diam	cm	distance meas.	
	TVI	cm	distance meas.	
	1 1 1	cm	Defer to M	
	Time	S	Refer to M	
	IID (C)	1	time meas.	
	HR(Single wave)	bpm		
			Formula:	
	SV	ml	0.785* Diam*	
			Diam* TVI	
	CO	l/min	Formula:	
		1/ 111111	SV*HR(Single	

			Meas. Method/	
Meas. Menu	Submenu	Unit	Meas.	Comment
			Formula	
			wave)/1000	

6.25 PW Abdomen Measurement

Refer to PW general measurement.

6.26 PW OB Measurement

Press [CALC] key to enter PW measurement in PW OB mode. Or press the corresponding parameter control key to switch the OB measurement item.

			Meas. Method/	
Meas. Menu	Submenu	Unit	Meas.	Comment
			Formula	
	Vs	cm/s	Refer to M	
	VS	CIII/S	speed meas.	
			Formula:	
	Pressure(s)	mmHg	Pressure =	
	Tressure(s)	mmig	$4\times Vs\times Vs/1000$	
Umb A			0	
	Vd	cm/s	Refer to M	
Aorta	V G	CHVS	speed meas.	
			Formula:	
Descending	Pressure(d)	mmHg	Pressure =	
Aorta	Tressure(a)	IIIIIII	4×Vd×Vd/1000	
			0	
Uterine	VMean	cm/s	Refer to M	
Artery(Lt)	VIVICUII		speed meas.	
			Formula:	
Uterine	Pressure(VMean)	mmHg	Pressure =	
Artery(Rt)	Tressure(vivicum)	11111115	4×VMean×VM	
			ean/10000	
Pulmonary	TVI	cm		
Artery	SD		Formula: SD=	
			Vs/Vd	
MCA	RI		Formula: SD=	
			(Vs-Vd)/Vs	
			Formula: SD=	
	PI		(Vs-Vd)/VMea	
			n	
	HR(Single wave)	bpm		

6.27 PW GYN Measurement

Press [CALC] to enter PW measurement in PW GYN mode. Or press the corresponding parameter control key to switch the GYN measurement item.

			Meas. Method/	
Meas. Menu	Submenu	Unit	Meas.	Comment
			Formula	
	17	,	Refer to M	
	Vs	cm/s	speed meas.	
			Formula:	
	Pressure(s)	mmHg	Pressure =	
	Plessule(s)		4×Vs×Vs/1000	
			0	
	Vd	cm/s	Refer to M	
	Vu	CIII/S	speed meas.	
			Formula:	
	Pressure(d)	mmHg	Pressure =	
Umb A	Tressure(u)		4×Vd×Vd/1000	
			0	
MCA	VMean	cm/s	Refer to M	
	Vivican		speed meas.	
Uterin A			Formula:	
	Pressure(VMean)	mmHg	Pressure =	
Fetal AO	Tressure(Vivieum)	mmig	4×VMean×VM	
			ean/10000	
	TVI	cm		
	SD		Formula: SD=	
	SD		Vs/Vd	
	RI		Formula: SD=	
	101		(Vs-Vd)/Vs	
			Formula: SD=	
	PI		(Vs-Vd)/VMea	
			n	
	HR(Single wave)	bpm		

6.28 PW Cardiology Measurement

Press [CALC] to enter PW measurement in PW cardiology mode. Or press the corresponding parameter control key to switch the cardiology measurement item.

Meas. Menu	Submenu	Unit	Meas. Method/ Meas. Formula	Comment
LVOT	Peak Velocity	cm/s	Refer to M	

Meas. Menu	Submenu	Unit	Meas. Method/ Meas. Formula	Comment
			speed meas.	
			Formula: Pressure =	
	Peak Pressure	mmHg	4×Peak Velocity×Peak Velocity	
			/10000	
	Diam	cm	Refer to B distance meas.	
	Diam Area	cm ²	Formula: π^* Diam* Diam/4	
	Vs	cm/s	Refer to M speed meas.	
	PPG	mmHg	Formula: PPG = 4×Vs×Vs/1000 0	
	VMean	cm/s	Refer to M speed meas.	
	MPG	mmHg	Formula: MPG = 4×VMean×VM ean/10000	
	TVI	cm		
	Time	s	Refer to M time meas.	
	HR(Single wave)	bpm		
	SV	ml	Formula: 0.785* Diam* Diam* TVI	
	СО	1/min	Formula: SV*HR(Single wave)/1000	
AV	Diam	cm	Refer to B distance meas.	
	Area	cm ²	同B轨迹测量	
	ACC	cm/s ²	Refer to M speed meas.	
	AV Trace Vs	cm/s	Refer to M speed meas.	
	AV Trace PPG	mmHg	Formula: PPG	

Meas. Menu	Submenu	Unit	Meas. Method/ Meas. Formula	Comment
			$\begin{vmatrix} = \\ 4 \times V_S \times V_S / 1000 \\ 0 \end{vmatrix}$	
	AV Trace VMean	cm/s	Refer to M speed meas.	
	AV Trace MPG	mmHg	Formula: MPG = 4×VMean×VM ean/10000	
	AV Vmax Velocity	cm/s	Refer to M speed meas.	
	AV Vmax Pressure	mmHg	Formula: Pressure = 4×Velocity×Vel ocity/10000	
	AV PHT VPeak	cm/s	Refer to M speed meas.	
	AV PHT Pressure	mmHg	Formula: Pressure = 4×VPeak×VPe ak/10000	
	AV PHT Slope	cm/s ²		
	AV PHT	s		
	AV PHT Area	cm ²	Formula:220/ AV PHT	
	R-R interval	bpm		
	AR Trace Vs	cm/s	Refer to M speed meas.	
	AR Trace PPG	mmHg	Formula: PPG = $4 \times Vs \times Vs/1000$ 0	
	AR Trace VMean	cm/s	Refer to M speed meas.	
	AR Trace MPG	mmHg	Formula: MPG = 4×VMean×VM ean/10000	
	AR Vmax Velocity	cm/s	Refer to M speed meas.	
	AR Vmax	mmHg	Formula:	

			Meas. Method/	
Meas. Menu	Submenu	Unit		Comment
			Meas. Formula	
	Pressure		Pressure =	
	Tiessaie		4×Velocity×Vel	
			ocity/10000	
			Refer to M	
	AR PHT VPeak	cm/s	speed meas.	
			Formula:	
	AR PHT		Pressure =	
	AR PHT Pressure	mmHg	4×VPeak×VPe	
			ak/10000	
	AR PHT Slope	cm/s ²		
	AR PHT	S		
	A D. DAVE. A	2	Formula:220/	
	AR PHT Area	cm ²	AV PHT	
	EPeak	ana /a	Refer to M	
	EPeak	cm/s	speed meas.	
	EPeak Pressure	mmHa	Formula:	
			Pressure =	
	LFEAK FIESSUIE	mmHg	4×EPeak×EPea	
			k/10000	
	APeak	cm/s	Refer to M	
	711 Cur	CIII/S	speed meas.	
			Formula:	
	APeak Pressure	mmHg	Pressure =	
		mmrig	4×APeak×APe	
			ak/10000	
			Formula:	
MV	E/A	%	EPeak/	
			APeak*100	
	MV VPeak	cm/s	Refer to M	
			speed meas. Formula:	
	MV PHT		Pressure =	
	Pressure	mmHg	4×VPeak×VPe	
	1 ICSSUIC		ak/10000	
	MV PHT Slope	cm/s ²	un/1000	
	MV PHT	S		
			Formula:220/	
	MV PHT Area	cm ²	MV PHT	
	ED		Refer to M	
	E Dur	S	time meas.	
	A Dur	S	Refer to M	

Meas. Menu	Submenu	Unit	Meas. Method/ Meas.	Comment
			Formula	
			time meas.	
	IRT		Refer to M	
	IKI	tunit s cm cm² cm/s mmHg cm/s bpm ml l/min bpm cm/s mmHg	time meas.	
	MV Diam	cm	Refer to B distance meas.	
	MV Area	cm ²	同B轨迹测量	
			Refer to M	
	MV Trace Vs	cm/s	speed meas.	
	MV Trace PPG	mmHg	Formula: PPG = 4×Vs×Vs/1000 0	
	MV Trace VMean	cm/s	Refer to M speed meas.	
	MV Trace MPG	mmHg	Formula: MPG = 4×VMean×VM ean/10000	
	MV Trace TVI	cm		
	Time	s	Refer to M time meas.	
	MV Trace HR	bpm	Formula:60/Ti	
	MV Trace SV	ml	Formula: 0.785* Diam* Diam* TVI	
	MV Trace CO	l/min	Formula: SV*HR(Single wave)/1000	
	R-R interval	bpm		
	MR Vmax	cm/s	Refer to M speed meas.	
	MR Vmax Pressure	mmHg	Formula: Pressure = 4×Vmax×Vma x/10000	
	MR TVI	cm		
TV	TV Manual Trace Vs	cm/s	Refer to M speed meas.	
TV	TV Manual Trace PPG	mmHg	Formula: PPG =	

Meas. Menu	Submenu	Unit	Meas. Method/ Meas. Formula	Comment
			4×Vs×Vs/1000 0	
	TV Manual Trace VMean	cm/s	Refer to M speed meas.	
	TV Manual Trace MPG	mmHg	Formula: MPG = 4×VMean×VM ean/10000	
	TV Manual Trace TVI	cm		
	TV PHT VPeak	cm/s	Refer to M speed meas.	
	TV PHT Pressure	mmHg	Formula: PPG = 4×VPeak×VPe ak/10000	
	TV PHT Slope	cm/s ²		
	TV PHT	S		
	TV PHT Area	cm ²	Formula:220/ TV PHT	
	R-R interval	bpm		
	TR Manual Trace Vs	cm/s	Refer to M speed meas.	
	TR Manual Trace PPG	mmHg	Formula: PPG = 4×Vs×Vs/1000 0	
	TR Manual Trace VMean	cm/s	Refer to M speed meas.	
	TR Manual Trace MPG	mmHg	Formula: MPG = 4×VMean×VM ean/10000	
	TR Manual Trace TVI	cm		
	TR Vmax	cm/s	Refer to M speed meas.	
	TR Vmax Pressure	mmHg	Formula: Pressure = $4 \times V \max \times V \max x/10000$	

Meas. Menu	Submenu	Unit	Meas. Method/ Meas. Formula	Comment
	TR TVI	cm		
	InFlow Velocity	cm/s	Refer to M speed meas.	
	InFlow Pressure	mmHg	Formula: Pressure = 4×Velocity×Vel ocity/10000	
	PV Diam	cm	Refer to B distance meas.	
	PV Trace Vs	cm/s	Refer to M speed meas.	
	PV Trace PPG	mmHg	Formula: PPG = 4×Vs×Vs/1000 0	
	PV Trace VMean	cm/s	Refer to M speed meas.	
	PV Trace MPG	mmHg	Formula: MPG = 4×VMean×VM ean/10000	
PV	PV Trace TVI	cm		
	Time	S		
	PV Trace HR	bpm	Formula:60/Ti me	
	PV Trace SV	ml	Formula: 0.785* Diam* Diam* TVI	
	PV Trace CO	l/min	Formula: SV*HR(Single wave)/1000	
	RV ET	s	Refer to M time meas.	
	RV AcT	s	Refer to M time meas.	
	RV AcT/ET		Formula: AcT/ET	
	RV REP	s	Refer to M time meas.	
	RV STI		Formula: REP/ET	

Meas. Menu	Submenu PV PHT VPeak	Unit cm/s	Meas. Method/ Meas. Formula Refer to M speed meas. Formula: PPG	Comment
	PV PHT Pressure	mmHg	= 4×VPeak×VPe ak/10000	
	PV PHT Slope	cm/s ²		
	PV PHT	s		
	PV PHT Area	cm ²	Formula:220/ TV PHT	
	R-R interval	bpm		
	PR Vmax	cm/s	Refer to M speed meas.	
	PR Vmax Pressure	mmHg	Formula: Pressure = $4 \times V \max \times V \max \times V \max \times V \min $ $x/10000$	
Pul. Vein	Pul. Vein Vs	cm/s	Refer to M speed meas.	
	Pul. Vein Vd	cm/s	Refer to M speed meas.	
	Pul. Vein SD		Formula:SD = Vs/Vd	
	ARV	cm/s	Refer to M speed meas.	
	ARD	s	Refer to M time meas.	

6.29 PW Vascular Measurement

Press [CALC] to enter PW measurement in PW vascular mode. Or press the corresponding parameter control key to switch the vascular measurement item.

Meas. Menu	Submenu	Unit	Meas. Method/ Meas. Formula	Comment
Subclavian A	Vs	cm/s	Refer to M speed meas.	
Prox CCA Mid CCA	Pressure(s)	mmHg	Formula: Pressure = $4 \times Vs \times Vs/1000$ 0	

			Meas. Method/	
Meas. Menu	Submenu	Unit	Meas.	Comment
			Formula	
Distal CCA	Vd	cm/s	Refer to M	
			speed meas.	
Bulb			Formula:	
	ICA Pressure(d)	mmHg	Pressure =	
Prox ICA			4×Vd×Vd/1000	
			0	
Mid ICA	VMean	cm/s	Refer to M	
			speed meas.	
Distal ICA	Pressure(VMean)	mmHg	Formula:	
			Pressure =	
ECA			4×VMean×VM	
			ean/10000	
Vertebral A	TVI	cm		
常规测量	SD		Formula: SD=	
			Vs/Vd	
	RI		Formula: SD=	
			(Vs-Vd)/Vs	
			Formula: SD=	
	PI		(Vs-Vd)/VMea	
			n	
	HR(Single wave)	bpm		

6.30 PW Urology Measurement

Refer to PW general measurement.

6.31 PW Small parts Measurement

Refer to PW general measurement.

6.32 PW Pediatric Measurement

Refer to PW general measurement.

Chapter 7 Preset

This chapter introduces the operation to make settings of the system through preset menu at preset mode.

Preset function is used to set up working environment and status, parameters of each examination mode. The setting will be stored in the memory of system and not be lost even after the system is switched off. When the system is switched on, it will work automatically with the status which is required by the operator.

In preset interface, all operation relies on moving trackball to required Function key position. Press **[ENTER]** key to start operation.

7.1 General setting

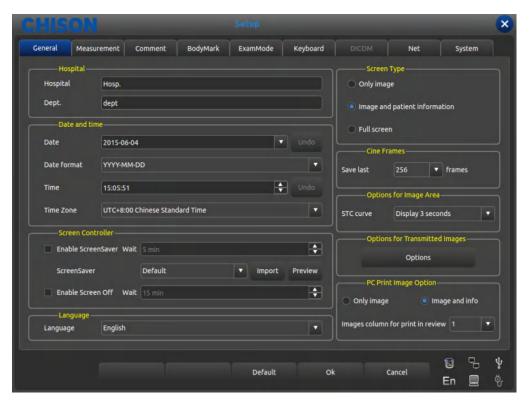


Fig. 26 General Setting Interface

Press to enter system setting interface. User can do user-defined setting.

Click [X] in the title bar or the exit key on the button can exit the system setting interface.

Form 1 General setting

Function name	Setting method	Function description		
Hospital Dept.	Input freely	Set up the hospital name which is shown at top left corner of "General Setting" dialog box, 20 characters Max. can be input		
Date and Time	Input freely	Set up the system date (calendar format), select current date directly. Date format can be changed by format setting.		
Date Format	Set up freely	Set up date format: Year/Month/Date,		

Function name	Setting method	Function description			
		Month/Date/Year, Date/Month/Year			
Time zone	Set up freely	Set up the working clock of the system.			
		Enable screen saver, user can custom screen saver			
Screen	Select the function				
Controller	and set its start time	PNG, BMP format, size does not exceed 512 * 384			
		pixels.			
Languaga	Calaat languaga	Select the language of operation interface(Simplified			
Language	Select language	Chinese, English and so on).			
Screen shot	C-1+ 41 1 +	Set the content which screen picture contain: only			
Type	Select the need type	picture, image area and patient information, full screen.			
Frame number	G 4 G 1	Set the default frame when save the film.			
choice	Set up freely				
Options for	Click the button to	Set the STC curve, including always shows, always			
image area	open the setting box	hide and hide for 1 to 8 seconds.			
Options for	Click the button to	Adjust the personators of transmitted images.			
Transmitted		Adjust the parameters of transmitted images: brightness, contrast, and gamma.			
Images	open the setting box				
	Click the mode you				
	need and open the				
Options for PC	setting box to choose	Including print area and arrangement condition in the image foresee interface.			
print image	the different				
	parameter				
default	Press button	Recover all preset to factory setting.			

7.2 Measurement

Measurement includes general measurement setting and measurement formula setting

7.2.1 General measurement setting

General settings can only change the display of measurement unit.

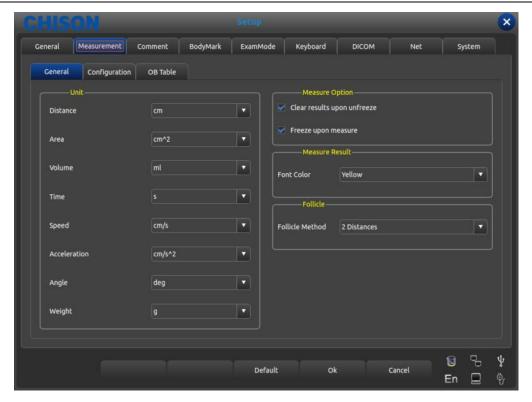


Fig. 27 General Measurement settings interface

Distance: cm, mm
Area: cm², mm²
Volume: ml, l

●Time: s, ms

● **Speed:** cm/s, mm/s

• Acceleration: cm/s², mm/s²

Angle: deg, radWeight: g, kg

•Measure Result Option: whether clear results upon unfreeze, and the automatic froze image

● Measure Result: the color of the result font is alternative, including yellow/white/orange/green

• Follicle Method: the ways to measure follicle, you can choose two distances and three distances.

7.2.2 Measurement formula setting

7.2.2.1 Interface Description-Measurement Menu

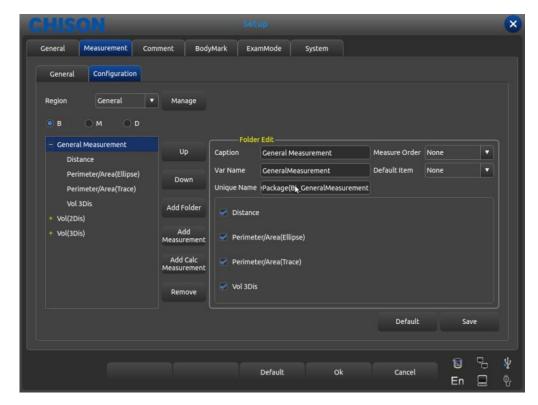


Fig. 28 Interface for Edition of measurement Formula

- Region: pull down and select needed measurement menu
- •Manage: pop up measurement software edition interface, add modify delete change marshalling sequence in measurement menu.
- •B, M: display measurement of each Exam mode
- •Up: press this button to move selected measurement term up
- Down: press this button to move selected measurement term down
- Add Folder: add a measurement item. In the left column when the term is fold there is "+" otherwise "-"
- •Add Measurement: add a measurement item for a term in the right column there is selected item and detailed parameter.
- •Add Calc Measurement: add a calc item for a measurement term
- Remove: remove selected measurement term or item.
- **Default:** restore all measurement term as factory setting.
- •Save: save measurement item modification users did
- Check: display needed items on measurement menu, otherwise not displayed

Sheet 2 Folder Edit content description

Caption	Display names of all items that is displayed name in					
	measurement menu.					
Var Name	The name of built-in selected measurement menu, user don't					
	need modify while display order according to the names.					
Unique Name	Built-in code, user doesn't need modify.					
Measurement	None: Disable rule, Repeat: Repeat this item, Sequential:					
rule	measure by sequence.					
Default item	After choosing the Repeat and Sequential, choose one					
	measurement or calculation to activate the measurement rule.					

7.2.2.2 Interface Description-Measurement Manipulation

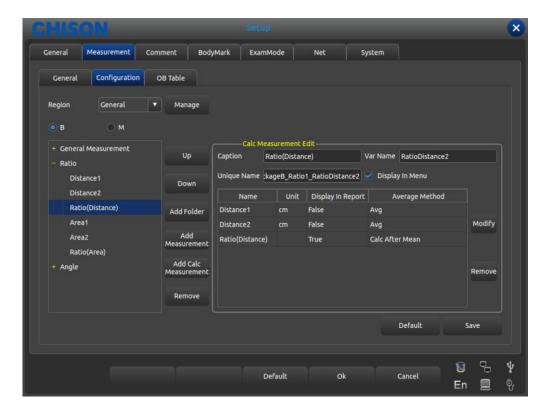


Fig. 29 Interface for Edition of Measurement Formula Sheet 3 Measurement Edit content description

Caption	Display the name of selected term that is display names in the			
	measurement menu.			
Var Name	The name of built-in selected measurement menu, user don't			
	need modify while display order according to the names.			
Unique Name	Built-in code, users don't need modify.			
Display In	Check the required item and it will display on the measurement			
Menu	menu. The item without checking will not display on the			
	measurement menu.			
Choose	Check the methods in measurement menu, press [update] key			
measurement	to switch the method; Otherwise, the measurement is not			
methods	available.			
Display in	Check and display the item in measurement menu, otherwise,			
Report	the item is not displayed.			
Name	Measurement operation of specific measurement display in			
	results.			
Unit	Data unit which measurement operation produces.			
Display In	Whether display in the report or not.			
Report				
Average	The average rule of data.			
Method				
Modify	Press this button to pop up interface to modify measurement			
	operation.			
Remove	Press this button to delete selected measurement operation.			

7.2.2.3 Interface Description-Measurement Calculation

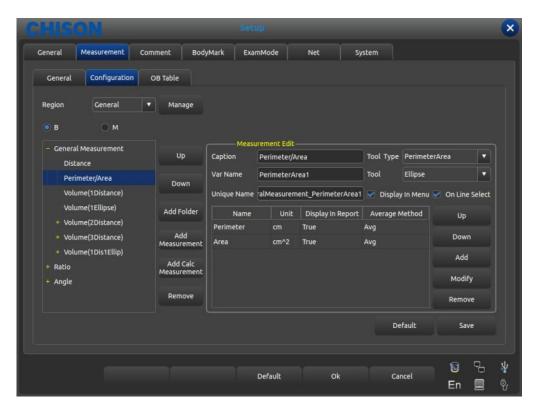


Fig. 30 Interface for Edition of Measurement Formal Sheet 4 Calc Measurement Edit content description

	Sheet 4 Carc Measurement Eart content description				
Caption	Display the name of selected term that is display names in the				
	measurement menu.				
Var Name	The name of built-in selected measurement menu, user don't				
	need modify while display order according to the names.				
Unique Name	Built-in code, users don't need modify.				
Tool	Select available measurement tool type				
Type/Tool	B distance (B line), area/circumference (ellipse, trace), M				
	distance (M vertical line), time (M horizontal line), M slope (M				
	slant).				
Name	Needed measurement operation of specific measurement and				
	calculation.				
Unit	Data unit which measurement operation produces.				
Display In	Whether display in the report or not.				
Report					
Up	Press this button to move measurement operation up.				
Down	Press this button to move measurement operation down.				
Average	The average rule of data.				
Method					
Add	Press this button to pop up interface to add measurement				
	operation.				
Modify	Press this button to pop up interface to modify measurement				
	operation.				
Remove	Press this button to delete selected measurement operation.				

7.2.2.4 Create Measurement Operation

Press [Add] button in measurement operation interface, pop up the following dialog box

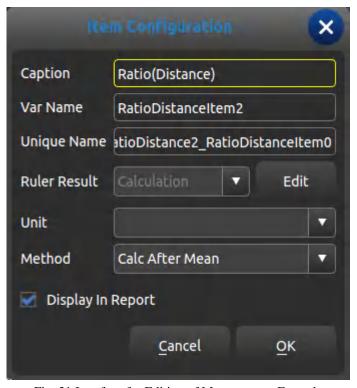


Fig. 31 Interface for Edition of Measurement Formula Sheet 5 Operation content description of creating new measurement

Caption	Display the name of selected term that is display names in the				
	measurement menu.				
Var Name	The name of built-in selected measurement menu, user don't				
	need modify while display order according to the names.				
Unique Name	Built-in code, user doesn't need modify.				
Ruler Result	Needed measurement operation of specific measurement and				
	calculation.				
Edit	Enter into interface to edit formula when selecting calculation				
	item.				
Maximum	The maximum value displays in result zone and report.				
Minimum	The minimum value displays in result zone and report.				
Unit	Data unit which measurement operation produces.				
Display In	Whether display in the report or not.				
Report					
Method	The average rule of data.				

7.2.2.5 Formula Edit-Normal

It is necessary to enter into the following interface when creating measurement operation except OB

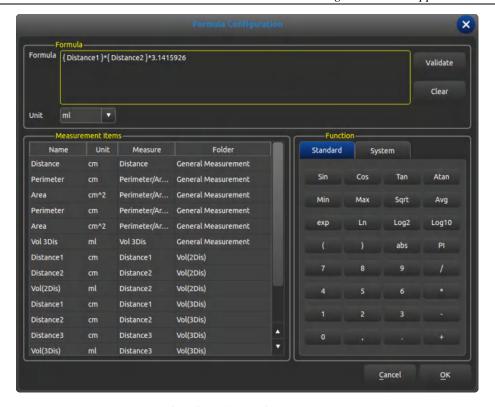


Fig. 32 Interface for Edition of Measurement Formula

- •Formula: edit formula in input box via keyboard and built-in formula.
- Validate: press this button to check whether the formula is right or not after editing formula.
- •Clear: clear the content in the input box.
- •Unit: select the unit of calculation consequence.
- Measurement Items: display all available measurement operation in the measurement menu.
- Function: built-in formula, number input and some parameters that system needs such as BSA, SPSA etc.
- Cancel: cancel editing formula and close the interface.
- •OK: save edited operation and close the interface.

7.2.2.6 Formula Edit-OB

It is necessary to call built-in OB formula sheet when creating OB measurement operation the following function interface is required.

Caution: the results of GA and EDD don't require unit, the unit of this class has been built-in.

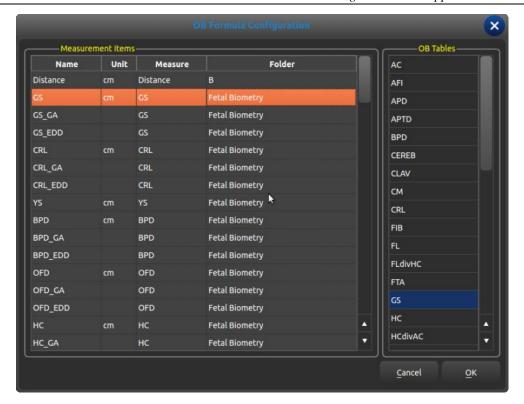


Fig. 33 Interface of OB Formula Configuration

- Measurement Items: display created measurement term by now.
- ●**OB Tables:** built-in OB formula table.

OB List

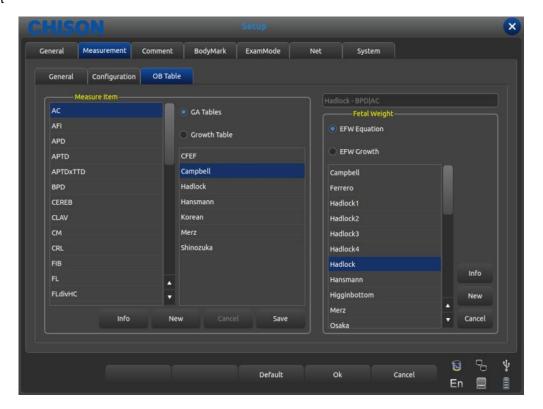


Fig. 34 Interface of OB Table

- Measure Item: OB Measurement Item.
- •GA Tables: Gestational list for the current measuring project.
- •Growth Table: Growth table for the current measuring.

- Fetal Weight: Fetal Weight calculation formula.
- **EFW Equation:** Fetal weight calculation for the current measuring.
- **EFW Growth:** Fetal weight growth curve for the current measuring.
- •Info: Display the gestational age and fetal weight for the current measuring.
- Cancel: Cancel the operation of choosing the formula.
- •Save: Save the users' choice of formulas.

7.3 Annotation

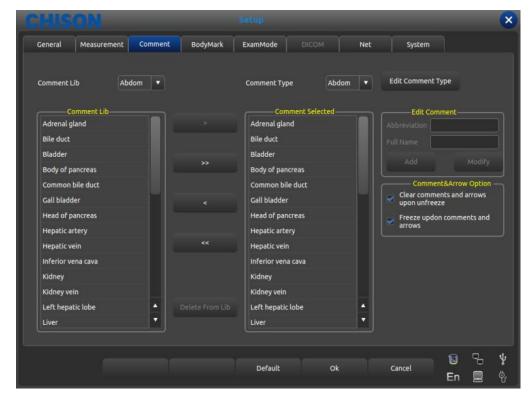


Fig. 35 Annotation Setting Interface

7.3.1 Annotation Library

The annotation database of the system is classified as: abdomen, OB, GYN, Cardiac, small parts, Pathological change Annotation can be made by inputting characters from the soft keyboard or recalling the terms saved in annotation database.

Press [CommentLib] pull down button, pop up annotation name within system, through trackball and [ENTER] key to show required annotation status.

7.3.1.1 Edit Annotation Library

Operation:

- 1.At the annotation status, Move the cursor to the **[Edit Comment Type]** button then press **[ENTER]** key, the annotation will be updated, and can be edited.
- 2.Input name into the new created annotation status box, Move the cursor to the [Create] button then press [ENTER] key, then create new annotation status and appear in selected annotation status list

- 3. Move the cursor to the **[Delete]** button, press **[ENTER]** key, then delete current annotation status in the selected annotation list.
- 4.Alter name of current annotation status list in [Current Type Name] input box, press [ENTER] key on the [Rename] button, then rename the selected annotation status name.

7.3.2 Edit Annotation

Operator uses only current annotation instead of all content annotation status provides inlay common annotation. If necessary, user can import annotation or self-compiled annotation into common annotation.

7.3.2.1 Add annotation from annotation library

Operation:

- 1. Select needed source annotation status via Trackball and [ENTER] key.
- 2. Select needed annotation at [CommentLib] column then press the [ENTER] key to activate this annotation.
- 3.Press [ENTER] key on [>] button to import selected annotation into user-selected annotation status; press [ENTER] on [>] button to move selected annotation in [Comment Selected] column into source annotation.
- 4.Press [ENTER] on [>>] button to import all annotation in source into user-selected annotation status; Press [ENTER] on [>>] button to move all annotation in [Comment Selected] column into source annotation.

7.3.2.2 Add annotation manually

Operation:

- 1.Activate [Edit Comment] input box via Trackball and [ENTER] key, and then input needed abbreviation and full name of annotation.
- 2.Press [ENTER] key on [Add] button, meanwhile this handout will be added into source and user-selected annotation status.

7.3.2.3 Alter annotation

Operation:

- 1.Alter annotation in user-selected status, the abbreviation and full name of annotation will be displayed in **[Edit Comment]** box.
- 2. Activate needed abbreviation and full name via [ENTER] key and alter via keyboard.
- 3. Press [ENTER] key on [Modify] button, modify the annotation in both source and user-selected status.

7.3.2.4 Delete annotation in library

Operation:

Select needed annotation in source status, press [ENTER] key on [Delete from Lib] button, then the annotation deleted.

7.3.3 Comment and Arrow Option

Optional: whether clear comments and arrows upon unfreeze.

Optional: whether freeze upon comments and arrows.

7.4 Body marks

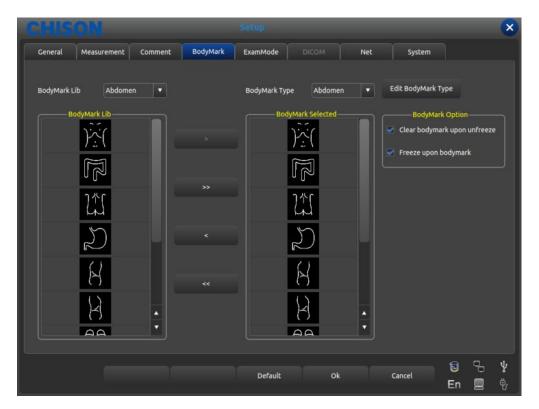


Fig. 36 Interface for Body Mark Setting

7.4.1 Body Marks Library

Built-in body marks: abdomen OB, GYN, Cardiac, small part, urology, vessel.

Press [BodyMarkLib] pull down button, pop up name of built-in body marks, show needed body marks via Trackball and [ENTER] key.

7.4.1.1 Edit body marks library

Operation:

- 1.Press [ENTER] key on [Edit BodyMark Type], pop edit box.
- 2.Input name into the new created body marks box, Move the cursor to the [Create] button then press [ENTER] key, then the new body marks will be created and appear in selected body marks list
- 3. Move the cursor to the [Delete] button then press [ENTER] key, then delete current body marks in the selected list.
- 4.Alter current annotation status list name in [Current Type Name] input box, press [ENTER] key on the [Rename] button, then rename the selected body marks.

7.4.2 Body mark edition

Operation:

1. Select needed source body marks via Trackball and [ENTER] key.

- 2.Select needed body marks at [BodyMarkLib] column then press the [ENTER] key to activate it.
- 3.Press [ENTER] key on [>] button to import selected body marks into user-selected status; press [ENTER] key on [>] button to move selected body marks in [BodyMark Selected] column into source body marks.
- 4.Press [ENTER] key on [>>] button to import all body marks in source into user-selected status; press [ENTER] key on [>>] button to move all body marks in [BodyMarks Selected] column into source.

7.4.3 Bodymark Option

Optional: whether clear bodymark upon unfreeze.

Optional: whether freeze upon bodymark.

7.5 Exam Mode

7.5.1 Exam Mode Edit

Press Utility in the submenu of [MENU], the parameters control area shows as following. According to the corresponding control key to turn on or off the function.



Fig. 37 Interface for Exam Mode Editing

• Preset: Display the current preset.

Rename: Rename the current preset.Load Preset: Load the preset displayed.

• Save: Save the current preset.

•Save As: Save the current preset as others.

7.5.2 Exam Mode Selection

Choose Utility and press [MENU], the following interface pops up. Open the relate function by corresponding control area.

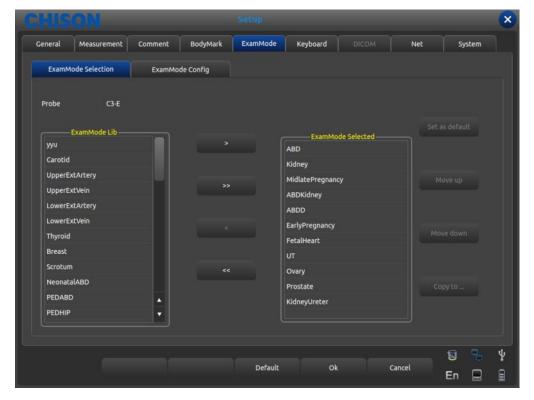


Fig. 38 Interface for ExamMode Setting

- Probe: select needed probe and ExamMode fit for it.
- •ExamModeLib: show all existed Exam modes.
- ●ExamMode Selected: show Exam modes in probe column.
- •>: import selected Exam modes from ExamModeLib column to ExamMode Selected column.
- •>>: import all Exam modes from ExamModeLib column into ExamMode Selected column.
- •<: delete selected Exam modes in ExamMode Selected column.
- •<<: delete all Exam modes in ExamMode Selected column.
- •Set as default: set selected Exam modes in ExamMode Selected column as default
- •Move up: move selected Exam modes in ExamMode Selected column up.
- Move down: move selected Exam modes ExamMode Selected column down.
- **Copy to:** copy the exam mode selected in ExamMode to a specified preset.

7.5.3 Exam mode selection

Operator can define needed Exam mode in detail including annotation, body marks, measurement menu import and export etc.

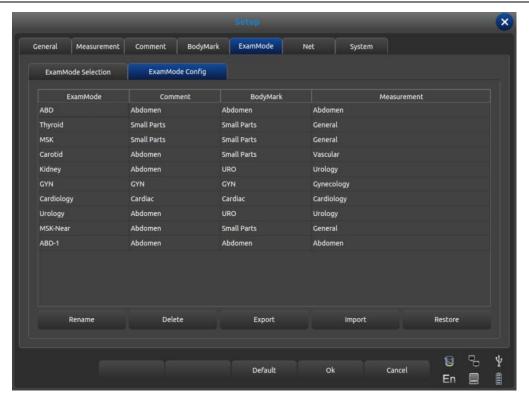


Fig. 39 Interface for Exam Mode Setting

- ●ExamMode: show all existed Exam modes in system
- Comment: double press [ENTER] key to activate widget box, can choose existed annotation status name. After setting, the default of the Exam mode is user-selected.
- •BodyMark: same as Comment, select user-needed default body marks.
- Measurement: same as Comment, select user-needed default measurement menu.
- •Rename: rename selected Exam mode
- Delete: delete selected Exam mode
- **Export:** export all built-in Exam modes into USB flash disk.
- •Import: import all built-in Exam modes into USB flash disk.
- **Restore:** restore all Exam mode as factory setting.

7.6 Keyboard

Users can set the number buttons and the store button on the keyboard, easy to use.

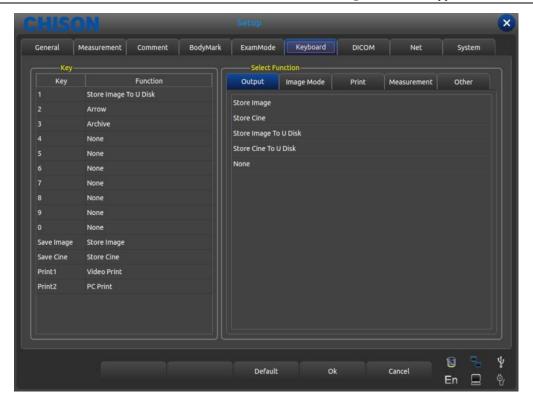


Fig. 40 Interface for Keyboard Setting

- •Output: including store images, store films, store images to U disk, store film to U disk, etc. function options.
- ●Image mode: including image full screen, biopsy, chroma, etc.
- •Print: including video print, pc print etc.
- Measure: including GS, CR, BPD, HC, AC, etc.
- •Others: including arrow, archive.

7.7 DICOM

DICOM includes DICOM Storage, DICOM Worklist, DICOM Print and DICOM SR. If DICOM is to be applied, please make sure DICOM has been activated. In the system page of setting interface, you can check whether DICOM is open or not. If you want to activate DICOM, please contact with CHISON.

There must be DICOM SCP server which has been installed with PACS or other relative DICOM server software

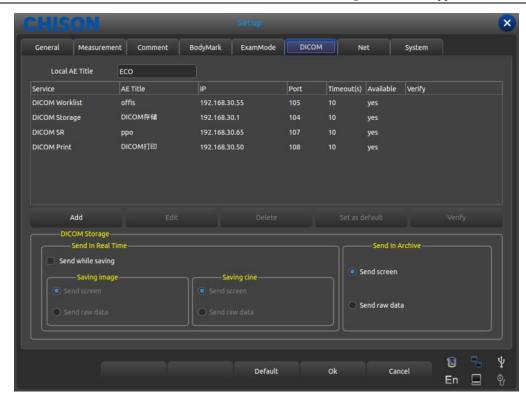
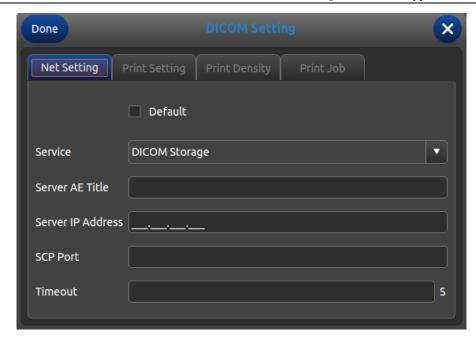


Fig. 41 Interface for DICOM setting

- ●Local AE Title: input local DICOM Title to separate the DICOM equipment in local network.
- •Service: display the local DICOM function worklist,
- •AE Title: display the name of local DICOM AE title,
- •IP: display the IP of DICOM server,
- ●Port: display the port of DICOM server
- Timeout(s): display the delay time
- Available: display whether DICOM is default or not,
- Verify: Press verify button and display whether DICOM setting is correct or not
- •Add: add DICOM function and pop up setting dialog,
- Delete: delete the existed DICOM function
- •Set as default: set one DICOM service as default,
- •Send while saving: check this item and enable DICOM storage while saving image or cine, send clip or image according to activated function.
- •Send in archive: send DICOM storage in archive or review; send clip or image according to activated function.

7.7.1 Add/Edit DICOM Function



• Default: check this option, set DICOM function as default;

•Service: choose DICOM Storage, DICOM Worklist, DICOM Print or DICOM SR;

•Server AE Title: input DICOM server AE name;

● Server IP address: input DICOM IP address;

•SCP port: input DICOM server SCP port;

• Timeout: set the delay time of DICOM;

• **Tip:** choosing the DICOM Print type must be before relative print setting.

7.8 NET Work

Set the unit's and target unit's IP and do the connection testing. And network storage settings, details see the appendix: Procedures of set network sharing in EBit series.

7.9 System

7.9.1 System information

Display the software version, hardware version, system version, etc.

7.9.2 Upgrade

Software and Hardware can be updated by USB flash drives.

Software upgrades File Path: X:\update_SN\AAA.

Hardware upgrades File Path: X:\fpga\AAA.

Keyboard upgrades File Path: X:\ keyboard_update\AAA.

X means USB flash drives. AAA means upgrades content .It should restart manually after hardware update, and after software update, machine can be restarted automatically.

7.9.3 Function Setting

DICOM: press [Open] button, it will bring up the DICOM Key Input dialog box. Input the DICOM SN, and press [OK] button to save and exit.

Full screen show: refer to DICOM.

7.9.4 Installment setting

Input relevant key to open trial function and the detail please contact CHISON Company.

7.9.5 Video VGA

Choose the video data: NTSC, PAL-M, and PAL-D.

Video opened: Choose the item to open this function.

VGA opened: Choose the item to open this function.

7.9.6 Image function

Export hardware SN and import hardware secret key, it only for engineer use.

7.9.7 System Maintenance

Only an authorized service engineer may perform maintenance.

7.9.8 USB Video Printer Option

Adjust the parameters of Video Printer Option: Dark, Light, Sharpness, and Gamma.

Select the parameters needed to adjust, press [Confirm] button on the slider of the parameter, and move the trackball to change the parameter.

Chapter 8 System Maintenance

8.1 Machine Clean

Caution: do turn off the power before cleaning and pull out the cable from socket. There is possibility of electric shock if the device is on

Clean methods:

Use the soft dry cloth to wrap the machine. If the device is quite dirty, use wet soft cloth. After wiping the blot, use soft dry cloth to wipe dry

⚠Caution:

- 1.Don't use organic solvent such s alcohol ,otherwise surface may be ruined
- 2. When cleaning the machine, don't let the liquid inflow the machine, otherwise it may malfunction and there is danger of electric shock.
- 3. When it is necessary to clean the probe connector and peripheral instrument, please contact Sales office contact customer service or agent of CHISON. Any self-cleaning may result in malfunction or degrading the function of device.

8.2 Probe Maintenance

The probes used by this machine can be divided into two series: body surface and intracavity. During all ultrasound scan, ultrasonic radiation on the human body should be as less as possible.

⚠Caution:

- 1. Only person Received professional training can use the probes.
- 2.Probes can't receive pressure sterilizer, when operation in sterile area, disposable sterile probe hood should be applied.
- 3.Make sure not to drop the transducer on hard surface. This can damage the transducer elements and compromise the electrical safety of the transducer.
- 4.Be careful when operation, make sure not to scratch the probe surface.
- 5. Avoid kinking or pinching the transducer cable.
- 6.Make sure not to connect the probe to plug or put adjacent cable into any kind of liquid.
- 7. Keep the probe clean and dry. Power off or freeze when fixing or dismantling the probe.
- 8.Make sure not to use or deposit the probe in the environment above 50 degree.
- 9.If any abnormal phenomena of probe is found, immediately stop operation and contact with Sale Office, Customer Service department or Agents of manufacturer.

Cleaning

The cleaning procedure is fit for all probes. After operation every probe should do cleaning according to stated procedure of this passage. Inspection should be done for intracavity probe depends on condition of use

Cleaning procedure:

- 1. Wipe the remaining coupling gel and blot with flowing clear water. Avoid the joint part between cable and probe touching the water or others
- 2.Use wet gauze or other soft cloth with a little liquid soap to clean the probe totally. Don't use cleaning agent and cleaner with abrasiveness
- 3.Use flowing water to rinse fully. Use soft cloth which has been soaked by the concentration of 70% isopropyl alcohol to scrub. Then check the probe to make sure there is no blot.
- 4. Use clean cloth to dry the probe

Caution: Don't put the body surface probe into liquid below acoustical lens. Intracavity probe can't exceed insertion region. Prohibit putting connector of probe into any liquid.

Infection

Infection procedure id fit for intracavity probe

If it is necessary to use in surgery, please abide with instruction of professional infection person

Infection procedure:

- 1. Obey the cleaning procedure to clean the probe totally
- 2.Prepare and retreat The concentration of 2% glutaraldehyde solution as the infection solution according to the instruction of manufacturer
- 3.Put the insertion region of probe into infection solution, the inserting depth can't exceed insertion region. Don't let the probe connector touch any liquid.
- 4. Soak the probe for 3 h
- 5.Pull out the probe, immediately rinse totally with sterile water and saline. To make sure of no any solution remaining. Please obey the rule to do right rinsing procedure including enough rinsing water and times
- 6. When probe is used in sterile area ,make sure to use disposable sterile probe hood

ACaution:

- 1.Don't soak probe connector into any liquid
- 2.Don't let the soaking depth of intracavity probe exceed insertion region
- 3. Prohibit soaking the probe in the liquid for more than 12 h
- 4. Only use qualified inspection resolution

Deposit:

Please replace the probe in clean and dry environment, avoid direct sunshine

Keep the environment to deposit the probe during -10~50°C, Do not put it in high pressure and vacuum environment.

When accessing probe be careful and avoid ruin.

During transportation or leisure, the probe should be deposited in probe box.

8.3 Safety Check

To make sure this device works normally, a piece of maintenance plan is suggested to make to check the

device regularly If any abnormal phenomena, immediately stop operation and contact with Sale Office, Customer Service department or Agents of manufacturer.

If no image or menu but image, please check following malfunction table. If the malfunction can't be solved, please contact with Sale Office, Customer Service department or Agents of manufacturer.

8.4 Malfunction Check

Serial number	Malfunction	Reason	Measures		
1	Switch button lights but power LED not	Battery lose efficacy, Adapter works irregular	Check the connector between cable and power		
2	Power Led lights but LED no image	The interval time is too short to restart	Restart after 1 minute		
3	LED display character menu but no scan image	Launch power, gain or STC control errors Not connect to probe or the probe connection is not correct Device is in freezing condition	Control launch power, gain or STC control Make sure of right connection Exit from freezing condition		
4	Abnormal image	Exam mode errors Image processing setting errors	Whether Exam mode is proper or not Adjust image processing setting or set it as default		
5	Probe works improperly	1.The plug plugs loosely 2.Internal circuit protects	1.Extract the probe and reinsert 2.Restart		
6	No OB calculation package menu	Do not select the OB application before scanning.	Select the OB application		
7	PRINT-button doesn't work	1.The connected printer is approved 2.Printer power is not on 3.Printer is not connect well	1.Change the approved printer 2.Turn on the printer 3.Connect the printer again		

Chapter 9 Probes

9.1 General Description

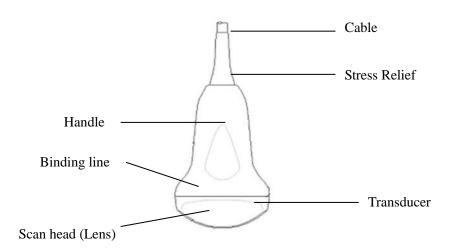


Fig. 42 Convex Probe Overview

The probes provide high spatial and contrast ultrasound imaging of frequencies from 2.0MHz to 11.0MHz. These probes operate by pulsing sound waves into the body and listening to the returning echoes to produce high-resolution brightness mode, and a real time display.

9.2 Care and Maintenance

The probes that come with the system are designed to be durable and dependable. These precision instruments should be inspected daily and handled with care. Please observe the following precautions:

- 1.Do not drop the transducer on hard surface. This can damage the transducer elements and compromise the electrical safety of the transducer.
- 2. Avoid kinking or pinching the transducer cable.
- 3.Use only approved ultrasonic coupling gels.
- 4. Follow the instructions for cleaning and disinfecting that come with each probe.

9.2.1 Inspecting Probes

Before and after each use, inspect carefully the probe's lens, cable, casing, and connector. Look for any damage that would allow liquid to enter the probe. If any damage is suspected, do not use the probe until it has been inspected and repaired/replaced by an authorized Service Representative.



Keep a log of all probe maintenance, along with a picture of any probe malfunction.

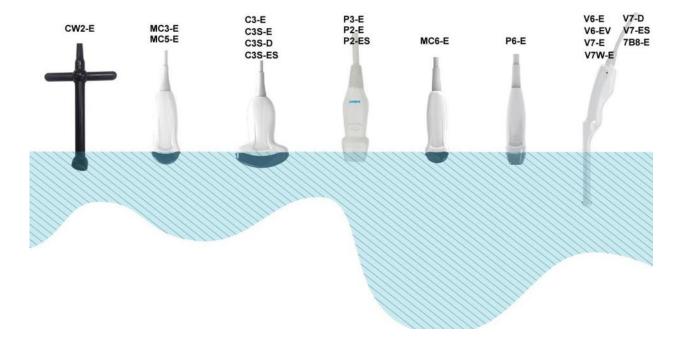


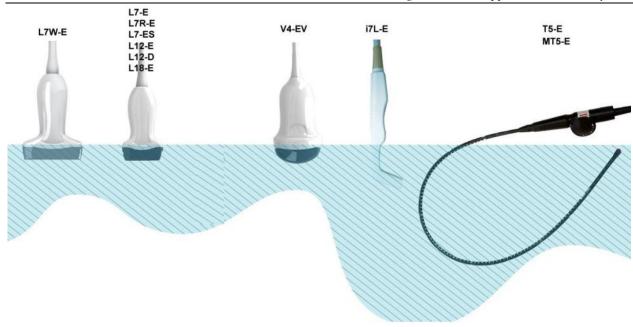
The probes are designed to be used only with this ultrasound system. Use of these probes on any other system or a non-qualified probe may cause electrical shock or damage on the system/transducer.

9.2.2 Cleaning and Disinfecting

- •Disconnect the probe from the ultrasound console and remove all coupling gel from the probe by wiping with a soft cloth and rinsing with flowing water.
- •Wash the probe with mild soap in lukewarm water. Scrub the probe as needed using a soft sponge, gauze, or cloth to remove all visible residue from the probe surface. Scrub the probe as needed using a soft sponge, gauze, or cloth to remove all visible residue from the probe surface.
- •Rinse the probe with enough clean, potable water to remove all disinfectant residues.
- •Use a soft cloth to clean the cable and the user section of the probe with the cleaning disinfectant liquid. Make sure that the surface of the probe and cable is wetted thoroughly with the cleaning-disinfectant.
- •Allow probe to air dry completely.
- Reconnect the probe to the ultrasound console and place the probe into its holder.

Probe Immersion Levels





ACAUTION

These transducers are not designed to withstand heat sterilization methods. Exposure to temperatures in excess of 60 °C will cause permanent damage. The transducers are not designed to be totally submerged in fluid, as permanent damage will result if the entire transducer is submerged.

Probe Safety

Handling precautions

Ultrasound probes are highly sensitive medical instruments that can easily be damaged by improper handling. Use care when handling and protect from damage when not in use. DO NOT use a damaged or defective probe. Failure to follow these precautions can result in serious injury and equipment damage.

Electrical shock hazard:

The probe is driven with electrical energy that can injure the patient or user if live internal parts are contacted by conductive solution:

- •DO NOT immerse the probe into any liquid beyond the level indicated by the immersion level diagram. Never immerse the probe connector into any liquid.
- •Prior to each use, visually inspect the probe lens and case area for cracks, cuts, tears, and other signs of physical damage. DO NOT use a probe that appears to be damaged until you verify functional and safe performance. You need to perform a more thorough inspection, including the cable, strain relief, and connector, each time you clean the probe.

- •Before inserting the connector into the probe port, inspect the probe connector pins. If a pin is bent, DO NOT use the probe until it has been inspected and repaired/replaced by a CHISON Service Representative.
- Electrical leakage checks should be performed on a routine basis by CHISON Service or qualified hospital personnel.

Mechanical hazard:

A defective probe or excess force can cause patient injury or probe damage:

- •Observe depth markings and do not apply excessive force when inserting or manipulating endo-cavitary probe.
- •Inspect probes for sharp edges or rough surfaces that may injure sensitive tissue.
- •DO NOT apply excessive force to the probe connector when inserting into the probe port. The pin of a probe connector may bend.

Special handling instructions

Using protective sheaths

The use of market cleared probe sheaths is recommended for clinical applications. Reference FDA March 29, 1991 "Medical Alert on Latex Products".

Protective sheaths may be required to minimize disease transmission. Probe sheaths are available for use with all clinical situations where infection is a concern. Use of legally marketed, sterile probe sheaths is strongly recommended for endo-cavitary procedures.

DO NOT use pre-lubricated condoms as a sheath. In some cases, they can damage the probe. Lubricants in these condoms may not be compatible with probe construction.

Devices containing latex may cause severe allergic reaction in latex sensitive individuals. Refer to FDA's March 29, 1991 Medical Alert on latex products.

DO NOT use an expired probe sheath. Before using a sheath, verify if it has expired.

Endo-cavitary Probe Handling Precautions

If the sterilization solution comes out of the endo-cavitary probe, please follow the cautions below:

Sterilant Exposure to Patient (e.g., Cidex): Contact with a sterilant to the patient's skin for mucous membrane may cause an inflammation. If this happens, refer to instruction manual of the sterilant.

Sterilant Exposure from Probe handle to Patient (e.g. Cidex): DO NOT allow the sterilant to contact the patient. Only immerse the probe to its specified level. Ensure that no solution has entered the probe's handle before scanning the patient. If sterilant comes into contact with the patient, refer to the sterilant's instruction manual.

Sterilant Exposure from Probe connector to Patient (e.g. Cidex): DO NOT allow the sterilant to contact the patient. Only immerse the probe to its specified level. Ensure that no solution has entered the probe's connector before scanning the patient. If sterilant comes into contact with the patient, refer to the sterilant's instruction manual.

Endo-cavitary Probe Point of Contact: Refer to the sterilant's instruction manual.

Probe handling and infection control:

This information is intended to increase user awareness of the risks of disease transmission associated with using this equipment and provide guidance in making decisions directly affecting the safety of the patient as well as the equipment user.

Diagnostic ultrasound systems utilize ultrasound energy that must be coupled to the patient by direct physical contact.

Depending on the type of examination, this contact occurs with a variety of tissues ranging from intact skin in a routine exam to recirculating blood in a surgical procedure. The level of risk of infection varies greatly with the type of contact.

One of the most effective ways to prevent transmission between patients is with single use or disposable devices. However, ultrasound transducers are complex and expensive devices that must be reused between patients. It is very important, therefore, to minimize the risk of disease transmission by using barriers and through proper processing between patients.

Risk of Infection

ALWAYS clean and disinfect the probe between patients to the level appropriate for the type of examination and use FDA-cleared probe sheaths where appropriate.

Adequate cleaning and disinfection are necessary to prevent disease transmission. It is the responsibility of the equipment user to verify and maintain the effectiveness of the infection control procedures in use. Always use sterile, legally marketed probe sheaths for intra-cavitary procedures.

Probe Cleaning process:

DO disconnect the probe from the system prior to cleaning/disinfecting the probe. Failure to do so could damage the system.

Perform Cleaning probe after each use

- •Disconnect the probe from the ultrasound console and remove all coupling gel from the probe by wiping with a soft cloth and rinsing with flowing water.
- •Wash the probe with mild soap in lukewarm water. Scrub the probe as needed using a soft sponge, gauze, or cloth to remove all visible residue from the probe surface. Prolonged soaking or scrubbing with a soft bristle brush (such as a toothbrush) may be necessary if material has dried onto the probe surface.



To avoid electrical shock, always turn off the system and disconnect the probe before cleaning the probe.

ACAUTION

Take extra care when handling the lens face of the Ultrasound transducer. The lens face is especially sensitive and can easily be damaged by rough handling. NEVER use excessive force when cleaning the lens face. Rinse the probe with enough clean potable water to remove all visible soap residue.

Air dry or dry with a soft cloth.

ACAUTION

To minimize the risk of infection from blood-borne pathogens, you must handle the probe and all disposables that have contacted blood, other potentially infectious materials, mucous membranes, and non-intact skin in accordance with infection control procedures. You must wear protective gloves when handling potentially infectious material. Use a face shield and gown if there is a risk of splashing or splatter.

Disinfecting the probes:

After each use, please disinfect the probes. Ultrasound probes can be disinfected using liquid chemical germicides. The level of disinfection is directly related to the duration of contact with the germicide. Increased contact time produces a higher level of disinfection.

In order for liquid chemical germicides to be effective, all visible residue must be removed during the cleaning process. Thoroughly clean the probe, as described earlier before attempting disinfection.

You MUST disconnect the probe from the system prior to cleaning/disinfecting the probe. Failure to do so could damage the system.

DO NOT soak probes in liquid chemical germicide for longer than is stated by the germicide instructions for use. Extended soaking may cause probe damage and early failure of the enclosure, resulting in possible electric shock hazard.

- •Prepare the germicide solution according to the manufacturer's instructions. Be sure to follow all precautions for storage, use and disposal. The transducer is not designed to be totally submerged in fluid. Permanent damage will result if the entire transducer is submerged. The immersed part shall not exceed the transducer binding line.
- •Place the cleaned and dried probe in contact with the germicide for the time specified by the germicide manufacturer. High-level disinfection is recommended for surface probes and is required for endo-cavitary probes (follow the germicide manufacturer's recommended time).
- After removing from the germicide, rinse the probe following the germicide manufacturer's rinsing instructions. Flush all visible germicide residues from the probe and allow to air dry.

Ultrasound transducers can easily be damaged by improper handling and by contact with certain chemicals. Failure to follow these precautions can result in serious injury and equipment damage

- •Do not immerse the probe into any liquid beyond the level specified for that probe. Never immerse the transducer connector or probe adapters into any liquid.
- Avoid mechanical shock or impact to the transducer and do not apply excessive bending or pulling force to the cable.
- Transducer damage can result from contact with inappropriate coupling or cleaning agents:
- •Do not soak or saturate transducers with solutions containing alcohol, bleach, ammonium chloride compounds or hydrogen peroxide
- Avoid contact with solutions or coupling gels containing mineral oil or lanolin
- Avoid temperatures above 60 °C. Under no circumstances should the transducer be subjected to heat sterilization method. Exposure to temperatures above 60 °C will cause permanent damage to the transducer.
- •Inspect the probe prior to use for damage or degeneration to the housing, strain relief, lens and seal. Do not use a damaged or defective probe.

Coupling gels

DO NOT use unrecommended gels (lubricants). They may damage the probe and void the warranty. *AQUASONIC Gel made by R. P. Kincheloe Company in USA is recommended.*

In order to assure optimal transmission of energy between the patient and probe, a conductive gel must be applied liberally to the patient where scanning will be performed.

ACAUTION

Please do not use any gel or other materials which are not provided by CHISON. Un-authorized gel, lubricants and other materials may corrode probes and other parts of the device, for example the keyboard. This may reduce the safety and effectiveness of the system and probes, and may also reduce the life time of the systems and probes. Damages caused by such reason will not be covered by the warranty.

DO NOT apply gel to the eyes. If there is gel contact to the eye, flush eye thoroughly with water.

Coupling gels should not contain the following ingredients as they are known to cause probe damage:

- •Methanol, ethanol, isopropanol, or any other alcohol-based product.
- Mineral oil
- Iodine
- Lotions
- Lanolin
- Aloe Vera
- Olive Oil
- Methyl or Ethyl Parabens (para hydroxybenzoic acid)
- Dimethylsilicone

Planned maintenance

The following maintenance plan is suggested for the system and probes to ensure optimum operation and safety.

Daily: inspect the probes

After each use: clean the probes disinfect the probes.

As necessary: inspect the probes, clean the probes, and disinfect the probes.

Returning/Shipping Probes and Repair Parts

Transportation dept. and our policy require that equipment returned for service MUST be clean and free of blood and other infectious substances.

When you return a probe or part for service, you need to clean and disinfect the probe or part prior to packing and shipping the equipment.

Ensure that you follow probe cleaning and disinfection instructions provided in this Manual.

This ensures that employees in the transportation industry as well as the people who receive the package are

protected from any risk.

AIUM outlines cleaning the endocavitary transducer:

Guidelines for Cleaning and Preparing Endocavitary Ultrasound Transducers between Patients from AIUM

Approved June 4, 2003

The purpose of this document is to provide guidance regarding the cleaning and disinfection of transvaginal and transrectal ultrasound probes.

All sterilization/disinfection represents a statistical reduction in the number of microbes present on a surface. Meticulous cleaning of the instrument is the essential icon to an initial reduction of the microbial/organic load by at least 99%. This cleaning is followed by a disinfecting procedure to ensure a high degree of protection from infectious disease transmission, even if a disposable barrier covers the instrument during use.

Medical instruments fall into different categories with respect to potential for infection transmission. The most critical level of instruments are those that are intended to penetrate skin or mucous membranes. These require sterilization. Less critical instruments (often called "semi-critical" instruments) that simply come into contact with mucous membranes such as fiber optic endoscopes require high-level disinfection rather than sterilization.

Although endocavitary ultrasound probes might be considered even less critical instruments because they are routinely protected by single use disposable probe covers, leakage rates of 0.9% - 2% for condoms and 8%-81% for commercial probe covers have been observed in recent studies. For maximum safety, one should therefore perform high-level disinfection of the probe between each use and use a probe cover or condom as an aid in keeping the probe clean.

There are four generally recognized categories of disinfection and sterilization. Sterilization is the complete elimination of all forms or microbial life including spores and viruses.

Disinfection, the selective removal of microbial life, is divided into three classes:

High-Level Disinfection - Destruction/removal of all microorganisms except bacterial spores.

Mid-Level Disinfection - Inactivation of Mycobacterium Tuberculosis, bacteria, most viruses, fungi, and some bacterial spores.

Low-Level Disinfection - Destruction of most bacteria, some viruses and some fungi. Low-level disinfection will not necessarily inactivate Mycobacterium Tuberculosis or bacterial spores.

The following specific recommendations are made for the use of Endocavitary ultrasound transducers. Users should also review the Centers for Disease Control and Prevention document on sterilization and disinfection of medical devices to be certain that their procedures conform to the CDC principles for disinfection of patient care equipment.

1. CLEANING

After removal of the probe cover, use running water to remove any residual gel or debris from the probe. Use a damp gauze pad or other soft cloth and a small amount of mild non-abrasive liquid soap (household

dishwashing liquid is ideal) to thoroughly cleanse the transducer. Consider the use of a small brush especially for crevices and areas of angulation depending on the design of your particular transducer. Rinse the transducer thoroughly with running water, and then dry the transducer with a soft cloth or paper towel.

2. DISINFECTION

Cleaning with a detergent/water solution as described above is important as the first step in proper disinfection since chemical disinfectants act more rapidly on clean surfaces. However, the additional use of a high level liquid disinfectant will ensure further statistical reduction in microbial load. Because of the potential disruption of the barrier sheath, additional high level disinfection with chemical agents is necessary. Examples of such high level disinfectants include but are not limited to:

- ●2% glutaraldehyde products (a variety of available proprietary products including "Cidex," "Metricide," or "Procide").
- •Non-glutaraldehyde agents including Cidex OPA (o-phthalaldehyde), Cidex PA (hydrogen peroxide & peroxyacetic acid).
- ●7.5% Hydrogen Peroxide solution.
- •Common household bleach (5.25% sodium hypochlorite) diluted to yield 500 parts per million chlorine (10 cc in one liter of tap water). This agent is effective, but generally not recommended by probe manufacturers because it can damage metal and plastic parts.

Other agents such as quaternary ammonium compounds are not considered high level disinfectants and should not be used. Isopropanol is not a high level disinfectant when used as a wipe and probe manufacturers generally do not recommend soaking probes in the liquid.

The FDA has published a list of approved sterilants and high level disinfectants for use in processing reusable medical and dental devices. That list can be consulted to find agents that may be useful for probe disinfection.

Practitioners should consult the labels of proprietary products for specific instructions. They should also consult instrument manufacturers regarding compatibility of these agents with probes. Many of the chemical disinfectants are potentially toxic and many require adequate precautions such as proper ventilation, personal protective devices (gloves, face/eye protection, etc.) and thorough rinsing before reuse of the probe.

3. PROBE COVERS

The transducer should be covered with a barrier. If the barriers used are condoms, these should be nonlubricated and nonmedicated. Practitioners should be aware that condoms have been shown to be less prone to leakage than commercial probe covers, and have a six-fold enhanced AQL (acceptable quality level) when compared to standard examination gloves. They have an AQL equal to that of surgical gloves. Users should be aware of latex-sensitivity issues and have available nonlatex-containing barriers.

4. ASEPTIC TECHNIQUE

For the protection of the patient and the health care worker, all endocavitary examinations should be performed with the operator properly gloved throughout the procedure. Gloves should be used to remove the condom or other barrier from the transducer and to wash the transducer as outlined above. As the barrier (condom) is removed, care should be taken not to contaminate the probe with secretions from the patient. At the completion

of the procedure, hands should be thoroughly washed with soap and water.

Note: Obvious disruption in condom integrity does NOT require modification of this protocol. These guidelines take into account possible probe contamination due to a disruption in the barrier sheath.

In summary, routine high-level disinfection of the endocavitary probe between patients, plus the use of a probe cover or condom during each examination is required to properly protect patients from infection during endocavitary examinations. For all chemical disinfectants, precautions must be taken to protect workers and patients from the toxicity of the disinfectant.

Amis S, Ruddy M, Kibbler CC, Economides DL, MacLean AB. Assessment of condoms as probe covers for transvaginal sonography. J Clin Ultrasound 2000;28:295-8.

Rooks VJ, Yancey MK, Elg SA, Brueske L. Comparison of probe sheaths for endovaginal sonography. Obstet. Gynecol 1996;87:27-9.

Milki AA, Fisch JD. Vaginal ultrasound probe cover leakage: implications for patient care. Fertil Steril 1998;69:409-11.

Hignett M, Claman P. High rates of perforation are found in endovaginal ultrasound probe covers before and after oocyte retrieval for in vitro fertilization-embryo transfer. J Assist Reprod Genet 1995;12:606-9.

Sterilization and Disinfection of Medical Devices: General Principles. Centers for Disease Control, Division of Healthcare Quality Promotion. http://www.cdc.gov/ncidod/hip/sterile/sterilgp.htm (5-2003).

ODE Device Evaluation Information--FDA Cleared Sterilants and High Level Disinfectants with General Claims for Processing Reusable Medical and Dental Devices, March 2003. http://www.fda.gov/cdrh/ode/germlab.html (5-2003).

9.3 Probe Operation Instructions

For details on connecting, activating, deactivating, disconnecting, transporting and storing the probes.

9.3.1 Scanning the Patient

In order to assure optimal transmission of energy between the patient and probe, a conductive gel must be applied liberally to the patient where scanning will be performed.

After the examination is complete, follow the cleaning and disinfecting, or sterilizing procedures as appropriate.

9.3.2 Operating Transvaginal probe

The transvaginal probe is an endo-cavity probe, for the operation safety, please refer to "Care and

Maintenance" for cleaning and disinfection.

The temperature at the tip of the probe displays on the screen for monitoring. No temperature above 43 °C is allowed. It also depends on the patient's body temperature. When the temperature of probe tip exceeds 43° C, the probe will stop working immediately to protect the patient.

Transvaginal probe should be used with FDA approved condom or probe cover. See the following instructions to put the probe into the condom:

ACAUTION

- •Some patients may be allergic to natural rubber or medical device with rubber contains. FDA suggests that the user to identify these patients and be prepared to treat allergic reactions promptly before scanning.
- •Only water-solvable solutions or gel can be used. Petroleum or mineral oil-based materials may harm the cover.
- •When the transvaginal probe is activated outside patient's body, its acoustic output level should be decreased to avoid any harmful interference with other equipment.

Operation Procedure:

- ▶Put on medical sterile glove
- ➤Get the condom for the package.
- ➤ Unfold the condom.
- Load some ultrasound gel into condom.
- Take the condom with one hand, and put the probe head into the condom.
- Fasten the condom on the end of the probe handle.
- Confirm the integrity of the condom, and repeat the above steps to the condom if any damage to the condom is found.

9.3.3 Cleaning and Disinfecting TV and TR Probes

We strongly recommend wearing gloves when cleaning and disinfecting any endocavitary probe.

- •Every time before and after each exam, please clean the probe handle and disinfect the transvaginal and transrectal probes probe using liquid chemical germicides
- If the probe is contaminated with body fluids, you should disinfect the probe after cleaning.
- •Regard any exam waste as potentially infectious and dispose of it accordingly.

ACAUTION

•Since the probe is not waterproof, you should disconnect it from the system before cleaning or disinfecting.

Before and after each exam, please clean the probe handle and disinfect the transvaginal and transrectal probes using liquid chemical germicides.

Cleaning

You can clean the transvaginal and transrectal probes to remove all coupling gel by wiping with a soft cloth and rinsing with flowing water. Then wash the probe with mild soap in lukewarm water. Scrub the probe as

needed and use a soft cloth to remove all visible residues from the transvaginal probe surface. Rinse the probe with enough clean potable water to remove all visible soap residues, and let the probe air dry.

\triangle CAUTION

Please remove the cover (if any) before cleaning the probe. (The cover like condom is one time usable). When cleaning the TV and TR probes, it is important to be sure that all surfaces are thoroughly cleaned.

Disinfecting

2 Glutaraldehyde-based solutions have been shown to be very effective for this purpose. Cidex is the only germicide that has been evaluated for compatibility with the material used to construct the probes.

To keep the effectiveness of the disinfection solutions, a thoroughly cleaning must be done to the probe before the disinfecting, make sure no residues remain on the probe.

Disinfecting Procedure:

Following all precautions for storage, use and disposal, prepare the germicide solution according to the manufacturer's instructions.

Place the cleaned and dried probe to contact with the germicide, being careful not to let the probe drop to the bottom of the container and thus damage the probe.

After placing/immersing, rotate and shake the probe while it is below the surface of the germicide to eliminate air pockets. Allow the germicide to remain in contact with the fully immersed probe. For high level disinfection, follow the manufacturer's recommended time.

Following all precautions for storage, use and disposal, prepare the germicide solution according to the manufacturer's instructions.

After removing from the germicide, rinse the probe according to the germicide manufacturer's rinsing instructions.

Flush all visible germicide residues from the probe and allow to air dry.

9.4 Service Responsibility

If users install, use and maintain the system fully according to CHISON's installation manual, operation manual and service manual, then CHISON EBit main unit has a life time of 5 years and CHISON EBit probes have life time of 5 years after ex-work.

The warranty of the system and probes after ex-work is as the time in the warranty card.

The system is a precise electronic system. Only the CHISON's authorized service engineer could replace the defective parts. Any assembly, disassembly, handling, repair, or replacement by any other people may have adverse impact on the safety and effectiveness of the systems and probes, and thus will reduce the life time of the system and probes, and such systems and probes will not be covered by CHISON warranty after the above improper handling. Standard maintenance must be performed by CHISON's authorized service engineer

during the life time of the product.

CAUTION: When the above life time is expired, the effectiveness and safety of system and probes maybe greatly affected, so it's NOT suggested to continue using the system and probes even the system and probes seem work properly. But if user still wants to continue using the system and probes, user should first contact CHISON service center at CHISON headquarter to arrange the necessary safety check and calibration by CHISON's authorized service engineer. If CHISON headquarter service center provides the calibration certificate for the related system or probe, then user could continue use the system or probes according to the calibration certificate. However, if CHISON headquarter service center concludes that the system or probe is no longer complied to the safety and effectiveness standard, then user should immediately stop using the system or probe. User understands that such check and calibration cost will be born by the user.

Systems and probes keep on using after the life time may also be difficult to repair and maintain, so it's suggested to renew the product after the life time.

Appendix A: The Information of EC Representative

R Sight B.V.

Address: Roald Dahllaan 47, 5629 MC, Eindhoven. The Netherlands

SRN: NL-AR-000010445

Tel:0031640845545

CCI No.:76704726 E-mail:info@rsight.nl

Appendix B: Acoustic Output Report Table

System: EBIT

Transducer Model: <u>C3-E</u> Operating Mode: <u>B</u>

Index Label				TIS			TIB		
			MI	Scan	non-scan		non goon	TIC	
					A _{aprt} ≤1	A _{aprt} >1	non-scan		
Global Maxi	Global Maximum Index Value		0.7	1.0					
	p _{r.3}	$p_{\mathrm{r},lpha}$	(MPa)	1.32					
	\mathbf{W}_{o}	P	(mW)		511.48				
	min of [W _{.3} (z ₁), I _{TA.3} (z ₁)]	$\begin{aligned} & \text{min of} \\ & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)						
Associated	z_1	$Z_{\rm s}$	(cm)						
Acoustic	Z _{bp}	$Z_{ m bp}$	(cm)						
Parameter	Z_{sp}	Z_b	(cm)						
	Z@PII.3max	Z at max $I_{pi\alpha}$	(cm)	6.5					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	$f_{ m awf}$	(MHz)	2.73	2.75				
	Dim of A	A _{aprt} Dim of A _{aprt}	X (cm)		4.61				
	Dim of A _{aprt}		Y (cm)		1.10				
	PD	$t_{\rm d}$	(µsec)	0.55					
	PRF	prr	(Hz)	9662					
Other	$p_r@PII_{max}$	p _r at max I _{pi}	(MPa)	2.35					
Information	$d_{eq}@PII_{max}$	d_{eq} at max I_{pi}	(cm)						
Information	Focal Length Focal Length	Eggal Langth	FL _x (cm)		0.21				
		Focal Length	FLy (cm)		0.33				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	75.41					
Operating	Mode	Mode	NA	В	В				
Control	Focus	Focus	(cm)	7	7				
Conditions	Power	Power	(%)	100	100				

Transducer Model: <u>C3-E</u> Operating Mode: <u>THI-B</u>

			_	1119 1110 41		TIS		TIB	
	Inde	x Label		MI	G	non-s	scan		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Maxi	mum Index Valu	e		0.7	0.7				
	$p_{r.3}$	$p_{r,\alpha}$	(MPa)	1.24					
	W_{o}	P	(mW)		511.48				
	min of [W _{.3} (z ₁), I _{TA.3} (z ₁)]	$\begin{aligned} & \text{min of} \\ & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)						
Associated	\mathbf{z}_1	Z_{s}	(cm)						
Acoustic	Z_{bp}	Z_{bp}	(cm)						
Parameter	Z_{sp}	Z_b	(cm)						
	Z@PII _{.3max}	Z at max $I_{pi \alpha}$	(cm)	6.5					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_{c}	$f_{ m awf}$	(MHz)	2.74	2.74				
	Dim of A	Dim of A	X (cm)		4.61				
	Dim of A _{aprt}	Dim of A _{aprt}	Y (cm)		1.10				
	PD	$t_{\rm d}$	(µsec)	0.54					
	PRF	prr	(Hz)	9668					
Other	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	2.35					
Other Information	d _{eq} @PII _{max}	d _{eq} at max I _{pi}	(cm)						
Information	Essal I snoth	Facal Laureth	FL_{x} (cm)		0.24				
	Focal Length	Focal Length	FLy (cm)		0.31				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	75.39					
Operating	Mode	Mode	NA	THI-B	THI-B				
Control	Focus	Focus	(cm)	7	7				
Conditions	Power	Power	(%)	100	100				

Transducer Model: <u>C3-E</u> Operating Mode: <u>B+C</u>

				2115 1/104		TIS		TIB	
	Inde	x Label		MI	C	non-	scan		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Maxi	mum Index Valu	e		0.5	0.6				
	$p_{r.3}$	$p_{r,\alpha}$	(MPa)	0.92					
	W_{o}	P	(mW)		345.59				
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	$\begin{aligned} & \text{min of} \\ & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)						
Associated	z_1	Z_{s}	(cm)						
Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	Z_{sp}	Z_b	(cm)						
	z@PII _{.3max}	Z at max $I_{pi\alpha}$	(cm)	6.2					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	f_{awf}	(MHz)	2.90	2.89				
	Dim of A	Dim of A _{aprt}	X (cm)		4.61				
	Dim of A _{aprt}	Dilli Of A _{aprt}	Y (cm)		1.10				
	PD	$t_{\rm d}$	(µsec)	1.32					
	PRF	prr	(Hz)	6012					
	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	1.65					
Other	d _{eq} @PII _{max}	d _{eq} at max I _{pi}	(cm)						
Information	Focal Langth	Food Langth	FL _x (cm)		0.21				
	Focal Length	Focal Length	FLy (cm)		0.31				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	35.25					
Operating	Mode	Mode	NA	С	C				
Control	Focus	Focus	(cm)	6	6				
Conditions	Power	Power	(%)	100	100				

Transducer Model: <u>C3-E</u> Operating Mode: <u>B+C+PW</u>

		1. <u>C5-E</u>				TIS		TIB	
	Inde	x Label		MI	G	non-	scan		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Maxi	mum Index Valu	e		0.5			1.8	1.0	
	p _{r.3}	$p_{r,\alpha}$	(MPa)	0.84					
	Wo	P	(mW)					621.55	
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	$\begin{aligned} & \text{min of} \\ & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)				276.05		
Associated	z_1	Z_{s}	(cm)				4.1		
Acoustic	Z _{bp}	Z_{bp}	(cm)				3.8		
Parameter	Z_{sp}	Z_b	(cm)					6.5	
	Z@PII.3max	Z at max $I_{pi \alpha}$	(cm)	4.4					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)					0.67	
	f_c	$\mathbf{f}_{\mathrm{awf}}$	(MHz)	2.88			2.85	2.82	
	Dim of A	Dim of A	X (cm)				4.61	4.61	
	Dim of A _{aprt}	Dim of A _{aprt}	Y (cm)				1.10	1.10	
	PD	$t_{\rm d}$	(µsec)	1.29					
	PRF	prr	(Hz)	9659					
041	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	1.43					
Other Information	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)					0.63	
Information	Essal I susath	Essal Lausth	FL_{x} (cm)				0.31		
	Focal Length	Focal Length	FLy (cm)				0.41		
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	129.62					
Operating	Mode	Mode	NA	PW			PW	PW	
Control	Focus	Focus	(cm)	6			7	10	
Conditions	Power	Power	(%)	100			100	100	

Transducer Model: <u>C3-E</u> Operating Mode: <u>M</u>

			_	ing Mode		TIS		TIB	
	Inde	x Label		MI	G	non-	scan		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Maxi	mum Index Valu	e		1.1			1.9	1.2	
	p _{r.3}	$p_{r,\alpha}$	(MPa)	1.57					
	W_{o}	P	(mW)					511.21	
	min of [W _{.3} (z ₁), I _{TA.3} (z ₁)]	$\begin{aligned} & \text{min of} \\ & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)				227.42		
Associated	z_1	Z_{s}	(cm)				4.2		
Acoustic	Z _{bp}	Z_{bp}	(cm)				3.8		
Parameter	Z_{sp}	Z_b	(cm)					5.1	
	Z@PII.3max	Z at max $I_{pi \alpha}$	(cm)	5.5					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)					0.81	
	f_c	f_{awf}	(MHz)	2.71			2.77	2.74	
	Dim of A _{aprt}	Dim of A _{aprt}	X (cm)				4.61	4.61	
	Dilli Of A _{aprt}	Dilli Of A _{aprt}	Y (cm)				1.10	1.10	
	PD	$t_{\rm d}$	(µsec)	0.55					
	PRF	prr	(Hz)	4756					
	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	2.66					
Other	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)					0.8	
Information	Focal Length	Focal Length	FL_{x} (cm)				0.23		
	rocai Lengui	rocai Lengui	FLy (cm)				0.18		
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	111.26					
Operating	Mode	Mode	NA	M			M	M	
Control	Focus	Focus	(cm)	7			6	6	
Conditions	Power	Power	(%)	100			100	100	

Transducer Model: <u>C3S-E</u> **Operating Mode: B**

		ici. <u>C35-E</u>		perating		TIS		TIB	
	Index	Label		MI		non-	scan		TIC
	mucx	Laber		1711	Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	TIC
Global Maxin	num Index Va	lue		0.8	1.0				
	$p_{r.3}$	$p_{r,^{lpha}}$	(MPa)	1.29					
	W_{o}	P	(mW)		508.22				
	min of	min of							
	$[W_{.3}(z_1),$	$[P_{\alpha}(Z_s),I_{ta,\alpha}(Z_s)$	(mW)						
	$I_{TA.3}(z_1)$]							
Associated	z_1	$Z_{\rm s}$	(cm)						
Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	z_{sp}	Z_b	(cm)						
	z@PII _{.3max}	Z at max $I_{pi \alpha}$	(cm)	6.6					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	$f_{ m awf}$	(MHz)	2.60	2.72				
	Dim of	Dim of A	X (cm)		2.88				
	A_{aprt}	Dim of A _{aprt}	Y (cm)		1.10				
	PD	t _d	(µsec)	0.56					
	PRF	prr	(Hz)	9685.2					
	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	2.35					
Other	d _{eq} @PII _{max}	d _{eq} at max I _{pi}	(cm)						
Information	Focal		FL _x (cm)		1.26				
	Length	Focal Length	FLy (cm)		1.28				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	78.65					
Operating	Mode	Mode	NA	В	В				
Control	Focus	Focus	(cm)	7	7				
Conditions	Power	Power	(%)	100	100				

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Transducer Model: <u>C3S-E</u> Operating Mode: <u>THI-B</u>

			_		1000.	TIS		TIB	
	Index	k Label		MI		non	-scan		TIC
	muez	Labei		1711	Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	ne
Global Maxi	mum Index Va	lue		0.8	0.9				
	p _{r.3}	$p_{r,^{lpha}}$	(MPa)	1.22					
	Wo	P	(mW)		508.22				
	min of [W _{.3} (z ₁), I _{TA.3} (z ₁)]	$\begin{aligned} & \text{min of} \\ & & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)						
Associated	z_1	Z_{s}	(cm)						
Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	Z _{sp}	Z_b	(cm)						
	z@PII _{.3max}	Z at max $I_{pi \alpha}$	(cm)	6.6					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	$f_{ m awf}$	(MHz)	2.62	2.72				
	Dim of A _{aprt}	Dim of A _{aprt}	X (cm)		2.88				
	Dilli Of A _{aprt}	Dilli Of Aaprt	Y (cm)		1.10				
	PD	t_d	(µsec)	0.56					
	PRF	prr	(Hz)	9685.2					
	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	2.35					
Other	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)						
Information	Focal	Focal Length	FL _x (cm)		1.24				
	Length	1 ocai Lengtii	FLy (cm)		1.25				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	78.55					
Operating	Mode	Mode	NA	THI-B	THI-B				
Control	Focus	Focus	(cm)	7	7				
Conditions	Power	Power	(%)	100	100				

Transducer Model: <u>C3S-E</u> Operating Mode: <u>B+C</u>

						TIS		TIB	
	Index	k Label		MI		non	-scan		TIC
	macz	Lubei		1711	Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Maxi	mum Index Va	lue		0.5	0.7				
	p _{r.3}	$p_{r,^{\scriptscriptstyle{lpha}}}$	(MPa)	0.93					
	\mathbf{W}_{o}	P	(mW)		325.62				
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	$\begin{aligned} & \text{min of} \\ & & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)						
Associated	z_1	Z_{s}	(cm)						
Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	Z_{sp}	Z_{b}	(cm)						
	Z@PII.3max	Z at max $I_{pi \alpha}$	(cm)	5.4					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	$f_{ m awf}$	(MHz)	2.76	2.84				
	Dim of A _{aprt}	Dim of A _{aprt}	X (cm)		2.88				
	Dilli Of Aaprt	Dilli Of Aaprt	Y (cm)		1.10				
	PD	t _d	(µsec)	1.16					
	PRF	prr	(Hz)	5822					
	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	1.55					
Other	d _{eq} @PII _{max}	d _{eq} at max I _{pi}	(cm)						
Information	Focal	Focal Length	FL _x (cm)		2.01				
	Length	Total Length	FLy (cm)		1.98				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	38.32					
Operating	Mode	Mode	NA	С	C				
Control	Focus	Focus	(cm)	6	6				
Conditions	Power	Power	(%)	100	100				

Transducer Model: <u>C3S-E</u> Operating Mode: <u>B+C+PW</u>

			_	jeruonig r		TIS		TIB	
	Inde	x Label		MI		non	-scan		TIC
	mucz	Label		1411	Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	ne
Global Maxi	mum Index Va	lue		0.5			1.0	0.6	
	p _{r.3}	р _{г, а}	(MPa)	0.79					
	W_{o}	P	(mW)					613.51	
	min of [W _{.3} (z ₁), I _{TA.3} (z ₁)]	$\begin{aligned} & \text{min of} \\ & & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)				275.04		
Associated	z_1	Z_{s}	(cm)				4.1		
Acoustic	z _{bp}	Z_{bp}	(cm)				3.0		
Parameter	z_{sp}	Z_b	(cm)					4.2	
	z@PII _{.3max}	Z at max $I_{pi\alpha}$	(cm)	4.4					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)					1.1	
	f_c	f_{awf}	(MHz)	2.84			2.85	2.78	
	Dim of A _{aprt}	Dim of A _{aprt}	X (cm)				2.88	2.88	
	Dilli Of A _{aprt}	Dilli Of Aaprt	Y (cm)				1.10	1.10	
	PD	t_d	(µsec)	1.26					
	PRF	prr	(Hz)	9659.3					
	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	1.35					
Other	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)					1.09	
Information	Focal	Focal Length	FL _x (cm)				1.55		
	Length	Pocar Length	FLy (cm)				1.46		
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	123.41					
Operating	Mode	Mode	NA	PW			PW	PW	
Control	Focus	Focus	(cm)	8			7	6	
Conditions	Power	Power	(%)	100			100	100	

Transducer Model: <u>C3S-E</u> Operating Mode: <u>M</u>

						TIS		TIB	
	Index	k Label		MI		non	-scan		TIC
	mucz	Label		1711	Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	TIC .
Global Maxi	mum Index Va	lue		1.0			1.0	0.2	
	p _{r.3}	р _{г, а}	(MPa)	1.58					
	W _o	P	(mW)					403.51	
	min of [W _{.3} (z ₁), I _{TA.3} (z ₁)]	$\begin{aligned} & \text{min of} \\ & & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)				229.16		
Associated	z_1	Z_{s}	(cm)				4.1		
Acoustic	Z _{bp}	Z_{bp}	(cm)				3.0		
Parameter	z_{sp}	Z_b	(cm)					5.1	
	z@PII _{.3max}	Z at max $I_{pi \alpha}$	(cm)	5.6					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)					0.85	
	f_c	$f_{ m awf}$	(MHz)	2.71			2.66	2.73	
	Dim of A _{aprt}	Dim of A _{aprt}	X (cm)				2.88	2.88	
	Dilli Of A _{aprt}	Dilli Of A _{aprt}	Y (cm)				1.10	1.10	
	PD	t_d	(µsec)	0.54					
	PRF	prr	(Hz)	4652.8					
	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	2.54					
Other	d _{eq} @PII _{max}	d _{eq} at max I _{pi}	(cm)					0.84	
Information	Focal	Focal Length	FL _x (cm)				1.16		
	Length	Tocal Length	FLy (cm)				1.24		
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	112.09					
Operating	Mode	Mode	NA	M			M	M	
Control	Focus	Focus	(cm)	7			4	5	
Conditions	Power	Power	(%)	100			100	100	

Transducer Model: <u>C3S-D</u> Operating Mode: <u>B</u>

				Peruong		TIS		TIB	
	Indev	Label		MI		non-	scan		TIC
	muca	Laber		WII	Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Maxir	num Index Va	llue		0.8	1.0				
	$p_{r.3}$	р _{г, а}	(MPa)	1.29					
	W_{o}	P	(mW)		508.22				
	min of	min of							
	$[W_{.3}(z_1),$	$[P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)$	(mW)						
	$I_{TA.3}(z_1)$]							
Associated	\mathbf{z}_1	Z_{s}	(cm)						
Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	Z_{sp}	Z_b	(cm)						
	Z@PII.3max	Z at max $I_{pi\alpha}$	(cm)	6.6					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	f_{awf}	(MHz)	2.60	2.72				
	Dim of	Dim of A	X (cm)		2.88				
	A _{aprt}	Dim of A _{aprt}	Y (cm)		1.10				
	PD	$t_{\rm d}$	(µsec)	0.56					
	PRF	prr	(Hz)	9685.2					
	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	2.35					
Other	d _{eq} @PII _{max}	d _{eq} at max I _{pi}	(cm)						
Information	Focal		FL _x (cm)		1.26				
	Length	Focal Length	FLy (cm)		1.28				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	78.65					
Operating	Mode	Mode	NA	В	В				
Control	Focus	Focus	(cm)	7	7				
Conditions	Power	Power	(%)	100	100				

Transducer Model: <u>C3S-D</u> Operating Mode: <u>THI-B</u>

						TIS		TIB	
	Index	k Label		MI		non	-scan		TIC
	macz	Lubei		1411	Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Maxi	mum Index Va	lue		0.8	0.9				
	p _{r.3}	$p_{r,^{\scriptscriptstyle{lpha}}}$	(MPa)	1.22					
	\mathbf{W}_{o}	P	(mW)		508.22				
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	$\begin{aligned} & \text{min of} \\ & & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)						
Associated	z_1	Z_{s}	(cm)						
Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	Z _{sp}	Z_b	(cm)						
	z@PII _{.3max}	Z at max $I_{pi\alpha}$	(cm)	6.6					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	$f_{ m awf}$	(MHz)	2.62	2.72				
	Dim of A _{aprt}	Dim of A _{aprt}	X (cm)		2.88				
	Dilli Of Aaprt	Dilli Of Aaprt	Y (cm)		1.10				
	PD	t _d	(µsec)	0.56					
	PRF	prr	(Hz)	9685.2					
	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	2.35					
Other	d _{eq} @PII _{max}	d _{eq} at max I _{pi}	(cm)						
Information	Focal	Focal Length	FL _x (cm)		1.24				
	Length	Total Length	FLy (cm)		1.25				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	78.55					
Operating	Mode	Mode	NA	THI-B	THI-B				
Control	Focus	Focus	(cm)	7	7				
Conditions	Power	Power	(%)	100	100				

Transducer Model: <u>C3S-D</u> Operating Mode: <u>B+C</u>

					10000	TIS		TIB	
	Index	k Label		MI		non	-scan		TIC
	muez	Labei		1711	Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Maxi	mum Index Va	lue		0.5	0.7				
	p _{r.3}	$p_{r,^{\alpha}}$	(MPa)	0.93					
	W_{o}	P	(mW)		325.62				
	min of [W _{.3} (z ₁), I _{TA.3} (z ₁)]	$\begin{aligned} & \text{min of} \\ & & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)						
Associated	z_1	Z_{s}	(cm)						
Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	z_{sp}	Z_{b}	(cm)						
	z@PII _{.3max}	Z at max $I_{pi \alpha}$	(cm)	5.4					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	f_{awf}	(MHz)	2.76	2.84				
	Dim of A _{aprt}	Dim of A _{aprt}	X (cm)		2.88				
	Dilli Of A _{aprt}	Dilli Of A _{aprt}	Y (cm)		1.10				
	PD	t _d	(µsec)	1.16					
	PRF	prr	(Hz)	5822					
	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	1.55					
Other	d _{eq} @PII _{max}	d _{eq} at max I _{pi}	(cm)						
Information	Focal	Focal Length	FL _x (cm)		2.01				
	Length	1 ocai Lengtii	FLy (cm)		1.98				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	38.32					
Operating	Mode	Mode	NA	С	C				
Control	Focus	Focus	(cm)	6	6				
Conditions	Power	Power	(%)	100	100				

Transducer Model: <u>C3S-D</u> Operating Mode: <u>B+C+PW</u>

		<u>сзз-Б</u>	•		vioue. <u> D+C</u>	TIS		TIB	
	Index	x Label		MI		non	-scan		TIC
	mucz	Label		1711	Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	ne
Global Maxi	mum Index Va	lue		0.5			1.0	0.6	
	p _{r.3}	р _{г, а}	(MPa)	0.79					
	\mathbf{W}_{o}	P	(mW)					613.51	
	min of [W _{.3} (z ₁), I _{TA.3} (z ₁)]	$\begin{aligned} & \text{min of} \\ & & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)				275.04		
Associated	z_1	Z_{s}	(cm)				4.1		
Acoustic	Z _{bp}	Z_{bp}	(cm)				3.0		
Parameter	z_{sp}	Z_b	(cm)					4.2	
	z@PII _{.3max}	Z at max $I_{pi\alpha}$	(cm)	4.4					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)					1.1	
	f_c	f_{awf}	(MHz)	2.84			2.85	2.78	
	Dim of A _{aprt}	Dim of A _{aprt}	X (cm)				2.88	2.88	
	Dilli Of A _{aprt}	Dilli Of Aaprt	Y (cm)				1.10	1.10	
	PD	t_d	(µsec)	1.26					
	PRF	prr	(Hz)	9659.3					
	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	1.35					
Other	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)					1.09	
Information	Focal	Focal Length	FL _x (cm)				1.55		
	Length	1 ocai Lengtii	FLy (cm)				1.46		
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	123.41					
Operating	Mode	Mode	NA	PW			PW	PW	
Control	Focus	Focus	(cm)	8			7	6	
Conditions	Power	Power	(%)	100			100	100	

Transducer Model: <u>C3S-D</u> Operating Mode: <u>M</u>

				8		TIS		TIB	
	Index	k Label		MI		non	-scan		TIC
	mucz	Label		1711	Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	TIC .
Global Maxi	mum Index Va	lue		1.0			1.0	0.2	
	p _{r.3}	р _{г, а}	(MPa)	1.58					
	W _o	P	(mW)					403.51	
	min of [W _{.3} (z ₁), I _{TA.3} (z ₁)]	$\begin{aligned} & \text{min of} \\ & & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)				229.16		
Associated	z_1	Z_{s}	(cm)				4.1		
Acoustic	Z _{bp}	Z_{bp}	(cm)				3.0		
Parameter	z_{sp}	Z_b	(cm)					5.1	
	z@PII _{.3max}	Z at max $I_{pi \alpha}$	(cm)	5.6					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)					0.85	
	f_c	$f_{ m awf}$	(MHz)	2.71			2.66	2.73	
	Dim of A _{aprt}	Dim of A _{aprt}	X (cm)				2.88	2.88	
	Dilli Of A _{aprt}	Dilli Of A _{aprt}	Y (cm)				1.10	1.10	
	PD	t_d	(µsec)	0.54					
	PRF	prr	(Hz)	4652.8					
	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	2.54					
Other	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)					0.84	
Information	Focal	Focal Length	FL _x (cm)				1.16		
	Length	Tocal Length	FLy (cm)				1.24		
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	112.09					
Operating	Mode	Mode	NA	M			M	M	
Control	Focus	Focus	(cm)	7			4	5	
Conditions	Power	Power	(%)	100			100	100	

Transducer Model: <u>C3S-ES</u> Operating Mode: <u>B</u>

				региен		TIS		TIB	
	Indev	Label		MI		non-	scan		TIC
	muca	Laber		WII	Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	TIC
Global Maxir	num Index Va	lue		0.8	1.0				
	$p_{r.3}$	$p_{r,^{lpha}}$	(MPa)	1.29					
	W_{o}	P	(mW)		508.22				
	min of	min of							
	$[W_{.3}(z_1),$	$[P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)$	(mW)						
	$I_{TA.3}(z_1)$]							
Associated	z_1	Z_{s}	(cm)						
Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	Z_{sp}	Z_b	(cm)						
	Z@PII.3max	Z at max $I_{pi \alpha}$	(cm)	6.6					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	f_{awf}	(MHz)	2.60	2.72				
	Dim of	Dim of A _{aprt}	X (cm)		2.88				
	A _{aprt}	Dilli Of A _{aprt}	Y (cm)		1.10				
	PD	t _d	(µsec)	0.56					
	PRF	prr	(Hz)	9685.2					
	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	2.35					
Other	d _{eq} @PII _{max}	d _{eq} at max I _{pi}	(cm)						
Information	Focal	Focal Length	FL _x (cm)		1.26				
	Length	rocai Length	FLy (cm)		1.28				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	78.65					
Operating	Mode	Mode	NA	В	В				
Control	Focus	Focus	(cm)	7	7				
Conditions	Power	Power	(%)	100	100				

Transducer Model: <u>C3S-ES</u> Operating Mode: <u>THI-B</u>

		C35-E5			110de. 11	TIS		TIB	
	Index	x Label		MI		non	-scan		TIC
	muez	Labei		1411	Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	TIC
Global Maxi	mum Index Va	lue		0.8	0.9				
	$p_{r.3}$	$p_{r,^{\scriptscriptstyle{lpha}}}$	(MPa)	1.22					
	\mathbf{W}_{o}	P	(mW)		508.22				
	min of [W _{.3} (z ₁), I _{TA.3} (z ₁)]	$\begin{aligned} & \text{min of} \\ & & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)						
Associated	z_1	$Z_{\rm s}$	(cm)						
Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	z_{sp}	Z_b	(cm)						
	z@PII _{.3max}	Z at max $I_{pi\alpha}$	(cm)	6.6					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	f_{awf}	(MHz)	2.62	2.72				
	Dim of A _{aprt}	Dim of A _{aprt}	X (cm)		2.88				
	Dilli Of A _{aprt}	Dilli Of Aaprt	Y (cm)		1.10				
	PD	t_d	(µsec)	0.56					
	PRF	prr	(Hz)	9685.2					
	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	2.35					
Other	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)						
Information	Focal	Focal Length	FL _x (cm)		1.24				
	Length	1 ocai Lengtii	FLy (cm)		1.25				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	78.55					
Operating	Mode	Mode	NA	THI-B	THI-B				
Control	Focus	Focus	(cm)	7	7				
Conditions	Power	Power	(%)	100	100				

Transducer Model: <u>C3S-ES</u> Operating Mode: <u>B+C</u>

					1,1000.	TIS		TIB	
	Inde	x Label		MI		non	-scan		TIC
	mucz	Label		1411	Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	TIC .
Global Maxi	mum Index Va	lue		0.5	0.7				
	$p_{r.3}$	$p_{r,^{lpha}}$	(MPa)	0.93					
	W_{o}	P	(mW)		325.62				
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	$\begin{aligned} & \text{min of} \\ & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)						
Associated	z_1	Z_{s}	(cm)						
Acoustic	z _{bp}	Z_{bp}	(cm)						
Parameter	z_{sp}	Z_b	(cm)						
	z@PII _{.3max}	Z at max $I_{pi\alpha}$	(cm)	5.4					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	f_{awf}	(MHz)	2.76	2.84				
	Dim of A _{aprt}	Dim of A _{aprt}	X (cm)		2.88				
	Dilli Of A _{aprt}	Dilli Of A _{aprt}	Y (cm)		1.10				
	PD	t_d	(µsec)	1.16					
	PRF	prr	(Hz)	5822					
	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	1.55					
Other	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)						
Information	Focal	Focal Length	FL _x (cm)		2.01				
	Length	1 ocai Ecngin	FLy (cm)		1.98				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	38.32					
Operating	Mode	Mode	NA	С	C				
Control	Focus	Focus	(cm)	6	6				
Conditions	Power	Power	(%)	100	100				

Transducer Model: <u>C3S-ES</u> Operating Mode: <u>B+C+PW</u>

					1,1000.	TIS		TIB	
	Index	x Label		MI		non	-scan		TIC
	mucz	Label		1711	Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	TIC .
Global Maxi	mum Index Va	lue		0.5			1.0	0.6	
	p _{r.3}	р _{г, а}	(MPa)	0.79					
	W_{o}	P	(mW)					613.51	
	min of [W _{.3} (z ₁), I _{TA.3} (z ₁)]	$\begin{aligned} & \text{min of} \\ & & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)				275.04		
Associated	z_1	Z_{s}	(cm)				4.1		
Acoustic	Z _{bp}	Z_{bp}	(cm)				3.0		
Parameter	z_{sp}	Z_b	(cm)					4.2	
	z@PII _{.3max}	Z at max $I_{pi\alpha}$	(cm)	4.4					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)					1.1	
	f_c	$f_{ m awf}$	(MHz)	2.84			2.85	2.78	
	Dim of A _{aprt}	Dim of A _{aprt}	X (cm)				2.88	2.88	
	Dilli Of A _{aprt}	Dilli Of A _{aprt}	Y (cm)				1.10	1.10	
	PD	t_d	(µsec)	1.26					
	PRF	prr	(Hz)	9659.3					
	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	1.35					
Other	$d_{eq}@PII_{max}$	d_{eq} at max I_{pi}	(cm)					1.09	
Information	Focal	Focal Length	FL _x (cm)				1.55		
	Length	rocar Length	FLy (cm)				1.46		
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	123.41					
Operating	Mode	Mode	NA	PW			PW	PW	
Control	Focus	Focus	(cm)	8			7	6	
Conditions	Power	Power	(%)	100			100	100	

Transducer Model: <u>C3S-ES</u> Operating Mode: <u>M</u>

					1710000 171	TIS		TIB	
	Index	x Label		MI		non	-scan		TIC
	mucz	Label		1411	Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Maxi	mum Index Va	lue		1.0			1.0	0.2	
	p _{r.3}	р _{г, а}	(MPa)	1.58					
	W_{o}	P	(mW)					403.51	
	min of [W _{.3} (z ₁), I _{TA.3} (z ₁)]	$\begin{aligned} & \text{min of} \\ & & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)				229.16		
Associated	z_1	Z_{s}	(cm)				4.1		
Acoustic	Z _{bp}	Z_{bp}	(cm)				3.0		
Parameter	Z_{sp}	Z_b	(cm)					5.1	
	z@PII _{.3max}	Z at max $I_{pi \alpha}$	(cm)	5.6					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)					0.85	
	f_c	$f_{ m awf}$	(MHz)	2.71			2.66	2.73	
	Dim of A _{aprt}	Dim of A _{aprt}	X (cm)				2.88	2.88	
	Dilli Of A _{aprt}	Dilli Of A _{aprt}	Y (cm)				1.10	1.10	
	PD	t_d	(µsec)	0.54					
	PRF	prr	(Hz)	4652.8					
	$p_r@PII_{max}$	p_r at max I_{pi}	(MPa)	2.54					
Other	$d_{eq}@PII_{max}\\$	d_{eq} at max I_{pi}	(cm)					0.84	
Information	Focal	Focal Length	FL _x (cm)				1.16		
	Length	Pocar Length	FLy (cm)				1.24		
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	112.09					
Operating	Mode	Mode	NA	M			M	M	
Control	Focus	Focus	(cm)	7			4	5	
Conditions	Power	Power	(%)	100			100	100	

Transducer Model: <u>L7-E</u> Operating Mode: <u>B</u>

			-	Turing 1/100		TIS		TIB	
	Index	Label		MI	C	non-	scan		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Max	imum Index Valu	ıe		0.9	0.5				
	$p_{r.3}$	$p_{r,\alpha}$	(MPa)	2.41					
	\mathbf{W}_{o}	P	(mW)		73.73				
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	$\begin{aligned} & \text{min of} \\ & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)						
Associated	\mathbf{z}_1	Z_{s}	(cm)						
Acoustic	z_{bp}	Z_{bp}	(cm)						
Parameter	z_{sp}	Z_b	(cm)						
	z@PII _{.3max}	Z at max $I_{pi \alpha}$	(cm)	2.2					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	\mathbf{f}_{c}	f_{awf}	(MHz)	6.23	6.25				
	Dim of A	Dim of A	X (cm)		2.05				
	Dim of A _{aprt}	Dim of A _{aprt}	Y (cm)		0.45				
	PD	$t_{\rm d}$	(µsec)	0.23					
	PRF	prr	(Hz)	2872					
0.1	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	3.37					
Other Information	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)						
Illiorniation	F 1 I	Escal I conth	FL _x (cm)		0.26				
	Focal Length	Focal Length	FLy (cm)		0.36				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	43.96					
Operating	Mode	Mode	NA	В	В				
Control	Focus	Focus	(cm)	2	2				
Conditions	Power	Power	(%)	100	100				

Transducer Model: <u>L7-E</u> Operating Mode: <u>THI-B</u>

				9		TIS		TIB	
	Index	Label		MI	Scan	non-	scan	mon goon	TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Max	imum Index Valu	ue		1.0	0.4				
	$p_{r.3}$	$p_{r,lpha}$	(MPa)	2.32					
	W_{o}	P	(mW)		73.73				
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	$\begin{aligned} & \text{min of} \\ & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)						
Associated	z_1	Z_{s}	(cm)						
Acoustic	z_{bp}	$Z_{ m bp}$	(cm)						
Parameter	Z_{sp}	Z_b	(cm)						
	Z@PII.3max	Z at max $I_{pi \alpha}$	(cm)	2.1					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	$f_{ m awf}$	(MHz)	6.21	6.22				
	Dim of A	Dim of A	X (cm)		2.05				
	Dim of A _{aprt}	Dim of A _{aprt}	Y (cm)		0.45				
	PD	$t_{\rm d}$	(µsec)	0.23					
	PRF	prr	(Hz)	2874					
Odhaa	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	3.37					
Other Information	d _{eq} @PII _{max}	d _{eq} at max I _{pi}	(cm)						
Information	Focal Langth	Eggel Langth	FL _x (cm)		0.26				
	Focal Length	Focal Length	FLy (cm)		0.34				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	43.89					
Operating	Mode	Mode	NA	THI-B	THI-B				
Control	Focus	Focus	(cm)	2	2				
Conditions	Power	Power	(%)	100	100				

Transducer Model: <u>L7-E</u> Operating Mode: <u>B+C</u>

				8		TIS		TIB	
	Index	Label		MI	C	non-	scan		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Maxi	mum Index Valu	ue		0.6	0.7				
	p _{r.3}	$p_{r,\alpha}$	(MPa)	1.38					
	Wo	P	(mW)		106.50				
	min of [W _{.3} (z ₁), I _{TA.3} (z ₁)]	$\begin{aligned} & \text{min of} \\ & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)						
Associated	z_1	Z_{s}	(cm)						
Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	Z_{sp}	Z_b	(cm)						
	Z@PII _{.3max}	Z at max $I_{pi \alpha}$	(cm)	1.7					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	$f_{ m awf}$	(MHz)	6.36	6.35				
	Dim of A	Dim of A	X (cm)		2.05				
	Dim of A _{aprt}	Dim of A _{aprt}	Y (cm)		0.45				
	PD	$t_{\rm d}$	(µsec)	0.77					
	PRF	prr	(Hz)	6944					
0.1	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	1.92					
Other Information	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)						
Illiorillation	Escal Londo	Escal Land	FL _x (cm)		0.23				
	Focal Length	Focal Length	FLy (cm)		0.35				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	91.42					
Operating	Mode	Mode	NA	С	С				
Control	Focus	Focus	(cm)	2.5	1				
Conditions	Power	Power	(%)	100	100				

Transducer Model: <u>L7-E</u> Operating Mode: <u>B+C+PW</u>

				8		TIS		TIB	
	Index	Label		MI	G	non-	scan		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Maxi	mum Index Valu	ıe		0.6		1.6		1.4	
	p _{r.3}	$p_{r,\alpha}$	(MPa)	1.59					
	Wo	P	(mW)			221.18		73.73	
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	$\begin{aligned} & \text{min of} \\ & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)						
Associated	z_1	Z_{s}	(cm)						
Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	Z_{sp}	Z_b	(cm)					1.9	
	z@PII _{.3max}	Z at max $I_{pi\alpha}$	(cm)	1.7					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)					0.42	
	f_c	f_{awf}	(MHz)	6.34		6.22		6.31	
	Dim of A	Dim of A	X (cm)			2.05		2.05	
	Dim of A _{aprt}	Dim of A _{aprt}	Y (cm)			0.45		0.45	
	PD	$t_{\rm d}$	(µsec)	0.58					
	PRF	prr	(Hz)	2873					
Other	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	2.14					
Other Information	$d_{eq}@PII_{max}$	d_{eq} at max I_{pi}	(cm)					0.44	
Information	Essal I small	Escal Land	FL _x (cm)			0.24			
	Focal Length	Focal Length	FLy (cm)			0.33			
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	118.84					
Operating	Mode	Mode	NA	PW		PW		PW	
Control	Focus	Focus	(cm)	4		2.5		2.5	
Conditions	Power	Power	(%)	100		100		100	

Transducer Model: <u>L7-E</u> Operating Mode: <u>M</u>

			_	The state of the s		TIS		TIB	
	Index	Label		MI	G	non-	scan		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Maxi	mum Index Valu	ıe		0.7		1.2		1.6	
	p _{r.3}	$p_{r,\alpha}$	(MPa)	1.89					
	Wo	P	(mW)			139.30		139.30	
	min of [W _{.3} (z ₁), I _{TA.3} (z ₁)]	$\begin{aligned} & \text{min of} \\ & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)						
Associated	z_1	$Z_{\rm s}$	(cm)						
Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	Z_{sp}	Z_b	(cm)					1.8	
	Z@PII.3max	Z at max $I_{pi \alpha}$	(cm)	1.6					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)					0.89	
	f_{c}	$f_{ m awf}$	(MHz)	6.19		6.22		6.19	
	Dim of A	Dim of A	X (cm)			2.05		2.05	
	Dim of A _{aprt}	Dim of A _{aprt}	Y (cm)			0.45		0.45	
	PD	$t_{\rm d}$	(µsec)	0.22					
	PRF	prr	(Hz)	2866					
0.1	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	2.60					
Other Information	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)					0.87	
Illiorniauon		Escal Land	FL _x (cm)			0.22			
	Focal Length	Focal Length	FLy (cm)			0.36			
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	158.26					
Operating	Mode	Mode	NA	M		M		M	
Control	Focus	Focus	(cm)	2		1.5		2	
Conditions	Power	Power	(%)	100		100	_	100	

Transducer Model: <u>L7W-E</u> Operating Mode: <u>B</u>

		DOGEN <u>ET VV E</u>		-	<u>g 1,10000.</u>	TIS		TIB	
	Inde	ex Label		MI	C.	non-	scan		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Maxi	i mum Index V	Value		0.6	0.5				
	$p_{r.3}$	$p_{\mathrm{r},\alpha}$	(MPa)	1.34					
	\mathbf{W}_{o}	P	(mW)		98.3				
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	min of $[P\alpha(Zs),Ita,\alpha(Zs)]$	(mW)						
Associated	z_1	Z_{s}	(cm)						
Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	$\begin{array}{ccc} z_{sp} & Z_b \\ \\ z@PII_{.3max} & Z \ at \ max \ I_{pi \ \alpha} \end{array}$		(cm)						
	Z@PII.3max	Z at max $I_{pi \alpha}$	(cm)	2.7					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	$f_{ m awf}$	(MHz)	5.99	6.09				
	Dim of	Dim of A _{aprt}	X (cm)		3.07				
	A _{aprt}	Dim Of Taprt	Y (cm)		0.65				
	PD	t _d	(µsec)	0.39					
	PRF	prr	(Hz)	6408					
	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	2.1					
	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)						
Other			FL_x		0.13				
Information	Focal	Focal Length	(cm)		0.13				
	Length	1 our zongur	FLy		0.24				
			(cm)						
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	66.88					
Operating	Mode	Mode	NA	В	В				
Control	Focus	Focus	(cm)	3	2.5				
Conditions	Power	Power	(%)	100	100				

Transducer Model: <u>L7W-E</u> Operating Mode: <u>THI-B</u>

		Division Division		-	<u>g 1/10uc</u>	TIS		TIB	
	Inde	ex Label		MI	q	non-	scan		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Maxi	imum Index V	Value		0.5	0.4				
	p _{r.3}	$p_{r,\alpha}$	(MPa)	1.32					
	W_{o}	P	(mW)		98.3				
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	$\begin{array}{c} \text{min of} \\ [P\alpha(Zs),Ita,\alpha(Zs)] \end{array}$	(mW)						
Associated	z_1	Z_{s}	(cm)						
Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	Z_{sp}	Z_{b}	(cm)						
	z@PII _{.3max}	Z at max $I_{pi \alpha}$	(cm)	2.7					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	f_{awf}	(MHz)	5.95	6.11				
	Dim of	Dim of A _{aprt}	X (cm)		3.07				
	A _{aprt}	Dim Of Aaprt	Y (cm)		0.65				
	PD	$t_{\rm d}$	(µsec)	0.39					
	PRF	prr	(Hz)	6414					
	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	2.1					
	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)						
Other Information	Focal	Focal Length	FL _x (cm)		0.13				
	Length	1 ocal Length	FLy (cm)		0.23				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	66.91					
Operating	Mode	Mode	NA	THI-B	THI-B				
Control	Focus	Focus	(cm)	3	2.5				
Conditions	Power	Power	(%)	100	100				

Transducer Model: <u>L7W-E</u> Operating Mode: <u>B+C</u>

		iouei. <u>L777-E</u>		•	ig 1410uc1	TIS		TIB	
	Inde	ex Label		MI	a	non-	scan		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Max	imum Index V	/alue		0.4	1.3				
	$p_{r.3}$	$p_{r,\alpha}$	(MPa)	1					
	\mathbf{W}_{o}	P	(mW)		307.2				
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	min of $[P\alpha(Zs),Ita,\alpha(Zs)]$	(mW)						
Associated	z_1	Z_{s}	(cm)						
Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	Z_{sp}	Z_b	(cm)						
	z@PII _{.3max}	Z at max $I_{pi \alpha}$	(cm)	3					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	f_{awf}	(MHz)	5.39	5.41				
	Dim of	Dim of A _{aprt}	X (cm)		3.07				
	A_{aprt}	Diffi of Trapri	Y (cm)		0.65				
	PD	$t_{ m d}$	(µsec)	0.88					
	PRF	prr	(Hz)	8988					
	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	1.59					
	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)						
Other Information	Focal	Focal Length	FL _x (cm)		0.26				
	Length	Pocar Length	FLy (cm)		0.29				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	46.59					
Operating	Mode	Mode	NA	С	С				
Control	Focus	Focus	(cm)	3	2				
Conditions	Power	Power	(%)	100	100				

Transducer Model: <u>L7W-E</u> Operating Mode: <u>B+C+PW</u>

		DIVINE		•	_	TIS		TIB	
	Inde	ex Label		MI	G	non-	scan		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Max	imum Index V	Value		0.5			1.2	0.7	
	$p_{r.3}$	$p_{r,\alpha}$	(MPa)	1.1					
	Wo	P	(mW)					208.9	
	min of [W _{.3} (z ₁), I _{TA.3} (z ₁)]	$\begin{array}{c} \text{min of} \\ [P\alpha(Zs),Ita,\alpha(Zs)] \end{array}$	(mW)				85.11		
Associated	z_1	Z_{s}	(cm)				2.4		
Acoustic	Z _{bp}	Z_{bp}	(cm)				2.4		
Parameter	z_{sp}	Z_b	(cm)					2.4	
	z@PII _{.3max}	Z at max $I_{\text{pi}\alpha}$	(cm)	3.2					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)					1.19	
	f_c	$f_{ m awf}$	(MHz)	5.42			5.42	5.41	
	Dim of		X (cm)				3.07	3.07	
	A _{aprt}	Dilli Of A _{aprt}	Y (cm)				0.65	0.65	
	PD	$t_{\rm d}$	(µsec)	0.7					
	PRF	prr	(Hz)	6411					
	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	1.65					
	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)					1.19	
Other Information	Focal	Focal Length	FL _x (cm)				0.25		
	Length	Pocar Length	FLy (cm)				0.16		
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	163.49					
Operating	Mode	Mode	NA	PW			PW	PW	
Control	Focus	Focus	(cm)	2.5			3.5	2.5	
Conditions	Power	Power	(%)	100			100	100	

Transducer Model: <u>L7W-E</u> Operating Mode: <u>M</u>

				a wording 117		TIS		TIB	
	Inde	ex Label		MI	G	non-	scan		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Max	imum Index Val	lue		0.5			1.8	2.1	
	p _{r.3}	$p_{\mathrm{r},lpha}$	(MPa)	1.24					
	\mathbf{W}_{o}	P	(mW)					172.00	
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	min of $[P\alpha(Zs),Ita,\alpha(Zs)]$	(mW)				63.39		
Associated	z_1	Z_{s}	(cm)				2.4		
Acoustic	Z _{bp}	Z_{bp}	(cm)				2.3		
Parameter	Z_{sp}	Z_b	(cm)					2.4	
	Z@PII.3max	Z at max $I_{pi \alpha}$	(cm)	2.7					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)					0.96	
	f_c	$\mathbf{f}_{\mathrm{awf}}$	(MHz)	6.02			6.04	6.08	
	Dim of A	Dim of A _{aprt}	X (cm)				3.07	3.07	
	Dim of A _{aprt}	Dilli Of A _{aprt}	Y (cm)				0.65	0.65	
	PD	t_d	(µsec)	0.39					
	PRF	prr	(Hz)	7042					
Other	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	1.89					
Informatio	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)					0.96	
n	F 1 I 1	Essell south	FL _x (cm)				0.23		
	Focal Length	Focal Length	FLy (cm)				0.26		
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	157.33					
Operating	Mode	Mode	NA	M			M	M	
Control	Focus	Focus	(cm)	3			3	2	
Conditions	Power	Power	(%)	100			100	100	

Transducer Model: <u>iL7-E</u> Operating Mode: <u>B</u>

	insuucei wio		-	ating with		TIS		TIB	
	Inde	x Label		MI	Caan	non-	scan		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Max	imum Index Val	ue		0.8	0.5				
	p _{r.3}	$p_{r,\alpha}$	(MPa)	2.08					
	W_{o}	P	(mW)		73.73				
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	min of $[P\alpha(Zs),Ita,\alpha(Zs)]$	(mW)						
Associated	z_1	Z_{s}	(cm)						
Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	Z_{sp}	Z_b	(cm)						
	z@PII _{.3max}	Z at max $I_{pi\alpha}$	(cm)	2.4					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	f_{awf}	(MHz)	6.14	6.12				
	Dim of A _{aprt}	Dim of A _{aprt}	X (cm)		2.05				
	Dilli Of Aaprt	Diffi of A _{aprt}	Y (cm)		0.65				
	PD	t _d	(µsec)	0.22					
	PRF	prr	(Hz)	2975					
	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	3.08					
Other	d _{eq} @PII _{max}	d _{eq} at max I _{pi}	(cm)						
Information	Es sal Laureth	Essal I su seb	FL _x (cm)		0.24				
	Focal Length	Focal Length	FLy (cm)		0.32				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	78.21					
Operating	Mode	Mode	NA	В	В				
Control	Focus	Focus	(cm)	3	2				
Conditions	Power	Power	(%)	100	100				

Transducer Model: <u>iL7-E</u> Operating Mode: <u>THI-B</u>

	insuucei wio			8	Jue. <u>1111-1</u>	TIS		TIB	
	Inde	x Label		MI	G	non-	-scan		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Max	imum Index Val	ue		0.7	0.5				
	$p_{r.3}$	$p_{r,\alpha}$	(MPa)	2.02					
	W_{o}	P	(mW)		73.73				
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	min of $[P\alpha(Zs),Ita,\alpha(Zs)]$	(mW)						
Associated	\mathbf{z}_1	Z_{s}	(cm)						
Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	Z_{sp}	Z_b	(cm)						
	z@PII _{.3max}	Z at max $I_{pi\alpha}$	(cm)	2.0					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	f_{awf}	(MHz)	6.11	6.11				
	Dim of A _{aprt}	Dim of A _{aprt}	X (cm)		2.05				
	Dilli Of Aaprt	Diffi of A _{aprt}	Y (cm)		0.65				
	PD	t _d	(µsec)	0.22					
	PRF	prr	(Hz)	2978					
	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	3.08					
Other	d _{eq} @PII _{max}	d _{eq} at max I _{pi}	(cm)						
Information	Focal Length	Focal Length	FL _x (cm)		0.28				
	rocai Lengui	rocai Length	FLy (cm)		0.32				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	78.20					
Operating	Mode	Mode	NA	THI-B	THI-B				
Control	Focus	Focus	(cm)	3	2				
Conditions	Power	Power	(%)	100	100				

Transducer Model: <u>iL7-E</u> Operating Mode: <u>B+C</u>

			_			TIS		TIB	
	Inde	ex Label		MI	C	non-	scan		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Max	imum Index Va	lue		0.5	0.7				
	p _{r.3}	$p_{r,\alpha}$	(MPa)	1.34					
	W_{o}	P	(mW)		105.66				
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	min of $[P\alpha(Zs),Ita,\alpha(Zs)]$	(mW)						
Associated	z_1	$Z_{\rm s}$	(cm)						
Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	Z_{sp}	Z_b	(cm)						
	Z@PII.3max	Z at max $I_{pi \alpha}$	(cm)	1.8					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	$ m f_{awf}$	(MHz)	6.34	6.35				
	Dim of A	Dim of A	X (cm)		2.05				
	Dim of A _{aprt}	Dim of A _{aprt}	Y (cm)		0.65				
	PD	$t_{\rm d}$	(µsec)	0.77					
	PRF	prr	(Hz)	7025.1					
Other	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	2.03					
Informatio	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)						
n	Focal	Essal Lanath	FL _x (cm)		0.23				
	Length	Focal Length	FLy (cm)		0.36				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	73.45					
Operating	Mode	Mode	NA	С	С				
Control	Focus	Focus	(cm)	3	2				
Conditions	Power	Power	(%)	100	100				

Transducer Model: <u>iL7-E</u> Operating Mode: <u>B+C+PW</u>

	iisducci iviod		<u>-</u>	Tating Wie		TIS		TIB	
	Inde	x Label		MI	Coon	non-	scan	man saan	TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Max	imum Index Va	lue		0.6		1.2		1.7	
	p _{r.3}	$p_{r,\alpha}$	(MPa)	1.58					
	W_{o}	P	(mW)			73.73		73.73	
	min of	min of							
	$[W_{.3}(z_1),$	[Pα(Zs),Ita,α(Zs	(mW)						
	$I_{TA.3}(z_1)$)]							
Associated	z_1	Z_{s}	(cm)						
Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	Z_{sp}	Z_b	(cm)					1.94	
	Z@PII.3max	Z at max $I_{pi \alpha}$	(cm)	1.8					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)					0.84	
	f_c	$ m f_{awf}$	(MHz)	6.31		6.35		6.36	
	Dim of A	Dim of A	X (cm)			2.05		2.05	
	Dim of A _{aprt}	Dim of A _{aprt}	Y (cm)			0.65		0.65	
	PD	$t_{\rm d}$	(µsec)	0.59					
	PRF	prr	(Hz)	2895					
Other	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	2.27					
Informatio	d _{eq} @PII _{max}	d _{eq} at max I _{pi}	(cm)					0.45	
n	Focal	E 11 d	FL _x (cm)			0.32			
	Length	Focal Length	FLy (cm)			0.29			
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	134.21					
Operating	Mode	Mode	NA	PW		PW		PW	
Control	Focus	Focus	(cm)	3		2		3.5	
Conditions	Power	Power	(%)	100		100		100	

Transducer Model: <u>iL7-E</u> Operating Mode: <u>M</u>

			-			TIS		TIB	
	Inde	x Label		MI	Cana	non-	scan		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Max	imum Index Val	ue		0.7		1.2		1.5	
	$p_{r.3}$	$p_{r,\alpha}$	(MPa)	1.82					
	W_{o}	P	(mW)			139.60		138.55	
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	min of $[P\alpha(Zs),Ita,\alpha(Zs)]$	(mW)						
Associated	z_1	Z_{s}	(cm)						
Acoustic	Z_{bp}	Z_{bp}	(cm)						
Parameter	Z_{sp}	Z_{b}	(cm)					2.0	
	z@PII _{.3max}	Z at max $I_{pi\alpha}$	(cm)	2.0					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)					0.88	
	f_c	f_{awf}	(MHz)	6.11		6.18		6.07	
	Dim of A _{aprt}	Dim of A _{aprt}	X (cm)			2.05		2.05	
	Dilli Of Aaprt	Diffi of A _{aprt}	Y (cm)			0.65		0.65	
	PD	t _d	(µsec)	0.21					
	PRF	prr	(Hz)	2905					
	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	2.68					
Other	d _{eq} @PII _{max}	d _{eq} at max I _{pi}	(cm)					0.87	
Information	Focal Length	Focal Length	FL _x (cm)			0.21			
	1 ocal Length	r ocar Ecngui	FLy (cm)			0.25			
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	156.89					
Operating	Mode	Mode	NA	M		M		M	
Control	Focus	Focus	(cm)	2		2		2	
Conditions	Power	Power	(%)	100		100		100	

Transducer Model: <u>V6-E</u> Operating Mode: <u>B</u>

				1119 1110 111		TIS		TIB	
	Inde	ex Label		MI	G	non-	scan		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Max	imum Index Val	ue		0.7	0.4				
	p _{r.3}	$p_{r,\alpha}$	(MPa)	1.49					
	W_{o}	P	(mW)		43.78				
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	$\begin{array}{c} \text{min of} \\ [P\alpha(Zs),Ita,\alpha(Zs)] \end{array}$	(mW)						
Associated	z_1	Z_{s}	(cm)						
Acoustic	Z _{bp}	$Z_{ m bp}$	(cm)						
Parameter	Z_{sp}	Z_b	(cm)						
	Z@PII.3max	Z at max $I_{pi \alpha}$	(cm)	2.5					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	$f_{ m awf}$	(MHz)	4.94	5.14				
	Dim of A	Dim of A	X (cm)		1.21				
	Dim of A _{aprt}	Dim of A _{aprt}	Y (cm)		0.90				
	PD	$t_{\rm d}$	(µsec)	0.34					
	PRF	prr	(Hz)	7286					
Other	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	1.95					
Informatio	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)						
n	Eggel Lamath	Eggel Langth	FL_{x} (cm)		0.29				
	Focal Length	Focal Length	FLy (cm)		0.26				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	62.76					
Operating	Mode	Mode	NA	В	В				
Control	Focus	Focus	(cm)	3	2				
Conditions	Power	Power	(%)	100	100				

Transducer Model: <u>V6-E</u> Operating Mode: <u>THI-B</u>

			-	ing Wiouc.		TIS		TIB	
	Index	Label		MI	G	non-	scan		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Max	imum Index Value			0.6	0.3				
	p _{r.3}	$p_{r,\alpha}$	(MPa)	1.42					
	Wo	P	(mW)		43.78				
	$\begin{aligned} & \text{min of } [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	min of $[P\alpha(Zs),Ita,\alpha(Zs)]$	(mW)						
Associated	\mathbf{z}_1	Z_{s}	(cm)						
Acoustic	z_{bp}	Z_{bp}	(cm)						
Parameter	\mathbf{z}_{sp}	Z_b	(cm)						
	Z@PII _{.3max}	Z at max I _{pi a}	(cm)	2.5					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	$ m f_{awf}$	(MHz)	4.92	5.14				
	Dim of A _{aprt}	Dim of A _{aprt}	X (cm)		1.21				
	DIII Of A _{aprt}	Dilli Of Aaprt	Y (cm)		0.90				
	PD	t_d	(µsec)	0.33					
	PRF	prr	(Hz)	7279					
	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	1.95					
Other	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)						
Information			FL _x (cm)		0.29				
	Focal Length	Focal Length	FLy (cm)		0.26				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	62.74					
Operating	Mode	Mode	NA	THI-B	THI-B				
Control	Focus	Focus	(cm)	3	2				
Conditions	Power	Power	(%)	100	100				

Transducer Model: <u>V6-E</u> Operating Mode: <u>B+C</u>

	isducer wiod	CI. <u>VU-L</u>		ting wide		TIS		TIB	
	Inde	x Label		MI	Scan	non-	scan		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Max	imum Index Val	ue		0.4	0.7				
	p _{r.3}	$p_{r,\alpha}$	(MPa)	0.89					
	W_{o}	P	(mW)		77.82				
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	min of $[P\alpha(Zs),Ita,\alpha(Zs)]$	(mW)						
Associated	z_1	Z_{s}	(cm)						
Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	Z_{sp}	Z_{b}	(cm)						
	Z@PII.3max	Z at max $I_{pi \alpha}$	(cm)	3.4					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	$ m f_{awf}$	(MHz)	4.03	5.25				
	Dim of A _{aprt}	Dim of A _{aprt}	X (cm)		1.21				
	Dilli Of A _{aprt}	Dilli Of A _{aprt}	Y (cm)		0.90				
	PD	t_d	(µsec)	1.19					
	PRF	prr	(Hz)	5000.23					
	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	1.29					
Other	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)						
Information			FL _x (cm)		0.22				
	Focal Length	Focal Length	FLy (cm)		0.34				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	34.32					
Operating	Mode	Mode	NA	С	С				
Control	Focus	Focus	(cm)	4	2.5				
Conditions	Power	Power	(%)	100	100				

Transducer Model: V6-E Operating Mode: B+C+PW

			Эреги		<u> </u>	TIS		TIB	
	Inde	x Label		MI	G	non-	scan		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Max	imum Index Val	ue		0.5			1.1	1.8	
	p _{r.3}	$p_{r,\alpha}$	(MPa)	1.17					
	W_{o}	P	(mW)					72.88	
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	min of $[P\alpha(Zs),Ita,\alpha(Zs)]$	(mW)				38.11		
Associated	z_1	Z_{s}	(cm)				1.8		
Acoustic	Z _{bp}	Z_{bp}	(cm)				1.8		
Parameter	Z_{sp}	Z_b	(cm)					2.0	
	Z@PII.3max	Z at max I _{pi a}	(cm)	2.4					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)					0.44	
	f_c	$\mathbf{f}_{\mathrm{awf}}$	(MHz)	5.21			5.22	5.17	
	Dim of A	Dim of A	X (cm)				1.21	1.21	
	Dim of A _{aprt}	Dim of A _{aprt}	Y (cm)				0.90	0.90	
	PD	t _d	(µsec)	0.70					
	PRF	prr	(Hz)	7279					
	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	1.54					
Other	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)					0.42	
Information			FL _x (cm)				0.24		
	Focal Length	Focal Length	FLy (cm)				0.22		
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	142.89					
Operating	Mode	Mode	NA	PW			PW	PW	
Control	Focus	Focus	(cm)	3			3.5	3.5	
Conditions	Power	Power	(%)	100			100	100	

Transducer Model: <u>V6-E</u> Operating Mode: <u>M</u>

		C1. <u> </u>	-	ing wode		TIS		TIB	
	Inde	x Label		MI	G	non-	scan		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Maxi	i mum Index Val	ue		0.7			0.4	1.1	
	p _{r.3}	$p_{r,\alpha}$	(MPa)	1.77					
	Wo	P	(mW)					24.32	
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	min of $[P\alpha(Zs),Ita,\alpha(Zs)]$	(mW)				13.24		
Associated	\mathbf{z}_1	Z_{s}	(cm)				1.8		
Acoustic	Z _{bp}	Z_{bp}	(cm)				1.8		
Parameter	Z_{sp}	Z_b	(cm)					2.1	
	Z@PII.3max	Z at max $I_{pi \alpha}$	(cm)	2.3					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)					0.23	
	f_c	f_{awf}	(MHz)	4.87			4.87	4.85	
	Dim of A _{aprt}	Dim of A _{aprt}	X (cm)				1.21	1.21	
	Dilli Of A _{aprt}	Dilli of A _{aprt}	Y (cm)				0.90	0.90	
	PD	t_d	(µsec)	0.31					
	PRF	prr	(Hz)	7273					
	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	2.29					
Other	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)					0.23	
Information			FL _x (cm)				0.35		
	Focal Length	Focal Length	FLy (cm)				0.27		
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	120.55					
Operating	Mode	Mode	NA	M			M	M	
Control	Focus	Focus	(cm)	3			3	3	
Conditions	Power	Power	(%)	100			100	100	

Transducer Model: <u>V7W-E</u> Operating Mode: <u>B</u>

	suucei Mio	uei. <u> </u>	,	perating		TIS		TIB	
	Inde	ex Label		MI		non-	scan		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Maxi	mum Index Va	alue		0.4	0.2				
	p _{r.3}	$p_{r,\alpha}$	(MPa)	0.96					
	W_{o}	P	(mW)		29.70				
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	$\begin{aligned} & \text{min of} \\ & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)						
	\mathbf{z}_1	$Z_{\rm s}$	(cm)						
Associated	Z _{bp}	Z_{bp}	(cm)						
Acoustic	Z_{sp}	Z_b	(cm)						
Parameter	z@PII _{.3max}	Z at max $I_{pi\alpha}$	(cm)	2.5					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_{c}	f_{awf}	(MHz)	4.25	4.23				
	Dim of		X (cm)		1.48				
	A _{aprt}	Dim of A _{aprt}	Y (cm)		0.70				
	PD	$t_{\rm d}$	(µsec)	0.68					
	PRF	prr	(Hz)	4350					
	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	1.3					
Other Information	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)						
Illiorillation	Focal	Focal Length	FL _x (cm)		0.21				
	Length	Focai Length	FLy (cm)		0.34				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	41.42					
Operating	Mode	Mode	NA	В	В				
Control	Focus	Focus	(cm)	2.5	1.5				
Conditions	Power	Power	(%)	100	100				

Transducer Model: <u>V7W-E</u> Operating Mode: <u>THI-B</u>

						TIS		TIB	
	Ind	ex Label		MI	G	non	-scan		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Maxi	mum Index Va	alue		0.6	0.2				
	p _{r.3}	$p_{r,\alpha}$	(MPa)	0.89					
	Wo	P	(mW)		30.61				
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	min of $[P\alpha(Zs),Ita,\alpha(Zs)]$	(mW)						
Associated	z_1	$Z_{\rm s}$	(cm)						
Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	Z_{sp}	Z_b	(cm)						
	Z@PII.3max	Z at max Ipi α	(cm)	2.4					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	$f_{ m awf}$	(MHz)	4.21	4.20				
	Dim of	Dim of A _{aprt}	X (cm)		1.48				
	A _{aprt}	Dilli of A _{aprt}	Y (cm)		0.70				
	PD	t _d	(µsec)	0.76					
	PRF	prr	(Hz)	4348					
	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	1.4					
Other Information	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)						
Imormation	Focal	Essal Lausth	FL _x (cm)		0.26				
	Length	Focal Length	FLy (cm)		0.37				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	42.17					
Operating	Mode	Mode	NA	THI-B	THI-B				
Control	Focus	Focus	(cm)	2.5	1.5				
Conditions	Power	Power	(%)	100	100				

Transducer Model: <u>V7W-E</u> Operating Mode: <u>B+C</u>

		dei. <u>V/W-E</u>	-	craiing iv		TIS		TIB	
	Ind	ex Label		MI	G	non-	-scan		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Maxi	mum Index Va	alue		0.5	0.4				
	p _{r.3}	$p_{\mathrm{r},\alpha}$	(MPa)	0.82					
	W_{o}	P	(mW)		77.22				
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	min of $[P\alpha(Zs),Ita,\alpha(Zs)]$	(mW)						
Associated	z_1	Z_{s}	(cm)						
Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	Z_{sp}	Z_{b}	(cm)						
	Z@PII.3max	Z at max Ipi α	(cm)	2.4					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	f_{awf}	(MHz)	5.27	5.27				
	Dim of	Dim of A _{aprt}	X (cm)		1.48				
	A _{aprt}	Dim of Frapri	Y (cm)		0.70				
	PD	$t_{\rm d}$	(µsec)	0.71					
	PRF	prr	(Hz)	6042					
	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	1.39					
Other Information	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)						
Information	Focal	Focal Langth	FL _x (cm)		0.22				
	Length	Focal Length	FLy (cm)		0.29				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	30.6					
Operating	Mode	Mode	NA	С	С				
Control	Focus	Focus	(cm)	2.5	2				
Conditions	Power	Power	(%)	100	100				

Transducer Model: <u>V7W-E</u> Operating Mode: <u>B+C+PW</u>

		<u> </u>		l uting iv		TIS		TIB	
	Inc	dex Label		MI	G	non-	scan		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Maxi	mum Index V	alue	_	0.4			1.0	2.1	
	$p_{r.3}$	$p_{\mathrm{r},\alpha}$	(MPa)	1.07					
	W_{o}	P	(mW)					100.97	
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	min of $[P\alpha(Zs),Ita,\alpha(Zs)]$	(mW)				53.19		
Associated	z_1	$Z_{\rm s}$	(cm)				1.8		
Acoustic	Z _{bp}	Z_{bp}	(cm)				1.7		
Parameter	z_{sp}	Z_{b}	(cm)					2.0	
	Z@PII.3max	Z at max Ipi α	(cm)	2.7					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)					0.51	
	f_c	$ m f_{awf}$	(MHz)	5.28			5.28	5.28	
	Dim of	Dim of A _{aprt}	X (cm)				1.48	1.48	
	A _{aprt}	Dilli Of A _{aprt}	Y (cm)				0.70	0.70	
	PD	t _d	(µsec)	0.86					
	PRF	prr	(Hz)	5555					
	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	1.52					
Other	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)					0.52	
Information	Focal	Focal Length	FL _x (cm)				0.25		
	Length	1 ocai Length	FLy (cm)				0.21		
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	142.69					
Operating	Mode	Mode	NA	PW			PW	PW	
Control	Focus	Focus	(cm)	3			2.5	2	
Conditions	Power	Power	(%)	100			100	100	

Transducer Model: <u>V7W-E</u> Operating Mode: <u>M</u>

		<u> </u>		cruting iv		TIS		TIB	
	Ind	ex Label		MI	G	non	-scan		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Maxi	mum Index Va	alue		0.4			0.5	1.1	
	p _{r.3}	$p_{\mathrm{r},lpha}$	(MPa)	0.98					
	\mathbf{W}_{o}	P	(mW)					47.68	
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	min of $[P\alpha(Zs),Ita,\alpha(Zs)]$	(mW)				28.70		
Associated	z_1	$Z_{\rm s}$	(cm)				1.8		
Acoustic	Z _{bp}	Z_{bp}	(cm)				1.7		
Parameter	Z_{sp}	Z_{b}	(cm)					2.3	
	z@PII _{.3max}	Z at max $I_{pi\alpha}$	(cm)	2.3					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)					0.46	
	f_c	$ m f_{awf}$	(MHz)	4.15			4.19	4.16	
	Dim of	Dim of A _{aprt}	X (cm)				1.48	1.48	
	A _{aprt}	Dilli Of Aaprt	Y (cm)				0.70	0.70	
	PD	t _d	(µsec)	0.67					
	PRF	prr	(Hz)	5550					
	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	1.31					
Other	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)					0.45	
Information	Focal	Focal Length	FL _x (cm)				0.26		
	Length	1 ocai Length	FLy (cm)				0.29		
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	145.23					
Operating	Mode	Mode		M			M	M	
Control	Focus	Focus	(cm)	3			2	3	
Conditions	Power	Power	(%)	100			100	100	

Transducer Model: <u>V7-E</u> Operating Mode: <u>B</u>

				cruting iv		TIS		TIB	
	Index	Label		MI	G	non-	scan		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Max	imum Index Val	ue		0.5	0.2				
	p _{r.3}	$p_{r,\alpha}$	(MPa)	0.98					
	W_{o}	P	(mW)		29.70				
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	$\begin{aligned} & \text{min of} \\ & & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)						
Associated	z_1	Z_{s}	(cm)						
Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	Z_{sp}	Z_b	(cm)						
	Z@PII _{.3max}	Z at max $I_{pi \alpha}$	(cm)	2.4					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	f_{awf}	(MHz)	4.15	4.17				
	Dim of A _{aprt}	Dim of A _{aprt}	X (cm)		1.48				
	Dilli Of A _{aprt}	Dilli Of A _{aprt}	Y (cm)		0.70				
	PD	$t_{\rm d}$	(µsec)	0.67					
	PRF	prr	(Hz)	4342					
	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	1.30					
Other	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)						
Information			FL _x (cm)		0.22				
	Focal Length	Focal Length	FLy (cm)		0.36				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	41.35					
Operating	Mode	Mode	NA	В	В				
Control	Focus	Focus	(cm)	2.5	1.5				
Conditions	Power	Power	(%)	100	100				

Transducer Model: <u>V7-E</u> Operating Mode: <u>THI-B</u>

			<u> </u>			TIS		TIB	
	Inde	ex Label		MI	G	non-s	scan		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Max	i mum Index Val	ue		0.4	0.2				
	p _{r.3}	$p_{r,\alpha}$	(MPa)	0.87					
	Wo	P	(mW)		29.70				
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	min of $[P\alpha(Zs),Ita,\alpha(Zs)]$	(mW)						
Associated	z_1	$Z_{\rm s}$	(cm)						
Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	Z_{sp}	Z_b	(cm)						
	z@PII _{.3max}	Z at max $I_{pi \alpha}$	(cm)	2.3					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_{c}	$ m f_{awf}$	(MHz)	4.13	4.16				
	Dim of A	Dim of A	X (cm)		1.48				
	Dim of A _{aprt}	Dim of A _{aprt}	Y (cm)		0.70				
	PD	$t_{\rm d}$	(µsec)	0.67					
	PRF	prr	(Hz)	4347					
0.1	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	1.30					
Other Information	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)						
IIIIOIIIIatioii	F 1 I 4b	Escal Land	FL _x (cm)		0.22				
	Focal Length	Focal Length	FLy (cm)		0.31				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	41.35					
Operating	Mode	Mode	NA	THI-B	THI-B				
Control	Focus	Focus	(cm)	2.5	1.5				
Conditions	Power	Power	(%)	100	100				

Transducer Model: <u>V7-E</u> Operating Mode: <u>B+C</u>

				ing ivious		TIS		TIB	
	Inde	ex Label		MI	Casa	non-	scan		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Max	imum Index Val	lue		0.4	0.7				
	p _{r.3}	$p_{\mathrm{r},\alpha}$	(MPa)	0.95					
	W_{o}	P	(mW)		77.20				
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	min of $[P\alpha(Zs),Ita,\alpha(Zs)]$	(mW)						
Associated	z_1	Z_{s}	(cm)						
Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	Z_{sp}	Z_{b}	(cm)						
	Z@PII.3max	Z at max $I_{pi \alpha}$	(cm)	2.5					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	$f_{ m awf}$	(MHz)	5.27	5.29				
	Dim of A	Dim of A	X (cm)		1.48				
	Dim of A _{aprt}	Dim of A _{aprt}	Y (cm)		0.70				
	PD	$t_{\rm d}$	(µsec)	0.70					
	PRF	prr	(Hz)	6024					
Other	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	1.38					
Informatio	d _{eq} @PII _{max}	d _{eq} at max I _{pi}	(cm)						
n	Focal Length	Focal Length	FL _x (cm)		0.21				
	rocai Length	Focal Length	FLy (cm)		0.29				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	30.21					
Operating	Mode	Mode	NA	С	С				
Control	Focus	Focus	(cm)	2.5	2				
Conditions	Power	Power	(%)	100	100				

Transducer Model: <u>V7-E</u> Operating Mode: <u>B+C+PW</u>

						TIS		TIB	
	Inde	ex Label		MI	G	non-	scan		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Max	imum Index Val	ue		0.5			1.3	2.2	
	p _{r.3}	$p_{r,\alpha}$	(MPa)	1.07					
	W_{o}	P	(mW)					100.97	
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	min of $[P\alpha(Zs),Ita,\alpha(Zs)]$	(mW)				53.19		
Associated	z_1	$Z_{\rm s}$	(cm)				1.8		
Acoustic	Z _{bp}	Z_{bp}	(cm)				1.7		
Parameter	Z_{sp}	Z_{b}	(cm)					2.0	
	Z@PII _{.3max}	Z at max $I_{pi \alpha}$	(cm)	2.6					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)					0.51	
	f_c	f_{awf}	(MHz)	5.30			5.30	5.28	
	Dim of A _{aprt}	Dim of A _{aprt}	X (cm)				1.48	1.48	
	Dilli Of Aaprt	Dilli Of Aaprt	Y (cm)				0.70	0.70	
	PD	t _d	(µsec)	0.87					
	PRF	prr	(Hz)	5551					
Other	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	1.52					
Other Information	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)					0.51	
imormation	Focal Length	Focal Length	FL _x (cm)				0.26		
	rocai Lengui	rocar Length	FLy (cm)				0.22		
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	143.32					
Operating	Mode	Mode	NA	PW			PW	PW	
Control	Focus	Focus	(cm)	3			2.5	2	
Conditions	Power	Power	(%)	100			100	100	

Transducer Model: <u>V7-E</u> Operating Mode: <u>M</u>

	ansuucei wio	uer. <u>V 7-12</u>		ating Mo		TIS		TIB	
	Inde	x Label		MI	C	non-	scan		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Max	imum Index Val	ue		0.5			0.6	1.2	
	$p_{r.3}$	$p_{\mathrm{r},\alpha}$	(MPa)	0.98					
	Wo	P	(mW)					47.51	
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	min of $[P\alpha(Zs),Ita,\alpha(Zs)]$	(mW)				28.70		
Associated	\mathbf{z}_1	$Z_{\rm s}$	(cm)				1.8		
Acoustic	Z _{bp}	Z_{bp}	(cm)				1.7		
Parameter	Z _{sp}	Z_{b}	(cm)					2.3	
	Z@PII _{.3max}	Z at max $I_{pi\alpha}$	(cm)	2.4					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)					0.46	
	f_c	f_{awf}	(MHz)	4.13			4.16	4.13	
	Dim of A _{aprt}	Dim of A _{aprt}	X (cm)				1.48	1.48	
	Dilli Of Aaprt	Dim of Aaprt	Y (cm)				0.70	0.70	
	PD	t_d	(µsec)	0.67					
	PRF	prr	(Hz)	5546					
	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	1.30					
Other	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)					0.45	
Information	Focal Length	Focal Length	FL _x (cm)				0.25		
	r ocar Length	rocal Length	FLy (cm)				0.21		
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	140.31					
Operating	Mode	Mode		M			M	M	
Control	Focus	Focus	(cm)	3			2	3	
Conditions	Power	Power	(%)	100			100	100	

Transducer Model: <u>V7-ES</u> Operating Mode: <u>B</u>

		<u> </u>		per uring r		TIS		TIB	
	Index	Label		MI	G	non-	scan		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Max	imum Index Val	ue		0.5	0.2				
	$p_{r.3}$	$p_{r,\alpha}$	(MPa)	0.98					
	W_{o}	P	(mW)		29.70				
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	$\begin{aligned} & \text{min of} \\ & & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)						
Associated	z_1	Z_{s}	(cm)						
Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	Z_{sp}	Z_b	(cm)						
	Z@PII _{.3max}	Z at max $I_{pi \alpha}$	(cm)	2.4					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	f_{awf}	(MHz)	4.15	4.17				
	Dim of A _{aprt}	Dim of A _{aprt}	X (cm)		1.48				
	Dilli Of Aaprt	Dilli Of Aaprt	Y (cm)		0.70				
	PD	t _d	(µsec)	0.67					
	PRF	prr	(Hz)	4342					
	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	1.30					
Other	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)						
Information			FL _x (cm)		0.22				
	Focal Length	Focal Length	FLy (cm)		0.36				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	41.35					
Operating	Mode	Mode	NA	В	В				
Control	Focus	Focus	(cm)	2.5	1.5				
Conditions	Power	Power	(%)	100	100				

Transducer Model: <u>V7-ES</u> Operating Mode: <u>THI-B</u>

	isducci iviou	CI. <u>V7-E5</u>			uc. <u>1111-</u>	TIS		TIB	
	Inde	ex Label		MI	q	non-s	scan		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Maxi	i mum Index Val	ue		0.4	0.2				
	p _{r.3}	$p_{r,\alpha}$	(MPa)	0.87					
	Wo	P	(mW)		29.70				
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	min of $[P\alpha(Zs),Ita,\alpha(Zs)]$	(mW)						
Associated	z_1	Z_{s}	(cm)						
Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	Z_{sp}	Z_b	(cm)						
	z@PII _{.3max}	Z at max $I_{pi \alpha}$	(cm)	2.3					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	$ m f_{awf}$	(MHz)	4.13	4.16				
	Dim of A	Dim of A	X (cm)		1.48				
	Dim of A _{aprt}	Dim of A _{aprt}	Y (cm)		0.70				
	PD	t _d	(µsec)	0.67					
	PRF	prr	(Hz)	4347					
0.1	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	1.30					
Other Information	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)						
Information	Escal Lameth	Es sal I amadh	FL _x (cm)		0.22				
	Focal Length	Focal Length	FLy (cm)		0.31				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	41.35					
Operating	Mode	Mode	NA	THI-B	THI-B				
Control	Focus	Focus	(cm)	2.5	1.5				
Conditions	Power	Power	(%)	100	100				

Transducer Model: <u>V7-ES</u> Operating Mode: <u>B+C</u>

			_			TIS		TIB	
	Inde	x Label		MI	Casa	non-	scan		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Max	imum Index Val	ue		0.4	0.7				
	p _{r.3}	$p_{r,\alpha}$	(MPa)	0.95					
	\mathbf{W}_{o}	P	(mW)		77.20				
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	min of $[P\alpha(Zs),Ita,\alpha(Zs)]$	(mW)						
Associated	z_1	Z_{s}	(cm)						
Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	Z_{sp}	Z_{b}	(cm)						
	Z@PII.3max	Z at max $I_{pi \alpha}$	(cm)	2.5					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	$f_{ m awf}$	(MHz)	5.27	5.29				
	Dim of A _{aprt}	Dim of A _{aprt}	X (cm)		1.48				
	Dilli Of A _{aprt}	Dilli Of A _{aprt}	Y (cm)		0.70				
	PD	$t_{\rm d}$	(µsec)	0.70					
	PRF	prr	(Hz)	6024					
Other	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	1.38					
Informatio	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)						
n	Focal Length	Focal Length	FL _x (cm)		0.21				
	rocai Length	rocai Length	FLy (cm)		0.29				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	30.21					
Operating	Mode	Mode	NA	С	С				
Control	Focus	Focus	(cm)	2.5	2				
Conditions	Power	Power	(%)	100	100				

Transducer Model: <u>V7-ES</u> Operating Mode: <u>B+C+PW</u>

			_			TIS		TIB	
	Inde	x Label		MI	Caan	non-	scan		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Max	imum Index Val	ue		0.5			1.3	2.2	
	p _{r.3}	$p_{r,\alpha}$	(MPa)	1.07					
	\mathbf{W}_{o}	P	(mW)					100.97	
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	min of $[P\alpha(Zs),Ita,\alpha(Zs)]$	(mW)				53.19		
Associated	z_1	Z_{s}	(cm)				1.8		
Acoustic	Z _{bp}	$Z_{ m bp}$	(cm)				1.7		
Parameter	Z_{sp}	Z_b	(cm)					2.0	
	z@PII _{.3max}	Z at max $I_{pi \alpha}$	(cm)	2.6					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)					0.51	
	f_c	$f_{ m awf}$	(MHz)	5.30			5.30	5.28	
	Dim of A _{aprt}	Dim of A _{aprt}	X (cm)				1.48	1.48	
	Dilli Of A _{aprt}	Dilli Of A _{aprt}	Y (cm)				0.70	0.70	
	PD	$t_{\rm d}$	(µsec)	0.87					
	PRF	prr	(Hz)	5551					
0.1	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	1.52					
Other Information	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)					0.51	
Illioilliation	Focal Length	Focal Length	FL_{x} (cm)				0.26		
	T ocur Bengui	Total Bengin	FLy (cm)				0.22		
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	143.32					
Operating	Mode	Mode	NA	PW			PW	PW	
Control	Focus	Focus	(cm)	3			2.5	2	
Conditions	Power	Power	(%)	100			100	100	

Transducer Model: <u>V7-ES</u> Operating Mode: <u>M</u>

	ansuucei wio	uei. <u>V / - L/S</u>	Î	craung w		TIS		TIB	
	Inde	x Label		MI	C	non-	scan		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Max	imum Index Val	ue		0.5			0.6	1.2	
	$p_{r,3}$	$p_{r,\alpha}$	(MPa)	0.98					
	Wo	P	(mW)					47.51	
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	min of $[P\alpha(Zs),Ita,\alpha(Zs)]$	(mW)				28.70		
Associated	\mathbf{z}_1	$Z_{\rm s}$	(cm)				1.8		
Acoustic	Z _{bp}	Z_{bp}	(cm)				1.7		
Parameter	Z _{sp}	Z_{b}	(cm)					2.3	
	Z@PII _{.3max}	Z at max $I_{pi\alpha}$	(cm)	2.4					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)					0.46	
	f_c	f_{awf}	(MHz)	4.13			4.16	4.13	
	Dim of A _{aprt}	Dim of A _{aprt}	X (cm)				1.48	1.48	
	Dilli Of Aaprt	Dim of Aaprt	Y (cm)				0.70	0.70	
	PD	t _d	(µsec)	0.67					
	PRF	prr	(Hz)	5546					
	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	1.30					
Other	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)					0.45	
Information	Focal Length	Focal Length	FL _x (cm)				0.25		
	r ocar Length	rocal Length	FLy (cm)				0.21		
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	140.31					
Operating	Mode	Mode		M			M	M	
Control	Focus	Focus	(cm)	3			2	3	
Conditions	Power	Power	(%)	100			100	100	

Transducer Model: MC5-E Operating Mode: B

	isducei wiode			perating iv		TIS		TIB	
	Index	Label		MI	G	non-	scan		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Maxi	imum Index Valu	ue		0.9	1.7				
	$p_{r.3}$	$p_{\mathrm{r},lpha}$	(MPa)	1.96					
	W_{o}	P	(mW)		350.19				
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	$\begin{aligned} & \text{min of} \\ & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)						
Associated	z_1	Z_{s}	(cm)						
Associated	Z _{bp}	Z_{bp}	(cm)						
Parameter	z_{sp}	Z_b	(cm)						
	Z@PII _{.3max}	Z at max $I_{pi\alpha}$	(cm)	2.4					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	$f_{ m awf}$	(MHz)	4.82	5.01				
	Dim of A _{aprt}	Dim of A _{aprt}	X (cm)		1.46				
	Dilli Of A _{aprt}	Dilli of A _{aprt}	Y (cm)		1.00				
	PD	$t_{\rm d}$	(µsec)	0.43					
	PRF	prr	(Hz)	14701					
	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	2.69					
Other	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)						
Information	Produced	E al Land	FL _x (cm)		0.27				
	Focal Length	Focal Length	FLy (cm)		0.22				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	80.61					
Operating	Mode	Mode	NA	В	В				
Control	Focus	Focus	(cm)	4	1.5				
Conditions	Power	Power	(%)	100	100				

Transducer Model: MC5-E Operating Mode: THI-B

				per uting 1		TIS		TIB	
	Index	Label		MI	Coor	non-	scan		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Maxi	imum Index Valu	ıe		0.8	1.9				
	$p_{r,3}$	$p_{r,\alpha}$	(MPa)	1.81					
	W_{o}	P	(mW)		350.21				
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	$\begin{aligned} & \text{min of} \\ & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)						
Associated	z_1	Z_{s}	(cm)						
Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	Z _{sp}	Z_b	(cm)						
	Z@PII.3max	Z at max $I_{pi \alpha}$	(cm)	2.5					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	f_{awf}	(MHz)	4.80	4.72				
	Dim of A _{aprt}	Dim of A _{aprt}	X (cm)		1.46				
	Dilli Of Aaprt	Dilli Of Aaprt	Y (cm)		1.00				
	PD	$t_{\rm d}$	(µsec)	0.43					
	PRF	prr	(Hz)	14701					
	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	2.65					
Other	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)						
Information	Focal Length	Focal Length	FL _x (cm)		0.27				
	1 ocai Lengui	Tocal Length	FLy (cm)		0.21				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	80.53					
Operating	Mode	Mode	NA	THI-B	THI-B				
Control	Focus	Focus	(cm)	4	1.5				
Conditions	Power	Power	(%)	100	100				

Transducer Model: MC5-E Operating Mode: B+C

	isuucei viouc			perating iv		TIS		TIB	
	Index	Label		MI	G	non-	scan		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Maxi	i mum Index Valı	ıe		0.6	2.2				
	$p_{r,3}$	$p_{r,\alpha}$	(MPa)	1.39					
	W_{o}	P	(mW)		321.02				
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	$\begin{aligned} & \text{min of} \\ & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)						
Associated	\mathbf{z}_1	Z_{s}	(cm)						
Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	z_{sp}	Z_b	(cm)						
	Z@PII.3max	Z at max $I_{pi \alpha}$	(cm)	2.9					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	f_{awf}	(MHz)	3.98	4.02				
	Dim of A _{aprt}	Dim of A _{aprt}	X (cm)		1.46				
	Dilli Of Aaprt	Dilli Of Aaprt	Y (cm)		1.00				
	PD	$t_{\rm d}$	(µsec)	0.96					
	PRF	prr	(Hz)	5949					
	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	1.70					
Other	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)						
Information	Focal Length	Focal Length	FL _x (cm)		0.18				
	rocai Lengui	rocal Length	FLy (cm)		0.23				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm^2)	58.35					
Operating	Mode	Mode	NA	С	С				
Control	Focus	Focus	(cm)	3.5	3.5				
Conditions	Power	Power	(%)	100	100				

Transducer Model: MC5-E Operating Mode: B+C+PW

		Wee E		peruumg m		TIS		TIB	
	Index	Label		MI	Caan	non-	scan		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Maxi	imum Index Valu	ie		0.7			1.7	1.5	
	$p_{r,3}$	$p_{r,\alpha}$	(MPa)	1.60					
	W_{o}	P	(mW)					449.43	
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	$\begin{aligned} & \text{min of} \\ & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)				256.69		
Associated	z_1	Z_{s}	(cm)				2.1		
Acoustic	Z _{bp}	Z_{bp}	(cm)				2.0		
Parameter	Z _{sp}	Z_b	(cm)					2.2	
	Z@PII.3max	Z at max $I_{pi \alpha}$	(cm)	2.3					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)					0.72	
	f_c	f_{awf}	(MHz)	3.93			3.94	3.95	
	Dim of A _{aprt}	Dim of A _{aprt}	X (cm)				1.46	1.46	
	Dilli Of Aaprt	Dilli Of Aaprt	Y (cm)				1.00	1.00	
	PD	$t_{\rm d}$	(µsec)	0.95					
	PRF	prr	(Hz)	6022					
	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	2.10					
Other	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)					0.69	
Information	Focal Length	Focal Length	FL _x (cm)				0.16		
	Toom Bengui	Total Bengan	FLy (cm)				0.21		
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	101.25					
Operating	Mode	Mode	NA	PW			PW	PW	
Control	Focus	Focus	(cm)	2			3	3	
Conditions	Power	Power	(%)	100			100	100	

Transducer Model: MC5-E Operating Mode: M

				per utilig iv		TIS		TIB	
	Index	Label		MI	Caan	non-	scan		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Max	imum Index Valı	ıe		0.8			2.1	2.0	
	$p_{r.3}$	$p_{r,\alpha}$	(MPa)	2.02					
	W_{o}	P	(mW)					356.04	
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	$\begin{aligned} & \text{min of} \\ & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)				177.51		
Associated	\mathbf{z}_1	Z_{s}	(cm)				2.1		
Acoustic	Z _{bp}	Z_{bp}	(cm)				2.0		
Parameter	Z_{sp}	Z_b	(cm)					2.1	
	z@PII _{.3max}	Z at max $I_{pi \alpha}$	(cm)	2.2					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)					0.74	
	f_c	f_{awf}	(MHz)	4.75			4.92	4.83	
	Dim of A _{aprt}	Dim of A _{aprt}	X (cm)				1.46	1.46	
	Dilli Of A _{aprt}	Dilli Of A _{aprt}	Y (cm)				1.00	1.00	
	PD	$t_{\rm d}$	(µsec)	0.42					
	PRF	prr	(Hz)	14725					
	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	2.83					
Other	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)					0.74	
Information	Focal Length	Focal Length	FL _x (cm)				0.31		
	1 ocai Lengui	1 ocai Lengtii	FLy (cm)				0.26		
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	111.30					
Operating	Mode	Mode	NA	M			M	M	
Control	Focus	Focus	(cm)	3.5			2.5	2	
Conditions	Power	Power	(%)	100			100	100	

Transducer Model: MC3-E Operating Mode: B

	isducer wiod	ci. <u>Nics-E</u>		crating iv.		TIS		TIB	
	Inde	x Label		MI	C	non-	scan		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Maxi	imum Index Val	ue		0.7	1.6				
	p _{r.3}	$p_{r,\alpha}$	(MPa)	1.30					
	W_{o}	P	(mW)		365.52				
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	min of $[P\alpha(Zs),Ita,\alpha(Zs)]$	(mW)						
Associated	z_1	Z_{s}	(cm)						
Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	Z_{sp}	Z_b	(cm)						
	z@PII _{.3max}	Z at max $I_{pi \alpha}$	(cm)	5.0					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	$f_{awCW2-E}$	(MHz)	3.27	3.42				
	Dim of A _{aprt}	Dim of A _{aprt}	X (cm)		2.05				
	Dilli Of Aaprt	Diffi of 7 taprt	Y (cm)		1.30				
	PD	t _d	(µsec)	0.60					
	PRF	prr	(Hz)	3846					
	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	2.22					
Other	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)						
Information	Focal Length	Focal Length	FL _x (cm)		0.23				
	1 ocal Length	1 ocal Length	FLy (cm)		0.25				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	55.70					
Operating	Mode	Mode	NA	В	В				
Control	Focus	Focus	(cm)	5	7				
Conditions	Power	Power	(%)	100	100				

Transducer Model: MC3-E Operating Mode: THI-B

		<u> </u>			<u> </u>	TIS		TIB]
	Inde	x Label		MI	Caam	non-	scan		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Max	imum Index Val	ue		0.7	1.7				
	p _{r.3}	$p_{\mathrm{r},\alpha}$	(MPa)	1.24					
	\mathbf{W}_{o}	P	(mW)		365.57				
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	min of $[P\alpha(Zs),Ita,\alpha(Zs)]$	(mW)						
Associated	z_1	Z_{s}	(cm)						
Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	Z_{sp}	Z_{b}	(cm)						
	Z@PII.3max	Z at max $I_{pi \alpha}$	(cm)	4.9					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	$ m f_{awf}$	(MHz)	3.25	3.36				
	Dim of A _{aprt}	Dim of A _{aprt}	X (cm)		2.05				
	Dilli Of A _{aprt}	Dilli Of A _{aprt}	Y (cm)		1.30				
	PD	t_d	(µsec)	0.60					
	PRF	prr	(Hz)	3841					
	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	2.22					
Other	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)						
Information	Focal Length	Focal Length	FL _x (cm)		0.25				
	Tocal Length	1 ocai Lengtii	FLy (cm)		0.25				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	55.74					
Operating	Mode	Mode	NA	THI-B	THI-B				
Control	Focus	Focus	(cm)	5	7				
Conditions	Power	Power	(%)	100	100				

Transducer Model: MC3-E Operating Mode: B+C

		<u> </u>			<u> </u>	TIS		TIB	
	Inde	x Label		MI	Coom	non-	scan		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Max	imum Index Val	ue		0.4	0.3				
	p _{r.3}	$p_{\mathrm{r},\alpha}$	(MPa)	0.49					
	W_{o}	P	(mW)		136.19				
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	min of $[P\alpha(Zs),Ita,\alpha(Zs)]$	(mW)						
Associated	z_1	Z_{s}	(cm)						
Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	Z_{sp}	Z_{b}	(cm)						
	Z@PII.3max	Z at max $I_{pi \alpha}$	(cm)	3.8					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	$ m f_{awf}$	(MHz)	2.84	2.84				
	Dim of A _{aprt}	Dim of A _{aprt}	X (cm)		2.05				
	Dilli Of A _{aprt}	Dilli Of A _{aprt}	Y (cm)		1.30				
	PD	t_d	(µsec)	0.91					
	PRF	prr	(Hz)	5948					
	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	0.79					
Other	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)						
Information	Focal Length	Focal Length	FL _x (cm)		0.21				
	1 ocai Lengui	1 ocai Lengin	FLy (cm)		0.21				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	10.35					
Operating	Mode	Mode	NA	С	С				
Control	Focus	Focus	(cm)	5	5				
Conditions	Power	Power	(%)	100	100				

Transducer Model: MC3-E Operating Mode: B+C+PW

					D+C	TIS		TIB	
	Inde	x Label		MI	Cana	non-	scan		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Max	imum Index Val	ue		0.3			0.4	0.7	
	p _{r.3}	$p_{r,\alpha}$	(MPa)	0.54					
	W_{o}	P	(mW)					78.80	
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	min of $[P\alpha(Zs),Ita,\alpha(Zs)]$	(mW)				36.09		
Associated	z_1	$Z_{\rm s}$	(cm)				3.8		
Acoustic	Z _{bp}	Z_{bp}	(cm)				2.8		
Parameter	Z_{sp}	Z_b	(cm)					3.4	
	Z@PII.3max	Z at max $I_{pi \alpha}$	(cm)	5.5					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)					1.13	
	f_c	f_{awf}	(MHz)	2.90			2.90	2.89	
	Dim of A _{aprt}	Dim of A _{aprt}	X (cm)				2.05	2.05	
	Dilli Of A _{aprt}	Dilli of A _{aprt}	Y (cm)				1.30	1.30	
	PD	t_d	(µsec)	0.90					
	PRF	prr	(Hz)	3835					
	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	0.74					
Other	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)					1.07	
Information	Focal Length	Focal Length	FL _x (cm)				0.25		
	Tour Bengui	2 ocus Bongui	FLy (cm)				0.31		
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	170.36					
Operating	Mode	Mode	NA	PW			PW	PW	
Control	Focus	Focus	(cm)	5			5	5	
Conditions	Power	Power	(%)	100			100	100	

Transducer Model: MC3-E Operating Mode: M

		<u> </u>	<u> </u>	or acting 10		TIS		TIB	
	Inde	x Label		MI	Cana	non-	scan		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Maxi	imum Index Val	ue		0.8			1.7	1.5	
	p _{r.3}	$p_{r,\alpha}$	(MPa)	1.27					
	Wo	P	(mW)					487.42	
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	min of $[P\alpha(Zs),Ita,\alpha(Zs)]$	(mW)				219.13		
Associated	z_1	Z_{s}	(cm)				3.6		
Acoustic	Z _{bp}	$Z_{ m bp}$	(cm)				2.8		
Parameter	Z_{sp}	Z_b	(cm)					4.3	
	z@PII _{.3max}	Z at max $I_{pi \alpha}$	(cm)	4.6					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)					0.92	
	f_c	$f_{ m awf}$	(MHz)	3.26			3.26	3.25	
	Dim of A _{aprt}	Dim of A _{aprt}	X (cm)				2.05	2.05	
	Dilli Of A _{aprt}	Dilli of A _{aprt}	Y (cm)				1.30	1.30	
	PD	$t_{\rm d}$	(µsec)	0.50					
	PRF	prr	(Hz)	7573					
	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	1.92					
Other	d _{eq} @PII _{max}	d _{eq} at max I _{pi}	(cm)					0.89	
Information	Focal Length	Focal Length	FL _x (cm)				0.34		
	Total Length	Total Longin	FLy (cm)				0.26		
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	162.39					
Operating	Mode	Mode	NA	M			M	M	
Control	Focus	Focus	(cm)	5			5	5	
Conditions	Power	Power	(%)	100			100	100	

Transducer Model: MC6-E Operating Mode: B

			<u> </u>	144411911110	<u> </u>	TIS		TIB	
	Inde	x Label		MI	G	non-	scan		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Maxi	imum Index Val	ue		0.8	1.1				
	p _{r.3}	$p_{r,\alpha}$	(MPa)	1.92					
	W_{o}	P	(mW)		409.60				
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	min of $[P\alpha(Zs),Ita,\alpha(Zs)]$	(mW)						
Associated	z_1	$Z_{\rm s}$	(cm)						
Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	Z_{sp}	Z_{b}	(cm)						
	Z@PII.3max	Z at max $I_{pi \alpha}$	(cm)	2.7					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	$ m f_{awf}$	(MHz)	5.66	5.85				
	Dim of A _{aprt}	Dim of A _{aprt}	X (cm)		1.22				
	Dilli Of A _{aprt}	Dilli Of A _{aprt}	Y (cm)		0.90				
	PD	t_d	(µsec)	0.26					
	PRF	prr	(Hz)	5923					
	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	2.75					
Other Information	d _{eq} @PII _{max}	d _{eq} at max I _{pi}	(cm)						
	Focal Length	Focal Length	FL _x (cm)		0.32				
	rocai Lengui	Focal Length	FLy (cm)		0.33				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	83.76					
Operating	Mode	Mode	NA	В	В				
Control	Focus	Focus	(cm)	2.5	2				
Conditions	Power	Power	(%)	100	100				

Transducer Model: MC6-E Operating Mode: THI-B

					1111	TIS		TIB	
	Inde	x Label		MI	Caar	non-s	scan		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Max	imum Index Valu	ıe		0.8	1.2				
	$p_{r.3}$	$p_{r,\alpha}$	(MPa)	1.85					
	W_{o}	P	(mW)		409.60				
	min of $[W_{.3}(z_1),$ $I_{TA.3}(z_1)]$	min of $[P\alpha(Zs),Ita,\alpha(Zs)]$	(mW)						
Associated	z_1	Z_{s}	(cm)						
Acoustic	z _{bp}	Z_{bp}	(cm)						
Parameter	Z_{sp}	Z_b	(cm)						
	Z@PII _{.3max}	Z at max $I_{pi \alpha}$	(cm)	2.7					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	f_{awf}	(MHz)	5.63	5.78				
	Dim of A _{aprt}	Dim of A _{aprt}	X (cm)		1.22				
	Dilli Of A _{aprt}	Dilli Of A _{aprt}	Y (cm)		0.90				
	PD	$t_{\rm d}$	(µsec)	0.26					
	PRF	prr	(Hz)	5924					
0.1	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	2.77					
Other	$d_{eq}@PII_{max}$	d_{eq} at max I_{pi}	(cm)						
Informatio n			FL _x (cm)		0.31				
п	Focal Length	Focal Length	FLy (cm)		0.34				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	83.73					
Operating	Mode	Mode	NA	THI-B	THI-B				
Control	Focus	Focus	(cm)	2.5	2				
Conditions	Power	Power	(%)	100	100				

Transducer Model: MC6-E Operating Mode: B+C

	isducei wiode	I. WICO-E	•	ating will		TIS		TIB	
	Inde	x Label		MI	G	non-	scan		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Maxi	imum Index Valu	e		0.7	1.2				
	$p_{r,3}$	$p_{r,lpha}$	(MPa)	1.72					
	W_{o}	P	(mW)		296.70				
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	min of $[P\alpha(Zs),Ita,\alpha(Zs)]$	(mW)						
Associated	\mathbf{z}_1	Z_{s}	(cm)						
Acoustic	z_{bp}	$Z_{ m bp}$	(cm)						
Parameter	z_{sp}	Z_b	(cm)						
	Z@PII.3max	Z at max $I_{pi \alpha}$	(cm)	1.8					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	f_{awf}	(MHz)	5.26	5.34				
	Dim of A _{aprt}	Dim of A _{aprt}	X (cm)		1.22				
	Dilli Of A _{aprt}	Dilli Of Aaprt	Y (cm)		0.90				
	PD	$t_{\rm d}$	(µsec)	0.72					
	PRF	prr	(Hz)	6024					
	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	2.39					
Other	d _{eq} @PII _{max}	d _{eq} at max I _{pi}	(cm)						
Information			FL _x (cm)		0.21				
	Focal Length	Focal Length	FLy (cm)		0.34				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	94.75					
Operating	Mode	Mode	NA	С	С				
Control	Focus	Focus	(cm)	2.5	1				
Conditions	Power	Power	(%)	100	100				

Transducer Model: MC6-E Operating Mode: B+C+PW

		I. WICO-E	•	anng Moc		TIS		TIB	
	Inde	x Label		MI	G	non-	scan		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Max	imum Index Valu	ie		0.6			1.4	1.3	
	$p_{r.3}$	$p_{\mathrm{r},lpha}$	(MPa)	1.58					
	W_{o}	P	(mW)					204.29	
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	min of $[P\alpha(Zs),Ita,\alpha(Zs)]$	(mW)				104.65		
Associated	\mathbf{z}_1	Z_{s}	(cm)				1.8		
Acoustic	Z _{bp}	$Z_{ m bp}$	(cm)				1.6		
Parameter	Z_{sp}	Z_b	(cm)					1.8	
	Z@PII.3max	Z at max $I_{pi \alpha}$	(cm)	2.9					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)					0.70	
	f_c	$ m f_{awf}$	(MHz)	5.21			5.34	5.36	
	Dim of A _{aprt}	Dim of A _{aprt}	X (cm)				1.22	1.22	
	Dilli Of A _{aprt}	Dilli Of A _{aprt}	Y (cm)				0.90	0.90	
	PD	$t_{\rm d}$	(µsec)	0.50					
	PRF	prr	(Hz)	5924					
	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	2.40					
Other	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)					0.70	
Information			FL _x (cm)				0.30		
	Focal Length	Focal Length	FLy (cm)				0.28		
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	188.48					
Operating	Mode	Mode	NA	PW			PW	PW	
Control	Focus	Focus	(cm)	2.5			3.5	3.5	
Conditions	Power	Power	(%)	100			100	100	

Transducer Model: MC6-E Operating Mode: M

				uting miou		TIS		TIB	
	Inde	x Label		MI	Scan	non-	scan	non goon	TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Max	imum Index Valu	ie		0.6			1.2	1.8	
	$p_{r,3}$	$p_{r,\alpha}$	(MPa)	1.79					
	\mathbf{W}_{o}	P	(mW)					272.38	
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	min of $[P\alpha(Zs),Ita,\alpha(Zs)]$	(mW)				128.38		
Associated	z_1	Z_{s}	(cm)				2.0		
Acoustic	Z _{bp}	Z_{bp}	(cm)				1.8		
Parameter	Z _{sp}	Z_b	(cm)					2.0	
	z@PII _{.3max}	Z at max $I_{pi \alpha}$	(cm)	3.6					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)					0.78	
	f_c	$ m f_{awf}$	(MHz)	4.91			5.42	4.96	
	Dim of A _{aprt}	Dim of A _{aprt}	X (cm)				1.22	1.22	
	Dilli Of Aaprt	Dilli Of Aaprt	Y (cm)				0.90	0.90	
	PD	t _d	(µsec)	0.28					
	PRF	prr	(Hz)	11236					
	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	2.44					
Other	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)					0.65	
Information			FL _x (cm)				0.26		
	Focal Length	Focal Length	FLy (cm)				0.31		
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	180.80					
Operating	Mode	Mode	NA	M			M	M	
Control	Focus	Focus	(cm)	4			2	3.5	
Conditions	Power	Power	(%)	100			100	100	

Transducer Model: <u>V4-EV</u> Operating Mode: <u>B</u>

						TIS		TIB	
	Index	x Label		MI	Scan	non	-scan	non coon	TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Max	imum Index Valu	ue	_	0.7	1.1				
	$p_{r,3}$	$p_{\mathrm{r},\alpha}$	(MPa)	1.44					
	W_{o}	P	(mW)		532.48				
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	min of $[P\alpha(Zs),Ita,\alpha(Zs)]$	(mW)						
Associated	z_1	Z_{s}	(cm)						
Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	Z_{sp}	Z_{b}	(cm)						
	z@PII _{.3max}	Z at max $I_{pi \alpha}$	(cm)	3.2					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	$ m f_{awf}$	(MHz)	4.28	4.32				
	Dim of A _{aprt}	Dim of A _{aprt}	X (cm)		2.56				
	Dilli Of Taprt	Dim of Aaprt	Y (cm)		1.40				
	PD	t _d	(µsec)	0.44					
	PRF	prr	(Hz)	9255					
	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	2.25					
Other	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)						
Information	Es sal Laurath	Escal Laureth	FL _x (cm)		0.26				
	Focal Length	Focal Length	FLy (cm)		0.30				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	56.92					
Operating	Mode	Mode	NA	В	В				
Control	Focus	Focus	(cm)	4	2				
Conditions				100	100				

Transducer Model: <u>V4-EV</u> Operating Mode: <u>THI-B</u>

		<u> </u>		Turing IVI		TIS		TIB	
	Inde	x Label		MI	Scan	non	-scan	non goon	TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Max	imum Index Val	ue		0.7	1.3				
	$p_{r,3}$	$p_{r,\alpha}$	(MPa)	1.40					
	Wo	P	(mW)		532.48				
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	min of $[P\alpha(Zs),Ita,\alpha(Zs)]$	(mW)						
Associated	z_1	$Z_{\rm s}$	(cm)						
Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	Z_{sp}	Z_{b}	(cm)						
	Z@PII.3max	Z at max $I_{pi \alpha}$	(cm)	3.2					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	$ m f_{awf}$	(MHz)	4.26	4.30				
	Dim of A _{aprt}	Dim of A _{aprt}	X (cm)		2.56				
	Dilli Of A _{aprt}	Dilli Of Aaprt	Y (cm)		1.40				
	PD	t _d	(µsec)	0.44					
	PRF	prr	(Hz)	9259					
	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	2.25					
Other	d _{eq} @PII _{max}	d _{eq} at max I _{pi}	(cm)						
Information	Focal Length	Focal Length	FL _x (cm)		0.25				
	Tocal Length	rocar Length	FLy (cm)		0.30				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	56.89					
Operating	Mode	Mode	NA	THI-B	THI-B				
Control	Focus	Focus	(cm)	4	2				
Conditions	Power	Power	(%)	100	100				

Transducer Model: <u>V4-EV</u> Operating Mode: <u>B+C</u>

				8		TIS		TIB	
	Inde	x Label		MI	Scan	non-	scan	non coon	TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Max	imum Index Val	ue		0.5	0.5				
	$p_{r.3}$	$p_{r,\alpha}$	(MPa)	0.97					
	W_{o}	P	(mW)		306.00				
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	min of $[P\alpha(Zs),Ita,\alpha(Zs)]$	(mW)						
Associated	z_1	$Z_{\rm s}$	(cm)						
Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	Z_{sp}	Z_b	(cm)						
	Z@PII.3max	Z at max $I_{pi \alpha}$	(cm)	5.3					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	$ m f_{awf}$	(MHz)	3.59	4.33				
	Dim of A _{aprt}	Dim of A _{aprt}	X (cm)		2.56				
	Dilli Of A _{aprt}	Dim of Aaprt	Y (cm)		1.40				
	PD	t_d	(µsec)	1.10					
	PRF	prr	(Hz)	4532					
	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	1.25					
Other	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)						
Information	Focal Length	Eggal Langth	FL _x (cm)		0.24				
	rocai Length	Focal Length	FLy (cm)		0.34				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	38.22					
Operating	Mode	Mode	NA	С	С				
Control	Focus	Focus	(cm)	6	6				
Conditions	Power	Power	(%)	100	100				

Transducer Model: <u>V4-EV</u> Operating Mode: <u>B+C+PW</u>

			_	uting 1710		TIS		TIB	
	Inde	x Label		MI	G	non-	scan		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Max	imum Index Val	ue		0.4			1.1	1.0	
	p _{r.3}	$p_{r,\alpha}$	(MPa)	0.84					
	W_{o}	P	(mW)					596.00	
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	min of $[P\alpha(Zs),Ita,\alpha(Zs)]$	(mW)				244.00		
Associated	z_1	Z_{s}	(cm)				4.1		
Acoustic	Z _{bp}	Z_{bp}	(cm)				3.0		
Parameter	Z_{sp}	Z_{b}	(cm)					4.1	
	Z@PII _{.3max}	Z at max $I_{pi \alpha}$	(cm)	3.2					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)					1.10	
	f_c	$ m f_{awf}$	(MHz)	3.96			4.00	4.02	
	Dim of A _{aprt}	Dim of A _{aprt}	X (cm)				2.56	2.56	
	Dilli Of A _{aprt}	Dilli Of A _{aprt}	Y (cm)				1.40	1.40	
	PD	$t_{\rm d}$	(µsec)	1.26					
	PRF	prr	(Hz)	7845					
	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	1.16					
Other	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)					1.09	
Information	Focal Length	Focal Length	FL _x (cm)				0.24		
	Toom Dongill	Toom Bongui	FLy (cm)				0.34		
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	123.28					
Operating	Mode	Mode	NA	PW			PW	PW	
Control	Focus	Focus	(cm)	6			7	6	
Conditions	Power	Power	(%)	100			100	100	

Transducer Model: <u>V4-EV</u> Operating Mode: <u>M</u>

				uting 1110		TIS		TIB]
	Inde	x Label		MI	G	non-	-scan		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Max	imum Index Val	ue		0.7			1.0	1.0	
	p _{r.3}	$p_{\mathrm{r},\alpha}$	(MPa)	1.55					
	\mathbf{W}_{o}	P	(mW)					450.00	
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	min of $[P\alpha(Zs),Ita,\alpha(Zs)]$	(mW)				221.00		
Associated	\mathbf{z}_1	Z_{s}	(cm)				3.8		
Acoustic	Z _{bp}	Z_{bp}	(cm)				2.9		
Parameter	Z_{sp}	Z_b	(cm)					5.1	
	Z@PII _{.3max}	Z at max $I_{pi \alpha}$	(cm)	4.2					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)					0.85	
	f_c	f_{awf}	(MHz)	3.96			3.94	4.01	
	Dim of A _{aprt}	Dim of A _{aprt}	X (cm)				2.56	2.56	
	Dilli Of Aaprt	Dilli Of Aaprt	Y (cm)				1.40	1.40	
	PD	t_d	(µsec)	0.54					
	PRF	prr	(Hz)	4648					
	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	2.46					
Other	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)					0.72	
Information	Focal Length	Focal Length	FL _x (cm)				0.34		
			FLy (cm)				0.27		
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	102.00					
Operating	Mode	Mode	NA	M			M	M	
Control	Focus	Focus	(cm)	7			4	5	
Conditions							100	100	

Transducer Model: P3-E Operating Mode: B

						TIS		TIB	TENT.
	Inde	ex Label		MI	G	non-	scan		TI C
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Max	imum Index Valı	ue		1.2	1.7				
	$p_{r.3}$	$p_{\mathrm{r},\alpha}$	(MPa)	1.84					
	\mathbf{W}_{o}	P	(mW)		269.95				
	min of	min of							
	$[W_{.3}(z_1),$	[Pα(Zs),Ita,α(Z	(mW)						
	$I_{TA.3}(z_1)$	s)]							
Associated	z_1	$Z_{\rm s}$	(cm)						
Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	z_{sp}	Z_b	(cm)						
	z@PII _{.3max}	Z at max $I_{pi\alpha}$	(cm)	4.5					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	$ m f_{awf}$	(MHz)	2.28	2.38				
	Dim of A	Dim of A	X (cm)		1.92				
	Dim of A _{aprt}	Dim of A _{aprt}	Y (cm)		1.58				
	PD	$t_{\rm d}$	(µsec)	0.97					
	PRF	prr	(Hz)	3337.5					
Other	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	3.83					
Informatio	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)						
n	Feed Lend	Escal Land	FL_{x} (cm)		0.32				
	Focal Length	Focal Length	FLy (cm)		0.24				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	98.54					
Operating	Mode	Mode	NA	В	В				
Control	Focus	Focus	(cm)	4	1				
Conditions	Power	Power	(%)	100	100				

Transducer Model: <u>P3-E</u> Operating Mode: <u>THI-B</u>

				<u> </u>		TIS		TIB	TENT.
	In	dex Label		MI	G.	non-	scan		TI C
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Max	imum Index Val	ue		1.2	1.5				
	p _{r.3}	$p_{r,\alpha}$	(MPa)	1.76					
	W_{o}	P	(mW)		269.95				
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	$\begin{array}{c} \text{min of} \\ [P\alpha(Zs),Ita,\alpha(Zs)] \end{array}$	(mW)						
Associated	z_1	Z_{s}	(cm)						
Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	Z_{sp}	Z_b	(cm)						
	Z@PII.3max	Z at max $I_{pi \alpha}$	(cm)	4.5					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	f_{awf}	(MHz)	2.25	2.44				
	Dim of A _{aprt}	Dim of A _{aprt}	X (cm) Y (cm)		1.92 1.58				
	PD	t _d	(µsec)	0.97					
	PRF	prr	(Hz)	3336					
	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	3.83					
Other	d _{eq} @PII _{max}	d _{eq} at max I _{pi}	(cm)						
Information	Focal Length	Focal Length	FL_{x} (cm)		0.36				
			FLy (cm)		0.22				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	98.50					
Operating	Mode	Mode	NA	THI-B	THI-B				
Control	Focus	Focus	(cm)	4	1				
Conditions	Power	Power	(%)	100	100				

Transducer Model: <u>P3-E</u> Operating Mode: <u>B+C</u>

	iisuucci wiouc			Ing Wout		TIS		TIB	
	Inde	ex Label		MI	G.	non-s	scan		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Max	imum Index Valı	ıe		0.9	0.5				
	$p_{r.3}$	$p_{r,\alpha}$	(MPa)	1.35					
	\mathbf{W}_{o}	P	(mW)		92.18				
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	min of $[P\alpha(Zs),Ita,\alpha(Zs)]$	(mW)						
Associated	\mathbf{z}_1	Z_{s}	(cm)						
Acoustic	z_{bp}	Z_{bp}	(cm)						
Parameter	z_{sp}	Z_b	(cm)						
	Z@PII.3max	Z at max $I_{pi \alpha}$	(cm)	3.6					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	f_{awf}	(MHz)	2.25	2.29				
	Dim of A _{aprt}	Dim of A _{aprt}	X (cm)		1.92				
	Dilli Of A _{aprt}	Dilli Of A _{aprt}	Y (cm)		1.58				
	PD	$t_{\rm d}$	(µsec)	1.69					
	PRF	prr	(Hz)	5948					
Other	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	1.76					
Informatio	d _{eq} @PII _{max}	d _{eq} at max I _{pi}	(cm)						
n	Food Longth	Focal Length	FL _x (cm)		0.27				
	Focal Length	rocai Lengui	FLy (cm)		0.32				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	57.36					
Operating	Mode	Mode	NA	С	С				
Control	Focus	Focus	(cm)	4	1				
Conditions	Power	Power	(%)	100	100				

Transducer Model: P3-E Operating Mode: B+C+PW

			-	ing Would		TIS		TIB	
	Index	k Label		MI	G	non-s	scan		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Max	imum Index Value	,		0.8			0.5	1.2	
	$p_{r,3}$	$p_{r,\alpha}$	(MPa)	1.25					
	W_{o}	P	(mW)					122.88	
	min of $[W_{.3}(z_1), I_{TA.3}(z_1)]$	min of $[P\alpha(Zs),Ita,\alpha(Zs)]$	(mW)				80.74		
	z_1	Z_{s}	(cm)				3.1		
Associated	Z _{bp}	Z_{bp}	(cm)				2.9		
Acoustic Parameter	z_{sp}	Z_b	(cm)					5.4	
rarameter	Z@PII _{.3max}	Z at max $I_{pi \alpha}$	(cm)	6.0					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)					0.40	
	f_{c}	f_{awf}	(MHz)	1.99			1.98	1.99	
	Dim of A _{aprt}	Dim of A _{aprt}	X (cm)				1.92	1.92	
	Dilli Of A _{aprt}	Dilli Of A _{aprt}	Y (cm)				1.58	1.58	
	PD	$t_{\rm d}$	(µsec)	1.83					
	PRF	prr	(Hz)	5049					
	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	1.81					
Other	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)					0.40	
Information	Focal Length	Focal Length	FL _x (cm)				0.32		
	rocai Lengui	rocar Length	FLy (cm)				0.39		
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	150.40					
Operating	Mode	Mode	NA	PW			PW	PW	
Control	Focus	Focus	(cm)	1			1	1	
Conditions	Power	Power	(%)	100			100	100	

Transducer Model: <u>P3-E</u> Operating Mode: <u>M</u>

	ansuucei wiout		•	ing wide		TIS		TIB	
	Index	Label		MI	G.	non-s	scan		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Max	imum Index Value	:		1.2			0.8	1.4	
	$p_{r,3}$	$p_{r,\alpha}$	(MPa)	1.64					
	W_{o}	P	(mW)					89.20	
	min of $[W_{.3}(z_1),$ $I_{TA.3}(z_1)]$	min of $[P\alpha(Zs),Ita,\alpha(Zs)]$	(mW)				30.72		
	z_1	Z_{s}	(cm)				2.9		
Associated	Z _{bp}	Z_{bp}	(cm)				2.9		
Acoustic	\mathbf{z}_{sp}	Z_b	(cm)					2.9	
Parameter	z@PII _{.3max}	Z at max $I_{pi \alpha}$	(cm)	2.6					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)					0.44	
	f_c	f_{awf}	(MHz)	1.88			1.89	1.88	
	Dim of A _{aprt}	Dim of A _{aprt}	X (cm)				1.92	1.92	
	Dilli Of A _{aprt}	Dilli Of Aaprt	Y (cm)				1.58	1.58	
	PD	$t_{ m d}$	(µsec)	0.45					
	PRF	prr	(Hz)	5543					
	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	1.59					
Other	d _{eq} @PII _{max}	d _{eq} at max I _{pi}	(cm)					0.33	
Information	Focal Length	Focal Length	FL _x (cm)				0.28		
	rocai Length	rocai Length	FLy (cm)				0.34		
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	189.20					
Operating	Mode	Mode	NA	M			M	M	
Control	Focus	Focus	(cm)	5			5	6	
Conditions	Power	Power	(%)	100			100	100	

Transducer Model: P3-E Operating Mode: B+C+CW

			_	111000		TIS		TIB	
	Index	x Label		MI	G	non-s	scan		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Max	imum Index Valı	ıe		0.3			0.7	1.7	1.0
	$p_{r.3}$	$p_{r,\alpha}$	(MPa)	0.42					
	\mathbf{W}_{o}	P	(mW)					178.00	172.00
	min of	min of							
	$[W_{.3}(z_1),$	[Pα(Zs),Ita,α(Z	(mW)				79.00		
	$I_{TA.3}(z_1)$	s)]							
Associated	\mathbf{z}_1	Z_{s}	(cm)				5.4		
Acoustic	Z_{bp}	$Z_{ m bp}$	(cm)				2.0		
Parameter	z_{sp}	Z_b	(cm)					6.7	
	Z@PII.3max	Z at max I _{pi α}	(cm)	6.8					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)					0.80	
	f_c	$f_{ m awf}$	(MHz)	2.65			2.75	2.70	2.75
	Dim of A	Dim of A	X (cm)				1.92	1.92	1.92
	Dim of A _{aprt}	Dim of A _{aprt}	Y (cm)				1.58	1.58	1.58
	PD	$t_{\rm d}$	(µsec)	26.00					
	PRF	prr	(Hz)	0					
Other	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	0.12					
Informatio	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)					0.81	
n	Essal I susath	Es sal I an ath	FL _x (cm)				0.42		0.43
	Focal Length	Focal Length	FLy (cm)				0.32		0.30
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	38.96					
Operating	Mode	Mode	NA	CW			CW	CW	CW
Control	Focus	Focus	(cm)	3			5	6	6
Conditions	Power	Power	(%)	100			100	100	100

Transducer Model: P3-E Operating Mode: CFM-M

						TIS		TIB	
	Index	Label		MI	Casa	non-	scan		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Max	imum Index Value			1.1			0.1	0.8	
	$p_{r.3}$	$p_{r,\alpha}$	(MPa)	1.51					
	W_{o}	P	(mW)					254.00	
	$\begin{aligned} & \text{min of } [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	min of $[P\alpha(Zs),Ita,\alpha(Zs)]$	(mW)				12.49		
	\mathbf{z}_1	Z_{s}	(cm)				6.1		
Associated	Z _{bp}	Z_{bp}	(cm)				2.8		
Acoustic Parameter	Z_{sp}	Z_b	(cm)					6.2	
1 arameter	Z@PII _{.3max}	Z at max I _{pi α}	(cm)	6.1					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)					3.08	
	$f_{\rm c}$	f_{awf}	(MHz)	2.36			2.36	2.35	
	Dim of A	Dim of A	X (cm)				1.92	1.92	
	Dim of A _{aprt}	Dim of A _{aprt}	Y (cm)				1.58	1.58	
	PD	$t_{\rm d}$	(µsec)	0.71					
	PRF	prr	(Hz)	200					
	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	2.61					
Other	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)					3.01	
Information	Focal Length	Focal Length	FL _x (cm)				0.42		
	Focal Length	rocal Length	FLy (cm)				0.54		
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	82.33					
Operating	Mode	Mode	NA	CFM-M			CFM-M	CFM-M	
Control	Focus	Focus	(cm)	4			5	6	
Conditions	Power	Power	(%)	100			100	100	

Transducer Model: <u>P2-E</u> Operating Mode: <u>B</u>

						TIS		TIB	
	Inde	x Label		MI		non-	scan]	TIC
		z zuwei		1,11	Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	110
Global Maxi	mum Index Va	alue		1.3	1.2				
	$p_{r.3}$	р _{г, а}	(MPa)	1.74					
	Wo	P	(mW)		256.82				
	min of	min of							
	$[W_{.3}(z_1),$	$[P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)$	(mW)						
	$I_{TA.3}(z_1)$]							
Associated	z_1	Z_{s}	(cm)						
Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	z_{sp}	Z_b	(cm)						
	Z@PII.3max	Z at max $I_{pi \alpha}$	(cm)	4.5					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	$f_{ m awf}$	(MHz)	1.89	1.78				
	Dim of A	Dim of A	X (cm)		1.92				
	Dim of A _{aprt}	Dim of A _{aprt}	Y (cm)		1.40				
	PD	$t_{\rm d}$	(µsec)	0.95					
	PRF	prr	(Hz)	3058.9					
	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	3.25					
Other	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)						
Information	Focal	Focal Length	FL _x (cm)		2.26				
	Length	Focal Length	FLy (cm)		2.19				
	I _{PA.3} @	I _{pi} at max MI	(W/cm ²)	89.72					
	MI_{max}	I _{pi} at max wn	(W/CIII)	09.12					
Operating	Mode	Mode	NA	В	В				
Control	Focus	Focus	(cm)	9	4				
Conditions	Power	Power	(%)	100	100				

⁽b) This probe is not intended for transcranial or neonatal cephalic uses.

⁽c) This formulation for TIS is less than that for an alternate formulation in this mode.

[#] No data are reported for this operating condition since the global maximum index value is not reported for the reason listed.

Transducer Model: <u>P2-E</u> Operating Mode: <u>THI-B</u>

						TIS		TIB	
	Inde	x Label		MI		non-	scan		TIC
	muc	a Zuloci		1122	Scan	$A_{aprt} \leq 1$	A _{aprt} >1	non-scan	
Global Maxi	mum Index V	alue		1.2	1.3				
	$p_{r.3}$	$p_{r,^{lpha}}$	(MPa)	1.63					
	W_{o}	P	(mW)		256.76				
	min of [W _{.3} (z ₁), I _{TA.3} (z ₁)]	$\begin{aligned} & \text{min of} \\ & & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)						
Associated	z_1	$Z_{\rm s}$	(cm)						
Acoustic	z _{bp}	Z_{bp}	(cm)						
Parameter	z_{sp}	Z_{b}	(cm)						
	z@PII _{.3max}	Z at max $I_{pi\alpha}$	(cm)	4.5					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	$f_{ m awf}$	(MHz)	1.85	1.78				
	Dim of	Dim of A _{aprt}	X (cm)		1.92				
	A_{aprt}	Dilli Of Aaprt	Y (cm)		1.40				
	PD	t_d	(µsec)	0.95					
	PRF	prr	(Hz)	3058.9					
	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	3.25					
Other	d _{eq} @PII _{max}	d _{eq} at max I _{pi}	(cm)						
Information	Focal		FL _x (cm)		1.98				
	Length	Focal Length	FLy (cm)		2.05				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	89.63					
Operating	Mode	Mode	NA	THI-B	THI-B				
Control	Focus	Focus	(cm)	9	4				
Conditions				100	100				

⁽b) This probe is not intended for transcranial or neonatal cephalic uses.

⁽c) This formulation for TIS is less than that for an alternate formulation in this mode.

[#] No data are reported for this operating condition since the global maximum index value is not reported for the reason listed.

Transducer Model: <u>P2-E</u> Operating Mode: <u>B+C</u>

						TIS		TIB	
	Inde	x Label		MI		non-	scan		TIC
	muc	a Zuoci		1122	Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Max	imum Index V	'alue		0.6	0.7				
	$p_{r.3}$	$p_{r,^{lpha}}$	(MPa)	0.79					
	W_{o}	P	(mW)		79.53				
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	$\begin{aligned} & \text{min of} \\ & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)						
Associated	z_1	Z_{s}	(cm)						
Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	z_{sp}	Z_b	(cm)						
	z@PII _{.3max}	Z at max $I_{pi\alpha}$	(cm)	4.5					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	f_{awf}	(MHz)	1.74	1.86				
	Dim of	Dim of A _{aprt}	X (cm)		1.92				
	A _{aprt}	Dilli Of Aaprt	Y (cm)		1.40				
	PD	$t_{\rm d}$	(µsec)	1.2					
	PRF	prr	(Hz)	5422					
	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	1.04					
Other	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)						
Information	Focal		FL _x (cm)		1.29				
	Length	Focal Length	FLy (cm)		1.31				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	26.05					
Operating	Mode	Mode	NA	С	С				
Control	Focus	Focus	(cm)	4	3				
Conditions	Power	Power	(%)	100	100				

⁽b) This probe is not intended for transcranial or neonatal cephalic uses.

⁽c) This formulation for TIS is less than that for an alternate formulation in this mode.

[#] No data are reported for this operating condition since the global maximum index value is not reported for the reason listed.

Transducer Model: P2-E Operating Mode: B+C+PW

						TIS		TIB	
	Inde	x Label		MI		non-	scan		TIC
	THU.	a Zuoci		1,11	Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Maxi	imum Index V	'alue		0.6			0.6	0.9	
	p _{r.3}	$p_{r,^{\scriptscriptstyle{lpha}}}$	(MPa)	0.79					
	Wo	P	(mW)					108.60	
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	$\begin{aligned} & \text{min of} \\ & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)				72.66		
Associated	\mathbf{z}_1	Z_{s}	(cm)				2.4		
Acoustic	Z _{bp}	Z_{bp}	(cm)				2.8		
Parameter	\mathbf{z}_{sp}	Z_b	(cm)					4.2	
	z@PII _{.3max}	Z at max $I_{pi\alpha}$	(cm)	5.6					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)					0.32	
	f_c	f_{awf}	(MHz)	1.75			1.84	1.78	
	Dim of	Dim of A _{aprt}	X (cm)				1.92	1.92	
	A_{aprt}	Dilli Of Aaprt	Y (cm)				1.40	1.40	
	PD	$t_{\rm d}$	(µsec)	1.5					
	PRF	prr	(Hz)	4722.9					
	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	1.52					
Other	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)					0.35	
Information	Focal		FL _x (cm)				1.25		
mormation	Length	Focal Length	FLy (cm)				1.28		
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	135.72					
Operating	Mode	Mode	NA	PW			PW	PW	
Control	Focus	Focus	(cm)	1			5	5	
Conditions	Power	Power	(%)	100			100	100	

⁽b) This probe is not intended for transcranial or neonatal cephalic uses.

⁽c) This formulation for TIS is less than that for an alternate formulation in this mode.

[#] No data are reported for this operating condition since the global maximum index value is not reported for the reason listed.

Transducer Model: <u>P2-E</u> Operating Mode: <u>M</u>

						TIS		TIB	
	Inde	x Label		MI		non-	scan		TIC
	muc	A Label		1411	Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	110
Global Maxi	mum Index V	alue		0.9			0.7	1.0	
	p _{r.3}	$p_{r,^{lpha}}$	(MPa)	1.23					
	W_{o}	P	(mW)					78.51	
	min of [W _{.3} (z ₁), I _{TA.3} (z ₁)]	$\begin{aligned} & \text{min of} \\ & & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)				28.3		
Associated	z_1	Z_{s}	(cm)				2.8		
Acoustic	z _{bp}	Z_{bp}	(cm)				2.7		
Parameter	z_{sp}	Z_{b}	(cm)					2.9	
	z@PII _{.3max}	Z at max $I_{pi\alpha}$	(cm)	2.5					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)					0.44	
	f_c	$f_{ m awf}$	(MHz)	1.89			1.88	1.88	
	Dim of	Dim of A _{aprt}	X (cm)				1.92	1.92	
	A _{aprt}	Dilli Of Aaprt	Y (cm)				1.40	1.40	
	PD	t_d	(µsec)	0.45					
	PRF	prr	(Hz)	5233.6					
	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	1.59					
Other	d _{eq} @PII _{max}	d _{eq} at max I _{pi}	(cm)					0.32	
Information	Focal		FL_{x} (cm)				1.45		
	Length	Focal Length	FLy (cm)				1.38		
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	129.21					
Operating	Mode	Mode	NA	M			M	M	
Control	Focus	Focus	(cm)	5			5	6	
Conditions	Power	Power	(%)	100			100	100	

⁽b) This probe is not intended for transcranial or neonatal cephalic uses.

⁽c) This formulation for TIS is less than that for an alternate formulation in this mode.

[#] No data are reported for this operating condition since the global maximum index value is not reported for the reason listed.

Transducer Model: P2-E Operating Mode: B+C+CW

						TIS		TIB	
	Inde	x Label		MI		non-	scan		TIC
	THU.	a Buser		1122	Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Maxi	i mum Index V	alue		0.1			0.8	1.8	0.6
	$p_{r.3}$	$p_{r,^{lpha}}$	(MPa)	0.15					
	W_{o}	P	(mW)					178.00	170.00
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	$\begin{aligned} & \text{min of} \\ & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)				84.42		
Associated	\mathbf{z}_1	Z_{s}	(cm)				5.4		
Acoustic	Z _{bp}	Z_{bp}	(cm)				2.0		
Parameter	z_{sp}	Z_b	(cm)					6.7	
	z@PII _{.3max}	Z at max $I_{pi\alpha}$	(cm)	6.8					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)					0.8	
	f_c	f_{awf}	(MHz)	2.22			2.48	2.32	2.25
	Dim of	Dim of A _{aprt}	X (cm)				1.92	1.92	1.92
	A_{aprt}	Dilli Of A _{aprt}	Y (cm)				1.40	1.40	1.40
	PD	t_d	(µsec)	20					
	PRF	prr	(Hz)	0					
	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	0.9					
Other	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)					0.79	
Information	Focal		FL _x (cm)				1.44		1.36
mormation	Length	Focal Length	FLy (cm)				1.45		1.39
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	43.25					
Operating	Mode	Mode	NA	CW			CW	CW	CW
Control	Focus	Focus	(cm)	4			5	4	4
Conditions	Power	Power	(%)	100			100	100	100

⁽b) This probe is not intended for transcranial or neonatal cephalic uses.

⁽c) This formulation for TIS is less than that for an alternate formulation in this mode.

[#] No data are reported for this operating condition since the global maximum index value is not reported for the reason listed.

Transducer Model: P2-E Operating Mode: CFM-M

						TIS		TIB	_
	Inde	x Label		MI		non-	scan		TIC
	muc	a Dubel		1,11	Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	110
Global Maxi	imum Index V	alue		1.0			0.1	0.7	
	p _{r.3}	$p_{r,^{lpha}}$	(MPa)	1.63					
	\mathbf{W}_{o}	P	(mW)					254.01	
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	$\begin{aligned} & \text{min of} \\ & & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)				12.49		
Associated	\mathbf{z}_1	Z_{s}	(cm)				6.1		
Acoustic	Z _{bp}	Z_{bp}	(cm)				2.7		
Parameter	Z_{sp}	Z_b	(cm)					6.1	
	z@PII _{.3max}	Z at max $I_{pi\alpha}$	(cm)	6.1					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)					3.08	
	f_c	$f_{ m awf}$	(MHz)	2.34			2.31	2.25	
	Dim of	Dim of A _{aprt}	X (cm)				1.92	1.92	
	A_{aprt}	Dim of Frapri	Y (cm)				1.40	1.40	
	PD	t _d	(µsec)	0.71					
	PRF	prr	(Hz)	220					
	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	2.63					
Other	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)					3.01	
Information	Focal		FL _x (cm)				1.25		
	Length	Focal Length	FLy (cm)				1.22		
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	79.46					
Operating	Mode	Mode	NA	CFM-M			CFM-M	CFM-M	
Control	Focus	Focus	(cm)	5			5	5	
Conditions	Power	Power	(%)	100			100	100	

⁽b) This probe is not intended for transcranial or neonatal cephalic uses.

⁽c) This formulation for TIS is less than that for an alternate formulation in this mode.

[#] No data are reported for this operating condition since the global maximum index value is not reported for the reason listed.

Transducer Model: <u>P2-ES</u> Operating Mode: <u>B</u>

					1,1000.	TIS		TIB	
	Indo	x Label		MI		non-	scan		TIC
	mue	x Labei		IVII	Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	TIC
Global Maxi	mum Index Va	alue		1.3	1.2				
	p _{r.3}	$p_{r,^{\scriptscriptstyle{lpha}}}$	(MPa)	1.74					
	W_{o}	P	(mW)		256.82				
	min of	min of							
	$[W_{.3}(z_1),$	$[P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)$	(mW)						
	$I_{TA.3}(z_1)$]							
Associated	\mathbf{z}_1	Z_{s}	(cm)						
Acoustic	z_{bp}	Z_{bp}	(cm)						
Parameter	Z_{sp}	Z_b	(cm)						
	z@PII _{.3max}	Z at max $I_{pi \alpha}$	(cm)	4.5					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	$f_{ m awf}$	(MHz)	1.89	1.78				
	D: f A	Dim of A	X (cm)		1.92				
	Dim of A _{aprt}	Dim of A _{aprt}	Y (cm)		1.40				
	PD	t _d	(µsec)	0.95					
	PRF	prr	(Hz)	3058.9					
	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	3.25					
Other	d _{eq} @PII _{max}	d _{eq} at max I _{pi}	(cm)						
Information	Focal		FL _x (cm)		2.26				
	Length	Focal Length	FLy (cm)		2.19				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	89.72					
Operating	Mode	Mode	NA	В	В				
Control	Focus	Focus	(cm)	9	4				
Conditions	Power	Power	(%)	100	100				

Transducer Model: P2-ES Operating Mode: THI-B

		<u> 12 15 </u>			, 1/10de/ <u>1</u> /	TIS		TIB	
	Indo	x Label		MI		non-	scan		TIC
	mue	x Label		1711	Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	TIC
Global Maxi	imum Index V	alue		1.2	1.3				
	p _{r.3}	$p_{r,^{lpha}}$	(MPa)	1.63					
	W_{o}	P	(mW)		256.76				
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	$\begin{aligned} & \text{min of} \\ & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)						
Associated	z_1	Z_{s}	(cm)						
Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	z_{sp}	Z_b	(cm)						
	z@PII _{.3max}	Z at max $I_{pi\alpha}$	(cm)	4.5					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	f_{awf}	(MHz)	1.85	1.78				
	Dim of	Dim of A _{aprt}	X (cm)		1.92				
	A_{aprt}	Dilli Of Aaprt	Y (cm)		1.40				
	PD	t_d	(µsec)	0.95					
	PRF	prr	(Hz)	3058.9					
	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	3.25					
Other	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)						
Information	Focal		FL _x (cm)		1.98				
imornation	Length	Focal Length	FLy (cm)		2.05				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	89.63					
Operating	Mode	Mode	NA	THI-B	THI-B				
Control	Focus	Focus	(cm)	9	4				
Conditions	Power	Power	(%)	100	100				

Transducer Model: P2-ES Operating Mode: B+C

					, 110ac. <u>D</u>	TIS		TIB	
	Indo	x Label		MI		non-	scan		TIC
	mue.	x Labei		IVII	Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Maxi	imum Index V	'alue		0.6	0.7				
	p _{r.3}	$p_{r,^{\scriptscriptstyle{lpha}}}$	(MPa)	0.79					
	\mathbf{W}_{o}	P	(mW)		79.53				
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	$\begin{aligned} & \text{min of} \\ & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)						
Associated	z_1	Z_{s}	(cm)						
Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	Z_{sp}	Z_b	(cm)						
	z@PII _{.3max}	Z at max $I_{pi\alpha}$	(cm)	4.5					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	f_{awf}	(MHz)	1.74	1.86				
	Dim of	Dim of A _{aprt}	X (cm)		1.92				
	A_{aprt}	Dilli Of Aaprt	Y (cm)		1.40				
	PD	t_d	(µsec)	1.2					
	PRF	prr	(Hz)	5422					
	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	1.04					
Other	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)						
Information	Focal		FL _x (cm)		1.29				
	Length	Focal Length	FLy (cm)		1.31				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	26.05					
Operating	Mode	Mode	NA	С	С				
Control	Focus	Focus	(cm)	4	3				
Conditions				100	100				

Transducer Model: P2-ES Operating Mode: B+C+PW

		1225			, 1110uc. <u>D</u>	TIS		TIB	
	Inde	x Label		MI		non-	scan		TIC
	muc.	a Lauci		1711	Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Maxi	imum Index V	alue		0.6			0.6	0.9	
	p _{r.3}	$p_{r,^{\scriptscriptstyle{lpha}}}$	(MPa)	0.79					
	W_{o}	P	(mW)					108.60	
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	$\begin{aligned} & \text{min of} \\ & & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)				72.66		
Associated	z_1	Z_{s}	(cm)				2.4		
Acoustic	Z _{bp}	Z_{bp}	(cm)				2.8		
Parameter	Z_{sp}	Z_b	(cm)					4.2	
	z@PII _{.3max}	Z at max $I_{pi\alpha}$	(cm)	5.6					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)					0.32	
	f_c	$f_{ m awf}$	(MHz)	1.75			1.84	1.78	
	Dim of	Dim of A _{aprt}	X (cm)				1.92	1.92	
	A_{aprt}	Dilli Of Aaprt	Y (cm)				1.40	1.40	
	PD	t _d	(µsec)	1.5					
	PRF	prr	(Hz)	4722.9					
	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	1.52					
Other	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)					0.35	
Information	Focal		FL _x (cm)				1.25		
imornation	Length	Focal Length	FLy (cm)				1.28		
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	135.72					
Operating	Mode	Mode	NA	PW			PW	PW	
Control	Focus	Focus	(cm)	1			5	5	
Conditions	Power	Power	(%)	100			100	100	

Transducer Model: <u>P2-ES</u> Operating Mode: <u>M</u>

						TIS		TIB	
	Inde	x Label		MI		non-	scan		TIC
	muc.	a Lauci		1711	Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Max	imum Index V	alue		0.9			0.7	1.0	
	$p_{r.3}$	$p_{r,^{lpha}}$	(MPa)	1.23					
	W_{o}	P	(mW)					78.51	
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	$\begin{aligned} & \text{min of} \\ & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)				28.3		
Associated	z_1	Z_{s}	(cm)				2.8		
Acoustic	Z _{bp}	Z_{bp}	(cm)				2.7		
Parameter	Z _{sp}	Z_b	(cm)					2.9	
	Z@PII.3max	Z at max $I_{pi\alpha}$	(cm)	2.5					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)					0.44	
	f_c	f_{awf}	(MHz)	1.89			1.88	1.88	
	Dim of	Dim of A _{aprt}	X (cm)				1.92	1.92	
	A _{aprt}	Dilli Of Aaprt	Y (cm)				1.40	1.40	
	PD	t _d	(µsec)	0.45					
	PRF	prr	(Hz)	5233.6					
	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	1.59					
Other	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)					0.32	
Information	Focal		FL _x (cm)				1.45		
	Length	Focal Length	FLy (cm)				1.38		
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	129.21					
Operating	Mode	Mode	NA	M			M	M	
Control	Focus	Focus	(cm)	5			5	6	
Conditions	Power	Power	(%)	100			100	100	

Transducer Model: P2-ES Operating Mode: B+C+CW

		<u> 12 25 </u>			, 1/10 uc.<u>D</u>	TIS		TIB	
	Inde	x Label		MI		non-	scan		TIC
	muc.	A Lauci		1411	Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	110
Global Maxi	imum Index V	'alue		0.1			0.8	1.8	0.6
	p _{r.3}	$p_{r,^{\scriptscriptstyle{lpha}}}$	(MPa)	0.15					
	W_{o}	P	(mW)					178.00	170.00
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	$\begin{aligned} & \text{min of} \\ & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)				84.42		
Associated	z_1	Z_{s}	(cm)				5.4		
Acoustic	Z _{bp}	Z_{bp}	(cm)				2.0		
Parameter	z_{sp}	Z_b	(cm)					6.7	
	z@PII _{.3max}	Z at max $I_{pi\alpha}$	(cm)	6.8					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)					0.8	
	f_c	f_{awf}	(MHz)	2.22			2.48	2.32	2.25
	Dim of	Dim of A _{aprt}	X (cm)				1.92	1.92	1.92
	A _{aprt}	Dilli Of Aaprt	Y (cm)				1.40	1.40	1.40
	PD	t _d	(µsec)	20					
	PRF	prr	(Hz)	0					
	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	0.9					
Other	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)					0.79	
Information	Focal		FL _x (cm)				1.44		1.36
	Length	Focal Length	FLy (cm)				1.45		1.39
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	43.25					
Operating	Mode	Mode	NA	CW			CW	CW	CW
Control	Focus	Focus	(cm)	4			5	4	4
Conditions	Power	Power	(%)	100			100	100	100

Transducer Model: P2-ES Operating Mode: CFM-M

		1215			, 1/10 uc. _ <u>c</u>	TIS		TIB	
	Inde	x Label		MI		non-	scan		TIC
	muc.	A Lauci		1711	Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	110
Global Maxi	imum Index V	'alue		1.0			0.1	0.7	
	p _{r.3}	$p_{r,^{lpha}}$	(MPa)	1.63					
	\mathbf{W}_{o}	P	(mW)					254.01	
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	$\begin{aligned} & \text{min of} \\ & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)				12.49		
Associated	z_1	Z_{s}	(cm)				6.1		
Acoustic	z _{bp}	Z_{bp}	(cm)				2.7		
Parameter	z_{sp}	Z_b	(cm)					6.1	
	z@PII _{.3max}	Z at max $I_{pi\alpha}$	(cm)	6.1					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)					3.08	
	f_c	f_{awf}	(MHz)	2.34			2.31	2.25	
	Dim of	Dim of A _{aprt}	X (cm)				1.92	1.92	
	A _{aprt}	Dilli Of Aaprt	Y (cm)				1.40	1.40	
	PD	t _d	(µsec)	0.71					
	PRF	prr	(Hz)	220					
	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	2.63					
Other	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)					3.01	
Information	Focal		FL _x (cm)				1.25		
	Length	Focal Length	FLy (cm)				1.22		
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	79.46					
Operating	Mode	Mode	NA	CFM-M			CFM-M	CFM-M	
Control	Focus	Focus	(cm)	5			5	5	
Conditions	Power	Power	(%)	100			100	100	

Transducer Model: <u>L12-E</u> Operating Mode: <u>B</u>

	ansuucei wiouc		•	ating Mo		TIS		TIB	
	Index	Label		MI	Caam	non-s	can		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Max	imum Index Value	:	_	0.6	0.1				
	$p_{r,3}$	$p_{r,\alpha}$	(MPa)	1.39					
	Wo	P	(mW)		8.19				
	$\begin{aligned} & \text{min of } [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	min of $[P\alpha(Zs),Ita,\alpha(Zs)]$	(mW)						
	z_1	Z_{s}	(cm)						
Associated	z_{bp}	Z_{bp}	(cm)						
Acoustic Parameter	z_{sp}	Z_b	(cm)						
rarameter	Z@PII _{.3max}	Z at max $I_{pi \alpha}$	(cm)	1.8					
	$d_{eq}(z_{sp})$	$d_{eq}\left(Z_{b}\right)$	(cm)						
	$f_{\rm c}$	f_{awf}	(MHz)	5.91	5.91				
	Dim of A _{aprt}	Dim of A _{aprt}	X (cm)		2.05				
	Dilli Of Aaprt	Dilli Of A _{aprt}	Y (cm)		0.45				
	PD	$t_{ m d}$	(µsec)	0.23					
	PRF	prr	(Hz)	5319					
	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	2.03					
Other	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)						
Information	Focal Length	Focal Length	FL _x (cm)		0.33				
	rocai Lengui	rocai Lengui	FLy (cm)		0.24				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	84.56					
Operating	Mode	Mode	NA	В	В				
Control	Focus	Focus	(cm)	2.5	2.5				
Conditions	Power	Power	(%)	100	100				

Transducer Model: <u>L12-E</u> Operating Mode: <u>THI-B</u>

	ansuucei wiouc		•		. <u>1111-D</u>	TIS		TIB	
	Index	Label		MI	G	non-s	can		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Max	imum Index Value	}		0.6	0.1				
	$p_{r,3}$	$p_{r,\alpha}$	(MPa)	1.39					
	Wo	P	(mW)		8.19				
	min of $[W_{.3}(z_1), I_{TA.3}(z_1)]$	$\begin{aligned} & \text{min of} \\ & [P\alpha(Zs),Ita,\alpha(Zs)] \end{aligned}$	(mW)						
	\mathbf{z}_1	$Z_{\rm s}$	(cm)						
Associated	z _{bp}	Z_{bp}	(cm)						
Acoustic Parameter	z_{sp}	Z_b	(cm)						
Tarameter	Z@PII _{.3max}	Z at max $I_{pi \alpha}$	(cm)	1.8					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_{c}	f_{awf}	(MHz)	5.89	5.90				
	Dim of A _{aprt}	Dim of A _{aprt}	X (cm)		2.05				
	Dilli Of Aaprt	Dilli Of Aaprt	Y (cm)		0.45				
	PD	t _d	(µsec)	0.23					
	PRF	prr	(Hz)	5319					
	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	2.03					
Other	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)						
Information	Focal Length	Focal Length	FL _x (cm)		0.33				
	rocai Lengui	Tocal Length	FLy (cm)		0.22				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	84.49					
Operating	Mode	Mode	NA	THI-B	THI-B				
Control	Focus	Focus	(cm)	2.5	2.5				
Conditions	Power	Power	(%)	100	100				

Transducer Model: <u>L12-E</u> Operating Mode: <u>B+C</u>

			-	ating Will		TIS		TIB	
	Index	Label		MI	C	non-s	can		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Maxi	imum Index Value	:		0.5	0.4				
	$p_{r.3}$	$p_{r,\alpha}$	(MPa)	1.18					
	W_{o}	P	(mW)		57.34				
	min of $[W_{.3}(z_1), I_{TA.3}(z_1)]$	min of $[P\alpha(Zs),Ita,\alpha(Zs)]$	(mW)						
A 1	z_1	Z_{s}	(cm)						
Associated Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	z_{sp}	Z_b	(cm)						
1 41 41 11 10 10 1	Z@PII _{.3max}	Z at max $I_{pi \alpha}$	(cm)	1.8					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	f_{awf}	(MHz)	5.12	5.40				
	Dim of A _{aprt}	Dim of A _{aprt}	X (cm)		2.05				
	Dim Of Taprt	Diffi of Taprt	Y (cm)		0.45				
	PD	$t_{ m d}$	(µsec)	0.86					
	PRF	prr	(Hz)	7887					
	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	1.51					
Other	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)						
Information	Focal Length	Focal Length	FL _x (cm)		0.27				
	rocai Length	rocal Length	FLy (cm)		0.32				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	72.65					
Operating	Mode	Mode	NA	С	С				
Control	Focus	Focus	(cm)	2.5	2.5				
Conditions	Power	Power	(%)	100	100				

Transducer Model: <u>L12-E</u> Operating Mode: <u>B+C+PW</u>

			_		uc. <u>B+C+1</u>	TIS		TIB	
	Index	Label		MI	G.	non-s	can		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Max	imum Index Value			0.2			1.4	1.8	
	$p_{r.3}$	$p_{r,\alpha}$	(MPa)	0.54					
	W_{o}	P	(mW)					106.50	
	$\begin{aligned} & \text{min of } [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	min of $[P\alpha(Zs),Ita,\alpha(Zs)]$	(mW)				54.21		
	z_1	Z_{s}	(cm)				1.8		
Associated Acoustic	z _{bp}	Z_{bp}	(cm)				1.8		
Parameter	z_{sp}	Z_b	(cm)					1.8	
Turumeter	Z@PII.3max	Z at max $I_{pi \alpha}$	(cm)	3.0					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)					0.86	
	f_c	f_{awf}	(MHz)	5.43			5.43	5.43	
	Dim of A _{aprt}	Dim of A _{aprt}	X (cm)				2.05	2.05	
		Dilli Of A _{aprt}	Y (cm)				0.45	0.45	
	PD	$t_{ m d}$	(µsec)	0.83					
	PRF	prr	(Hz)	8051					
	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	0.75					
0.1	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)					0.86	
Other Information	Focal Length	Focal Length	FL _x (cm)				0,26		
	rocai Length	rocai Length	FLy (cm)				0.21		
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	103.77					
Operating	Mode	Mode	NA	PW			PW	PW	
Control	Focus	Focus	(cm)	2.5			2.5	2.5	
Conditions	Power	Power	(%)	100			100	100	

Transducer Model: <u>L12-E</u> Operating Mode: <u>M</u>

	ansuucei wioue		•	atilig Wio		TIS		TIB	
	Index	Label		MI	G.	non-s	can		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Max	imum Index Value			0.5			0.6	1.0	
	$p_{r.3}$	$p_{r,\alpha}$	(MPa)	1.21					
	Wo	P	(mW)					40.98	
	$\begin{aligned} & \text{min of } [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	$\begin{array}{c} \text{min of} \\ [P\alpha(Zs),Ita,\alpha(Zs)] \end{array}$	(mW)				19.75		
Associated	\mathbf{z}_1	Z_{s}	(cm)				1.8		
Acoustic	Z_{bp}	Z_{bp}	(cm)				1.8		
Parameter	Z_{sp}	Z_b	(cm)					1.8	
	Z@PII _{.3max}	Z at max $I_{pi \alpha}$	(cm)	1.8					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)					0.67	
	f_c	f_{awf}	(MHz)	5.85			5.87	5.82	
	Dim of A _{aprt}	Dim of A _{aprt}	X (cm)				2.05	2.05	
	Dim Of Traprt	Diffi of Taprt	Y (cm)				0.45	0.45	
	PD	t _d	(µsec)	0.23					
	PRF	prr	(Hz)	5319					
	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	1.74					
	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)					0.67	
Other Information	Focal Length	Focal Length	FL _x (cm)				0.25		
	Tocal Length	Tocal Length	FLy (cm)				0.18		
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	170.00					
Operating	Mode	Mode	NA	M			M	M	
Control	Focus	Focus	(cm)	2.5			2.5	2	
Conditions	Power	Power	(%)	100			100	100	

Transducer Model: <u>L12-D</u> Operating Mode: <u>B</u>

	ansuucei wiouc		•	ating Mo		TIS		TIB	
	Index	Label		MI	Caam	non-s	can		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Max	imum Index Value	:	_	0.6	0.1				
	$p_{r,3}$	$p_{r,\alpha}$	(MPa)	1.39					
	W_{o}	P	(mW)		8.19				
	$\begin{aligned} & \text{min of } [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	min of $[P\alpha(Zs),Ita,\alpha(Zs)]$	(mW)						
	z_1	Z_{s}	(cm)						
Associated	z _{bp}	Z_{bp}	(cm)						
Acoustic Parameter	z_{sp}	Z_b	(cm)						
rarameter	Z@PII _{.3max}	Z at max $I_{pi \alpha}$	(cm)	1.8					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_{c}	f_{awf}	(MHz)	5.91	5.91				
	Dim of A _{aprt}	Dim of A _{aprt}	X (cm)		2.05				
	Dilli Of Aaprt	Dilli Of A _{aprt}	Y (cm)		0.45				
	PD	$t_{ m d}$	(µsec)	0.23					
	PRF	prr	(Hz)	5319					
	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	2.03					
Other	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)						
Information	Focal Length	Focal Length	FL _x (cm)		0.33				
	Pocar Length	rocal Length	FLy (cm)		0.24				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	84.56					
Operating	Mode	Mode	NA	В	В				
Control	Focus	Focus	(cm)	2.5	2.5				
Conditions	Power	Power	(%)	100	100				

Transducer Model: <u>L12-D</u> Operating Mode: <u>THI-B</u>

	ansuucei wiouc		•		uc. <u>1111-D</u>	TIS		TIB	
	Index	Label		MI	G	non-s	can		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Max	imum Index Value	}		0.6	0.1				
	$p_{r,3}$	$p_{r,\alpha}$	(MPa)	1.39					
	Wo	P	(mW)		8.19				
	min of $[W_{.3}(z_1), I_{TA.3}(z_1)]$	$\begin{aligned} & \text{min of} \\ & [P\alpha(Zs),Ita,\alpha(Zs)] \end{aligned}$	(mW)						
	\mathbf{z}_1	$Z_{\rm s}$	(cm)						
Associated Acoustic	z_{bp}	Z_{bp}	(cm)						
Parameter	z_{sp}	Z_b	(cm)						
Turumeter	Z@PII _{.3max}	Z at max $I_{pi \alpha}$	(cm)	1.8					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_{c}	f_{awf}	(MHz)	5.89	5.90				
	Dim of A _{aprt}	Dim of A _{aprt}	X (cm)		2.05				
	Dilli Of Aaprt	Dilli Of Aaprt	Y (cm)		0.45				
	PD	t _d	(µsec)	0.23					
	PRF	prr	(Hz)	5319					
	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	2.03					
Other	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)						
Information	Focal Length	Focal Length	FL _x (cm)		0.33				
	rocar Length	Tocal Length	FLy (cm)		0.22				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	84.49					
Operating	Mode	Mode	NA	THI-B	THI-B				
Control	Focus	Focus	(cm)	2.5	2.5				
Conditions	Power	Power	(%)	100	100				

Transducer Model: <u>L12-D</u> Operating Mode: <u>B+C</u>

			-	ating Wio		TIS		TIB	
	Index	Label		MI	G.	non-s	can		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Maxi	imum Index Value	:		0.5	0.4				
	$p_{r,3}$	$p_{r,\alpha}$	(MPa)	1.18					
	W_{o}	P	(mW)		57.34				
	$\begin{aligned} & \text{min of } [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	min of $[P\alpha(Zs),Ita,\alpha(Zs)]$	(mW)						
A 1	z_1	Z_{s}	(cm)						
Associated Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	Z_{sp}	Z_b	(cm)						
1 41 41 11 10 10 1	Z@PII _{.3max}	Z at max $I_{pi \alpha}$	(cm)	1.8					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	f_{awf}	(MHz)	5.12	5.40				
	Dim of A _{aprt}	Dim of A _{aprt}	X (cm)		2.05				
	Dim Of A _{aprt}	Dilli Of Aaprt	Y (cm)		0.45				
	PD	$t_{ m d}$	(µsec)	0.86					
	PRF	prr	(Hz)	7887					
	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	1.51					
Other	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)						
Information	Focal Length	Focal Length	FL _x (cm)		0.27				
	Pocar Length	rocal Length	FLy (cm)		0.32				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	72.65					
Operating	Mode	Mode	NA	С	С				
Control	Focus	Focus	(cm)	2.5	2.5				
Conditions	Power	Power	(%)	100	100				

Transducer Model: <u>L12-D</u> Operating Mode: <u>B+C+PW</u>

					ис. <u> Бтсті</u>	TIS		TIB	
	Index	Label		MI	G	non-s	can		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Max	imum Index Value	:		0.2			1.4	1.8	
	$p_{r.3}$	$p_{r,\alpha}$	(MPa)	0.54					
	W_{o}	P	(mW)					106.50	
	$\begin{aligned} & \text{min of } [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	min of $[P\alpha(Zs),Ita,\alpha(Zs)]$	(mW)				54.21		
	z_1	Z_{s}	(cm)				1.8		
Associated Acoustic	z_{bp}	Z_{bp}	(cm)				1.8		
Parameter	z_{sp}	Z_b	(cm)					1.8	
Turumeter	Z@PII.3max	Z at max $I_{pi \alpha}$	(cm)	3.0					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)					0.86	
	f_c	f_{awf}	(MHz)	5.43			5.43	5.43	
	Dim of A _{aprt}	Dim of A _{aprt}	X (cm)				2.05	2.05	
			Y (cm)				0.45	0.45	
	PD	$t_{ m d}$	(µsec)	0.83					
	PRF	prr	(Hz)	8051					
	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	0.75					
0.1	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)					0.86	
Other Information	Focal Length	Focal Length	FL _x (cm)				0,26		
	Focal Length	rocai Length	FLy (cm)				0.21		
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	103.77					
Operating	Mode	Mode	NA	PW			PW	PW	
Control	Focus	Focus	(cm)	2.5			2.5	2.5	
Conditions	Power	Power	(%)	100			100	100	

Transducer Model: <u>L12-D</u> Operating Mode: <u>M</u>

	ansuucei wioue			ating Mo		TIS		TIB	
	Index	Label		MI	G.	non-s	can		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Max	imum Index Value			0.5			0.6	1.0	
	$p_{r.3}$	$p_{r,\alpha}$	(MPa)	1.21					
	Wo	P	(mW)					40.98	
	$\begin{aligned} & \text{min of } [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	$\begin{array}{c} \text{min of} \\ [P\alpha(Zs),Ita,\alpha(Zs)] \end{array}$	(mW)				19.75		
Associated	\mathbf{z}_1	Z_{s}	(cm)				1.8		
Acoustic	Z_{bp}	Z_{bp}	(cm)				1.8		
Parameter	Z_{sp}	Z_b	(cm)					1.8	
	Z@PII _{.3max}	Z at max $I_{pi \alpha}$	(cm)	1.8					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)					0.67	
	f_c	f_{awf}	(MHz)	5.85			5.87	5.82	
	Dim of A _{aprt}	Dim of A _{aprt}	X (cm)				2.05	2.05	
	Dim Of Traprt	Diffi of Taprt	Y (cm)				0.45	0.45	
	PD	t _d	(µsec)	0.23					
	PRF	prr	(Hz)	5319					
	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	1.74					
	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)					0.67	
Other Information	Focal Length	Focal Length	FL _x (cm)				0.25		
	Pocar Length	Focal Length	FLy (cm)				0.18		
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	170.00					
Operating	Mode	Mode	NA	M			M	M	
Control	Focus	Focus	(cm)	2.5			2.5	2	
Conditions	Power	Power	(%)	100			100	100	

Transducer Model: <u>P6-E</u> Operating Mode: <u>B</u>

				8		TIS		TIB	
	Inde	x Label		MI	Caran	non-s	scan		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Max	imum Index Val	ue		0.9	1.5				
	$p_{r.3}$	$p_{r,^{lpha}}$	(MPa)	1.80					
	Wo	P	(mW)		1.34				
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	min of $[P\alpha(Zs),Ita,\alpha(Zs)]$	(mW)						
Associated	z_1	$Z_{\rm s}$	(cm)						
Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	Z_{sp}	Z_b	(cm)						
	Z@PII.3max	Z at max $I_{pi \alpha}$	(cm)	2.2					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	f_{awf}	(MHz)	3.82	3.90				
	Dim of A _{aprt}	Dim of A _{aprt}	X (cm)		0.83				
			Y (cm)		0.90				
	PD	$t_{\rm d}$	(µsec)	0.46					
	PRF	prr	(Hz)	4201					
	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	2.20					
Other	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)						
Information	Focal Length	Focal Length	FL _x (cm)		0.26				
	rocal Length	rocal Length	FLy (cm)		0.32				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	98.14					
Operating	Mode	Mode	NA	В	В				
Control	Focus	Focus	(cm)	5	8				
Conditions					100				

Transducer Model: <u>P6-E</u> Operating Mode: <u>THI-B</u>

			_	unig Wide		TIS		TIB	
	Inde	x Label		MI	G	non-	scan		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Max	imum Index Val	ue		0.9	1.4				
	p _{r.3}	$p_{r,^{lpha}}$	(MPa)	1.72					
	Wo	P	(mW)		1.34				
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	min of $[P\alpha(Zs),Ita,\alpha(Zs)]$	(mW)						
Associated	z_1	$Z_{\rm s}$	(cm)						
Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	Z _{sp}	Z_b	(cm)						
	Z@PII.3max	Z at max $I_{pi \alpha}$	(cm)	2.2					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	$f_{ m awf}$	(MHz)	3.80	3.88				
	Dim of A _{aprt}	Dim of A _{aprt}	X (cm)		0.83				
		Dilli Of A _{aprt}	Y (cm)		0.90				
	PD	$t_{\rm d}$	(µsec)	0.46					
	PRF	prr	(Hz)	4201					
	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	2.20					
Other	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)						
Information	Focal Length	Eggel Lanoth	FL _x (cm)		0.26				
	rocai Lengui	Focal Length	FLy (cm)		0.32				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	98.11					
Operating	Mode	Mode	NA	THI-B	THI-B				
Control	Focus	Focus	(cm)	5	8				
Conditions	Power	Power	(%)	100	100				

Transducer Model: <u>P6-E</u> Operating Mode: <u>B+C</u>

				ating Wide		TIS		TIB	
	Inde	x Label		MI	Caan	non-s	scan		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Max	imum Index Val	ue		0.6	0.9				
	p _{r.3}	$p_{r,^{\alpha}}$	(MPa)	1.24					
	W_{o}	P	(mW)		1.00				
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	min of $[P\alpha(Zs),Ita,\alpha(Zs)]$	(mW)						
Associated	z_1	Z_{s}	(cm)						
Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	Z_{sp}	Z_b	(cm)						
	Z@PII.3max	Z at max $I_{pi \alpha}$	(cm)	2.3					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	$ m f_{awf}$	(MHz)	4.05	4.06				
	Dim of A _{aprt}	Dim of A _{aprt}	X (cm)		0.83				
		Dilli Of Aaprt	Y (cm)		0.90				
	PD	$t_{\rm d}$	(µsec)	0.97					
	PRF	prr	(Hz)	6993					
	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	1.58					
Other	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)						
Information	Focal Length	Focal Length	FL _x (cm)		0.33				
	1 ocai Lengtii	r ocar Length	FLy (cm)		0.22				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	65.50					
Operating	Mode	Mode	NA	С	С				
Control	Focus	Focus	(cm)	6	7				
Conditions					100				

Transducer Model: P6-E Operating Mode: B+C+PW

			_	unig mo		TIS		TIB	
	Inde	x Label		MI	G	non-	scan		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Max	imum Index Val	ue		0.4		0.9		1.1	
	$p_{r,3}$	$p_{r,^{\alpha}}$	(MPa)	0.95					
	Wo	P	(mW)			24.96		24.96	
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	min of $[P\alpha(Zs),Ita,\alpha(Zs)]$	(mW)						
Associated	z_1	Z_{s}	(cm)						
Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	Z_{sp}	Z_b	(cm)					1.8	
	Z@PII _{.3max}	Z at max $I_{pi \alpha}$	(cm)	2.0					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)					0.20	
	f_c	$ m f_{awf}$	(MHz)	7.35		7.36		7.35	
	Dim of A _{aprt}	Dim of A _{aprt}	X (cm)			0.83		0.83	
	Dilli Of A _{aprt}	Dilli Of Aaprt	Y (cm)			0.90		0.90	
	PD	$t_{\rm d}$	(µsec)	2.03					
	PRF	prr	(Hz)	6983					
	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	1.42					
Other	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)					0.20	
Information	Focal Length	Focal Length	FL _x (cm)			0.22			
	1 ocai Lengtii	1 ocai Lengui	FLy (cm)			0.34			
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	119.18					
Operating	Mode	Mode	NA	PW		PW		PW	
Control	Focus	Focus	(cm)	7		5		5	
Conditions	Power	Power	(%)	100		100		100	

Transducer Model: P6-E Operating Mode: M

		<u> 10 L</u>	_	ating Wilde		TIS		TIB	
	Inde	x Label		MI	G	non-s	scan		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Max	imum Index Val	ue		1.0		1.2		1.3	
	p _{r.3}	$p_{r,^{\alpha}}$	(MPa)	1.87					
	W_{o}	P	(mW)			66.56		66.56	
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	min of $[P\alpha(Zs),Ita,\alpha(Zs)]$	(mW)						
Associated	z_1	Z_{s}	(cm)						
Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	Z_{sp}	Z_{b}	(cm)					2.0	
	Z@PII.3max	Z at max $I_{pi \alpha}$	(cm)	2.1					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)					0.33	
	f_c	$f_{ m awf}$	(MHz)	3.84		3.84		3.80	
	Dim of A _{aprt}	Dim of A _{aprt}	X (cm)			0.83		0.83	
	Dilli Of Taprt	Dilli Of Taprt	Y (cm)			0.90		0.90	
	PD	t _d	(µsec)	0.45					
	PRF	prr	(Hz)	5814					
	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	2.33					
Other	d _{eq} @PII _{max}	d _{eq} at max I _{pi}	(cm)					0.33	
Information	Focal Length	Focal Length	FL _x (cm)			0.23			
	rocai Length	r ocar Length	FLy (cm)			0.36			
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	147.25					
Operating	Mode	Mode	NA	M		M		M	
Control	Focus	Focus	(cm)	5		5		6	
Conditions	Power	Power	(%)	100		100		100	

Transducer Model: P6-E Operating Mode: B+C+CW

			_	unig mio		TIS		TIB	
	Inde	x Label		MI	g	non-	scan		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Max	imum Index Val	ue		0.3		0.9		1.0	0.9
	p _{r.3}	$p_{r,^{lpha}}$	(MPa)	0.47					
	Wo	P	(mW)			70.00		68.00	75.00
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	min of $[P\alpha(Zs),Ita,\alpha(Zs)]$	(mW)						
Associated	z_1	Z_{s}	(cm)						
Acoustic	z _{bp}	Z_{bp}	(cm)						
Parameter	Z _{sp}	Z_b	(cm)					4.1	
	Z@PII.3max	Z at max $I_{pi \alpha}$	(cm)	4.0					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)					0.57	
	f_c	$ m f_{awf}$	(MHz)	3.25		3.50		3.61	3.54
	Dim of A _{aprt}	Dim of A _{aprt}	X (cm)			0.83		0.83	0.83
	Dilli Of A _{aprt}	Dilli Of A _{aprt}	Y (cm)			0.70		0.70	0.70
	PD	$t_{\rm d}$	(µsec)	18.94					
	PRF	prr	(Hz)	0					
	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	0.09					
Other	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)					0.62	
Information	Focal Length	Focal Length	FL _x (cm)			0.30			0.21
	rocal Length	rocal Length	FLy (cm)			0.25			0.24
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	26.80					
Operating	Mode	Mode	NA	CW		CW		CW	CW
Control	Focus	Focus	(cm)	5		5		6	6
Conditions	Power	Power	(%)	100		100		100	100

Transducer Model: P6-E Operating Mode: CFM-M

		<u> 10 L</u>	_	uting 1710th		TIS		TIB	
	Inde	x Label		MI	Caran	non-s	scan		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Max	imum Index Val	ue		0.7		0.2		0.3	
	p _{r.3}	$p_{r,^{\alpha}}$	(MPa)	1.22					
	W_{o}	P	(mW)			14.00		16.00	
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	min of $[P\alpha(Zs),Ita,\alpha(Zs)]$	(mW)						
Associated	z_1	Z_{s}	(cm)						
Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	Z_{sp}	Z_{b}	(cm)					3.0	
	Z@PII _{.3max}	Z at max $I_{pi \alpha}$	(cm)	3.2					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)					0.90	
	f_c	${ m f}_{ m awf}$	(MHz)	3.48		3.53		3.63	
	Dim of A _{aprt}	Dim of A _{aprt}	X (cm)			0.83		0.83	
	Dilli Of A _{aprt}	Dilli Of A _{aprt}	Y (cm)			0.70		0.70	
	PD	t_d	(µsec)	0.93					
	PRF	prr	(Hz)	200					
	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	2.39					
Other	d _{eq} @PII _{max}	d _{eq} at max I _{pi}	(cm)					0.58	
Information	Focal Length	Focal Length	FL _x (cm)			0.39			
	rocai Length	r ocar Length	FLy (cm)			0.60			
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	55.88					
Operating	Mode	Mode	NA	CFM-M		CFM-M		CFM-M	
Control	Focus	Focus	(cm)	5		5		6	
Conditions	Power	Power	(%)	100		100		100	

Transducer Model: <u>L7-ES</u> Operating Mode: <u>B</u>

					<u> </u>	TIS		TIB	
	Index	k Label		MI		non-	scan		TIC
	Mucz	Label		1711	Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	ne
Global Maxi	i mum Index V	alue		0.8	0.5				
	p _{r.3}	р _{г, а}	(MPa)	1.98					
	W_{o}	P	(mW)		73.73				
	min of [W _{.3} (z ₁), I _{TA.3} (z ₁)]	$\begin{aligned} & \text{min of} \\ & & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)						
Associated	z_1	Z_{s}	(cm)						
Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	Z_{sp}	Z_{b}	(cm)						
	Z@PII.3max	Z at max $I_{pi \alpha}$	(cm)	2.1					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	f_{awf}	(MHz)	6.05	6.15				
	Dim of	Dim of A _{aprt}	X (cm)		1.34				
	A_{aprt}	Dim of Mapri	Y (cm)		0.45				
	PD	t _d	(µsec)	0.23					
	PRF	prr	(Hz)	2763.6					
	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	3.12					
	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)						
Other Information	Focal	Focal Length	FL _x (cm)		1.49				
	Length	rocai Length	FLy (cm)		1.58				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	210.51					
Operating	Mode	Mode	NA	В	В				
Control	Focus	Focus	(cm)	2.5	3				
Conditions	Power	Power	(%)	100	100				

Transducer Model: <u>L7-ES</u> Operating Mode: <u>THI-B</u>

		Mei. <u>L7-E8</u>		F	<u> 1</u>	TIS		TIB	
							scan		TTV C
	Index	Label		MI	Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	TIC
Global Max	imum Index V	alue		0.6	0.4				
	p _{r.3}	р _{г, а}	(MPa)	1.86					
	W_{o}	P	(mW)		73.71				
	min of [W _{.3} (z ₁), I _{TA.3} (z ₁)]	$\begin{aligned} & \text{min of} \\ & & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)						
Associated	z_1	$Z_{\rm s}$	(cm)						
Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	Z_{sp}	Z_{b}	(cm)						
	Z@PII.3max	Z at max I _{pi α}	(cm)	2.0					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	$ m f_{awf}$	(MHz)	6.02	6.11				
	Dim of	Dim of A _{aprt}	X (cm)		1.34				
	A_{aprt}	Dilli Of A _{aprt}	Y (cm)		0.45				
	PD	t_d	(µsec)	0.21					
	PRF	prr	(Hz)	2759.62					
	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	3.12					
	$d_{eq}@PII_{max}$	d_{eq} at max I_{pi}	(cm)						
Other Information	Focal	Focal Length	FL _x (cm)		1.49				
	Length	Focal Length	FLy (cm)		1.58				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	210.51					
Operating	Mode	Mode	NA	THI-B	THI-B				
Control	Focus	Focus	(cm)	2.5	3				
Conditions				100	100				

Transducer Model: <u>L7-ES</u> Operating Mode: <u>B+C</u>

					<u> </u>	TIS		TIB	
	Index	k Label		MI		non-	scan		TIC
	Mucz	Label		1711	Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	ne
Global Maxi	i mum Index V	alue		0.5	0.8				
	p _{r.3}	р _{г, а}	(MPa)	1.62					
	W_{o}	P	(mW)		105.45				
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	$\begin{aligned} & \text{min of} \\ & & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)						
Associated	z_1	Z_{s}	(cm)						
Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	Z_{sp}	Z_{b}	(cm)						
	Z@PII.3max	Z at max $I_{pi \alpha}$	(cm)	1.7					
-	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	f_{awf}	(MHz)	6.36	6.37				
	Dim of	Dim of A _{aprt}	X (cm)		1.34				
	A_{aprt}	Dim of Mapri	Y (cm)		0.45				
	PD	t _d	(µsec)	0.77					
	PRF	prr	(Hz)	7032.5					
	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	1.85					
	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)						
Other Information	Focal	Focal Length	FL _x (cm)		1.49				
	Length	rocai Length	FLy (cm)		1.51				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	82.56					
Operating	Mode	Mode	NA	С	С				
Control	Focus	Focus	(cm)	2	1.5				
Conditions	Power	Power	(%)	100	100				

Transducer Model: <u>L7-ES</u> Operating Mode: <u>B+C+PW</u>

					<u> </u>	TIS		TIB	
	Inde	k Label		MI		non-	scan		TIC
	Indez	Lubei		1,11	Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Max	imum Index V	alue		0.6		2.2		1.9	
	p _{r.3}	р _{г, а}	(MPa)	1.49					
	\mathbf{W}_{o}	P	(mW)			73.79		73.79	
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	$\begin{aligned} & \text{min of} \\ & & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)						
Associated	z_1	Z_{s}	(cm)						
Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	Z_{sp}	Z_{b}	(cm)					1.7	
	Z@PII _{.3max}	Z at max $I_{pi \alpha}$	(cm)	1.6					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)					0.44	
	f_c	$f_{ m awf}$	(MHz)	6.25		6.52		6.34	
	Dim of	Dim of A _{aprt}	X (cm)			1.34		1.34	
	A_{aprt}	Dilli Of Aaprt	Y (cm)			0.45		0.45	
	PD	t _d	(µsec)	0.62					
	PRF	prr	(Hz)	2896.3					
	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	2.16					
	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)					0.44	
Other Information	Focal		FL _x (cm)			2.56			
	Length	Focal Length	FLy (cm)			2.47			
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	120.5					
Operating	Mode	Mode	NA	PW		PW		PW	
Control	Focus	Focus	(cm)	3.5		3.5		3.5	
Conditions	Power	Power	(%)	100		100		100	

Transducer Model: <u>L7-ES</u> Operating Mode: <u>M</u>

		uci. <u>Li Lo</u>			<u> </u>	TIS		TIB	
	Inde	x Label		MI		non-s	scan		TIC
	muc.	a Lauci		1411	Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Maxi	imum Index V	alue		0.7		3.9		1.6	
	p _{r.3}	$p_{r,^{lpha}}$	(MPa)	1.8					
	W_{o}	P	(mW)			128.90		128.90	
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	$\begin{aligned} & \text{min of} \\ & & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)						
Associated	\mathbf{z}_1	Z_{s}	(cm)						
Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	Z_{sp}	Z_b	(cm)					1.8	
	Z@PII.3max	Z at max $I_{pi\alpha}$	(cm)	1.9					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)					0.98	
	f_c	$ m f_{awf}$	(MHz)	6.12		6.07		6.12	
	Dim of	Dim of A _{aprt}	X (cm)			1.34		1.34	
	A_{aprt}	Dilli Of A _{aprt}	Y (cm)			0.45		0.45	
	PD	t_d	(µsec)	0.23					
	PRF	prr	(Hz)	2799.3					
	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	2.72					
Other	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)					0.94	
Information	Focal	Focal Length	FL _x (cm)			2.59			
	Length	rocai Length	FLy (cm)			2.35			
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	142.7					
Operating	Mode	Mode	NA	M		M		M	
Control	Focus	Focus	(cm)	2		2		2	
Conditions	Power	Power	(%)	100		100		100	

Transducer Model: <u>V7-D</u> Operating Mode: <u>B</u>

				peruumg		TIS		TIB	
	Inda	x Label		MI		non-	-scan		TIC
	inde	x Labei		1711	Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	110
Global Max	imum Index V	alue		0.4	0.2				
	p _{r.3}	$p_{r,^{lpha}}$	(MPa)	0.81					
	W_{o}	P	(mW)		28.33				
	min of [W _{.3} (z ₁), I _{TA.3} (z ₁)]	$\begin{aligned} & \text{min of} \\ & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)						
Associated	z_1	Z_{s}	(cm)						
Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	Z_{sp}	Z_b	(cm)						
	z@PII _{.3max}	Z at max $I_{pi\alpha}$	(cm)	2.5					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	f_{awf}	(MHz)	4.07	4.05				
	Dim of	Dim of A _{aprt}	X (cm)		0.99				
	A_{aprt}	Dilli Of A _{aprt}	Y (cm)		0.70				
	PD	t _d	(µsec)	0.62					
	PRF	prr	(Hz)	4426.5					
	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	1.24					
Other	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)						
Information	Focal	Focal Length	FL _x (cm)		1.05				
	Length	1 ocai Length	FLy (cm)		1.21				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	42.25					
Operating	Mode	Mode	NA	В	В				
Control	Focus	Focus	(cm)	3	3				
Conditions	Power	Power	(%)	100	100				

Transducer Model: <u>V7-D</u> Operating Mode: <u>THI-B</u>

						TIS		TIB	
	Inde	x Label		MI		non-	scan		TIC
	muc	A Labei		1711	Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	110
Global Maxi	imum Index V	alue		0.5	0.2				
	$p_{r.3}$	$p_{r,^{lpha}}$	(MPa)	1.01					
	\mathbf{W}_{o}	P	(mW)		28.32				
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	$\begin{aligned} & \text{min of} \\ & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)						
Associated	z_1	Z_{s}	(cm)						
Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	Z_{sp}	Z_b	(cm)						
	z@PII _{.3max}	Z at max $I_{pi\alpha}$	(cm)	2.6					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	f_{awf}	(MHz)	4.08	4.05				
	Dim of	Dim of A _{aprt}	X (cm)		0.99				
	A _{aprt}	Dilli Of A _{aprt}	Y (cm)		0.70				
	PD	$t_{\rm d}$	(µsec)	0.62					
	PRF	prr	(Hz)	4426.5					
	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	1.24					
Other	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)						
Information	Focal	Focal Length	FL _x (cm)		2.02				
	Length	1 ocur Ecngui	FLy (cm)		1.99				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	42.38					
Operating	Mode	Mode	NA	THI-B	THI-B				
Control	Focus	Focus	(cm)	3	3				
Conditions	Power	Power	(%)	100	100				

Transducer Model: <u>V7-D</u> Operating Mode: <u>B+C</u>

				peruumg		TIS		TIB	
	Inda	x Label		MI		non-	-scan		TIC
	mue	x Labei		1711	Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Max	imum Index V	alue		0.4	0.6				
	$p_{r.3}$	$p_{r,^{lpha}}$	(MPa)	0.91					
	W_{o}	P	(mW)		76.52				
	min of [W _{.3} (z ₁), I _{TA.3} (z ₁)]	$\begin{aligned} & \text{min of} \\ & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)						
Associated	z_1	Z_{s}	(cm)						
Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	Z_{sp}	Z_b	(cm)						
	Z@PII.3max	Z at max $I_{pi\alpha}$	(cm)	2.5					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	f_{awf}	(MHz)	5.16	5.25				
	Dim of	Dim of A _{aprt}	X (cm)		0.99				
	A_{aprt}	Dilli Of Aaprt	Y (cm)		0.70				
	PD	$t_{\rm d}$	(µsec)	0.69					
	PRF	prr	(Hz)	6055.5					
	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	1.3					
Other	$d_{eq}@PII_{max}$	d_{eq} at max I_{pi}	(cm)						
Information	Focal	Focal Length	FL _x (cm)		2.21				
	Length	1 ocur Length	FLy (cm)		2.06				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	32.29					
Operating	Mode	Mode	NA	С	С				
Control	Focus	Focus	(cm)	3	3				
Conditions	Power	Power	(%)	100	100				

Transducer Model: <u>V7-D</u> Operating Mode: <u>B+C+PW</u>

						TIS		TIB	
	Indo	x Label		MI		non-	-scan		TIC
	inde	a Labei		WII	Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	ПС
Global Max	imum Index V	alue		0.5		1.5		1.1	
	p _{r.3}	$p_{r,^{lpha}}$	(MPa)	1.03					
	W_{o}	P	(mW)			98.66		100.61	
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	$\begin{aligned} & \text{min of} \\ & & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)						
Associated	z_1	Z_{s}	(cm)						
Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	Z_{sp}	Z_b	(cm)					2.1	
	z@PII _{.3max}	Z at max $I_{pi \alpha}$	(cm)	2.7					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)					0.45	
	f_c	f_{awf}	(MHz)	5.23		5.23		5.23	
	Dim of	Dim of A _{aprt}	X (cm)			0.99		0.99	
	A_{aprt}	Dilli Of A _{aprt}	Y (cm)			0.70		0.70	
	PD	t_d	(µsec)	0.85					
	PRF	prr	(Hz)	5526.5					
	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	1.65					
Other	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)					0.44	
Information	Focal	Focal Length	FL _x (cm)			1.55			
	Length	1 ocar Ecngui	FLy (cm)			1.68			
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	144.25					
Operating	Mode	Mode	NA	PW		PW		PW	
Control	Focus	Focus	(cm)	3.5		3.5		3.5	
Conditions	Power	Power	(%)	100		100		100	

Transducer Model: <u>V7-D</u> Operating Mode: <u>M</u>

					1,10 0.0. <u>1,11</u>	TIS		TIB	
	Indo	x Label		MI		non	-scan		TIC
	mue	x Labei		WII	Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Max	imum Index V	alue		0.5		0.9		1.2	
	p _{r.3}	$p_{r,^{lpha}}$	(MPa)	0.96					
	W _o	P	(mW)			47.50		47.50	
	min of [W _{.3} (z ₁), I _{TA.3} (z ₁)]	$\begin{aligned} & \text{min of} \\ & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)						
Associated	z_1	Z_{s}	(cm)						
Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	Z_{sp}	Z_b	(cm)					2.4	
	z@PII _{.3max}	Z at max $I_{pi\alpha}$	(cm)	2.8					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)					0.47	
	f_c	f_{awf}	(MHz)	4.14		4.13		4.12	
	Dim of	Dim of A _{aprt}	X (cm)			0.99		0.99	
	A_{aprt}	Dilli Of A _{aprt}	Y (cm)			0.70		0.70	
	PD	$t_{\rm d}$	(µsec)	0.66					
	PRF	prr	(Hz)	5522.6					
	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	1.24					
Other	$d_{eq}@PII_{max}$	d_{eq} at max I_{pi}	(cm)					0.47	
Information	Focal	Focal Length	FL _x (cm)			1.56			
	Length		FLy (cm)			1.78			
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	134.55					
Operating	Mode	Mode	NA	M		M		M	
Control	Focus	Focus	(cm)	2.5		2.5		2.5	
Conditions	Power	Power	(%)	100		100		100	

Transducer Model: <u>7B8-E</u> Operating Mode: <u>B</u>

				- Feruing		TIS		TIB	
	Inde	ex Label		MI		non-	scan		TIC
	mac	ALAUCI		1711	Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Maxi	mum Index V	alue		0.5	0.2				
	$p_{r.3}$	$p_{r,^{lpha}}$	(MPa)	0.88					
	\mathbf{W}_{o}	P	(mW)		29.69				
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	$\begin{aligned} & \text{min of} \\ & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)						
	z_1	Z_{s}	(cm)						
Associated Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	z_{sp}	Z_b	(cm)						
Turumeter	Z@PII.3max	Z at max $I_{pi\alpha}$	(cm)	2.3					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	f_{awf}	(MHz)	4.15	4.15				
	Dim of	Dim of A _{aprt}	X (cm)		1.07				
	A _{aprt}	Dilli Of A _{aprt}	Y (cm)		0.70				
	PD	$t_{\rm d}$	(µsec)	0.62					
	PRF	prr	(Hz)	4356.9					
	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	1.35					
Other Information	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)						
mormation	Focal	Food Langth	FL _x (cm)		1.23				
	Length	Focal Length	FLy (cm)		1.45				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	43.23					
Operating	Mode	Mode	NA	В	В				
Control	Focus	Focus	(cm)	2.5	2.5				
Conditions	Power	Power	(%)	100	100				

Transducer Model: <u>7B8-E</u> Operating Mode: <u>THI-B</u>

	isuucei Mio	uci. /bo-E			1110uc. 111	TIS		TIB	
	Inda	ex Label		MI		non	-scan		TIC
	mue	A Labei		IVII	Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Maxi	mum Index V	alue		0.4	0.2				
	p _{r.3}	р _{г, а}	(MPa)	0.83					
	W_{o}	P	(mW)		29.32				
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	$\begin{aligned} & \text{min of} \\ & & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)						
	z_1	Z_{s}	(cm)						
Associated Acoustic	z_{bp}	Z_{bp}	(cm)						
Parameter	z_{sp}	Z_b	(cm)						
Turumeter	Z@PII.3max	Z at max $I_{pi\alpha}$	(cm)	2.4					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	$f_{ m awf}$	(MHz)	4.11	4.11				
	Dim of	Dim of A	X (cm)		1.07				
	A_{aprt}	Dim of A _{aprt}	Y (cm)		0.70				
	PD	t _d	(µsec)	0.56					
	PRF	prr	(Hz)	438.66					
	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	1.35					
Other Information	d _{eq} @PII _{max}	d _{eq} at max I _{pi}	(cm)						
imormation	Focal	Food Langth	FL _x (cm)		1.23				
	Length	Focal Length	FLy (cm)		1.45				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	42.56					
Operating	Mode	Mode	NA	THI-B	THI-B				
Control	Focus	Focus	(cm)	2.5	2.5				
Conditions	Power	Power	(%)	100	100				

Transducer Model: <u>7B8-E</u> Operating Mode: <u>B+C</u>

					<u> </u>	TIS		TIB	
	Inde	x Label		MI		non	-scan		TIC
	mue	A Label		IVII	Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Maxi	mum Index Va	lue		0.4	0.6				
	$p_{r.3}$	р _{г, а}	(MPa)	0.91					
	W_{o}	P	(mW)		77.32				
	min of [W _{.3} (z ₁), I _{TA.3} (z ₁)]	$\begin{aligned} & \text{min of} \\ & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)						
	z_1	Z_{s}	(cm)						
Associated	Z _{bp}	Z_{bp}	(cm)						
Acoustic Parameter	Z_{sp}	Z_b	(cm)						
Tarameter	Z@PII _{.3max}	Z at max $I_{pi \alpha}$	(cm)	2.5					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	f_{awf}	(MHz)	5.24	5.24				
	D: f A	Dim of A	X (cm)		1.07				
	Dim of A _{aprt}	Dim of A _{aprt}	Y (cm)		0.70				
	PD	$t_{\rm d}$	(µsec)	0.67					
	PRF	prr	(Hz)	6.23.2					
	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	1.32					
Other	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)						
Information	Focal	Escal I and the	FL _x (cm)		1.25				
	Length	Focal Length	FLy (cm)		1.41				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	31.89					
Operating	Mode	Mode	NA	С	С				
Control	Focus	Focus	(cm)	2.5	2.5				
Conditions	Power	Power	(%)	100	100				

Transducer Model: <u>7B8-E</u> Operating Mode: <u>B+C+PW</u>

	suucei Wiou	iei. <u>/Do-E</u>			.ouc. <u>b+C</u>	TIS		TIB	
	Inde	x Label		MI		non	-scan		TIC
	muc	A Labei			Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Maxi	mum Index Va	lue		0.5		2.5		2.0	
	$p_{r.3}$	$p_{r,^{\alpha}}$	(MPa)	1.04					
	W_{o}	P	(mW)			100.02		100.02	
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	$\begin{aligned} & \text{min of} \\ & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)						
	z_1	$Z_{\rm s}$	(cm)						
Associated Acoustic	z_{bp}	Z_{bp}	(cm)						
Parameter	z_{sp}	Z_{b}	(cm)					2.3	
1 0.00.000	z@PII _{.3max}	Z at max $I_{pi \alpha}$	(cm)	3.4					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)					0.47	
	f_c	$f_{ m awf}$	(MHz)	5.29		5.29		5.29	
	Dim of A _{aprt}	Dim of A _{aprt}	X (cm)			1.07		1.07	
	Dilli Of A _{aprt}	Dilli Of A _{aprt}	Y (cm)			0.70		0.70	
	PD	$t_{\rm d}$	(µsec)	0.85					
	PRF	prr	(Hz)	5466.3					
	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	1.53					
Other Information	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)					0.45	
Imormation	Focal	Essal Lanath	FL _x (cm)			1.45			
	Length	Focal Length	FLy (cm)			1.26			
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	42.72					
Operating	Mode	Mode	NA	PW		PW		PW	
Control	Focus	Focus	(cm)	2.5		2.5		2.5	
Conditions	Power	Power	(%)	100		100		100	

Transducer Model: <u>7B8-E</u> Operating Mode: <u>M</u>

						TIS		TIB	
	Inde	x Label		MI		non	-scan		TIC
	muc	A Lubei			Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Maxi	mum Index Va	lue		0.5		0.9		1.2	
	p _{r.3}	$p_{r,^{lpha}}$	(MPa)	0.93					
	W_{o}	P	(mW)			47.58		47.52	
	min of [W _{.3} (z ₁), I _{TA.3} (z ₁)]	$\begin{aligned} & \text{min of} \\ & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)						
A	z_1	$Z_{\rm s}$	(cm)						
Associated Acoustic	z_{bp}	Z_{bp}	(cm)						
Parameter	z_{sp}	Z_{b}	(cm)					2.41	
1 4144110001	Z@PII _{.3max}	Z at max $I_{pi \alpha}$	(cm)	2.5					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)					0.46	
	f_c	f_{awf}	(MHz)	4.12		4.12		4.13	
	Dim of A _{aprt}	Dim of A _{aprt}	X (cm)			1.07		1.07	
	Dilli Of A _{aprt}	Dilli Of A _{aprt}	Y (cm)			0.70		0.70	
	PD	t _d	(µsec)	0.64					
	PRF	prr	(Hz)	5366.2					
	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	1.27					
Other	$d_{eq}@PII_{max}$	d_{eq} at max I_{pi}	(cm)					0.46	
Information	Focal	Essal Lanath	FL _x (cm)			2.36			
	Length	Focal Length	FLy (cm)			1.89			
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	36.92					
Operating	Mode	Mode	NA	M		M		M	
Control	Focus	Focus	(cm)	3		3		3	
Conditions	Power	Power	(%)	100		100		100	

Transducer Model: <u>L7R-E</u> Operating Mode: <u>B</u>

		den <u>Erice</u>		perung		TIS		TIB	
	Inde	x Label		MI		non	-scan		TIC
	Inde	A Lavei		1411	Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	110
Global Maxi	mum Index V	alue		0.8	0.5				
	p _{r.3}	$p_{r,^{lpha}}$	(MPa)	2.08					
	W_{o}	P	(mW)		73.28				
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	$\begin{aligned} & \text{min of} \\ & & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)						
Associated	z_1	Z_{s}	(cm)						
Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	Z_{sp}	Z_b	(cm)						
	Z@PII.3max	Z at max $I_{pi \alpha}$	(cm)	1.9					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	$\mathbf{f}_{\mathrm{awf}}$	(MHz)	6.14	6.14				
	Dim of	Dim of A	X (cm)		2.05				
	A_{aprt}	Dim of A _{aprt}	Y (cm)		0.45				
	PD	$t_{\rm d}$	(µsec)	0.22					
	PRF	prr	(Hz)	2865.3					
	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	3.07					
Other	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)						
Information	Focal	Focal Length	FL _x (cm)		2.32				
	Length	rocai Length	FLy (cm)		2.18				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	178.21					
Operating	Mode	Mode	NA	В	В				
Control	Focus	Focus	(cm)	3	3				
Conditions	Power	Power	(%)	100	100				

Transducer Model: <u>L7R-E</u> Operating Mode: <u>THI-B</u>

	isducci ivio	ici. <u>L/K-E</u>		3	vioue. <u>111</u>	TIS		TIB	
	Inde	x Label		MI		non-	scan		TIC
	mac	A Lubei		1111	Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Maxi	mum Index Va	alue		0.7	0.4				
	p _{r.3}	$p_{r,^{\alpha}}$	(MPa)	2.04					
	W_{o}	P	(mW)		73.17				
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	$\begin{aligned} & \text{min of} \\ & & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)						
Associated	z_1	Z_{s}	(cm)						
Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	z_{sp}	Z_b	(cm)						
	Z@PII.3max	Z at max $I_{pi \alpha}$	(cm)	1.9					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	f_{awf}	(MHz)	6.11	6.12				
	Dim of	Dim of A _{aprt}	X (cm)		2.05				
	A _{aprt}	Dilli Of Aaprt	Y (cm)		0.45				
	PD	t _d	(µsec)	0.21					
	PRF	prr	(Hz)	2855.4					
	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	3.04					
Other	d _{eq} @PII _{max}	d _{eq} at max I _{pi}	(cm)						
Information	Focal	Focal Length	FL_{x} (cm)		2.31				
	Length	T ocur Bengun	FLy (cm)		2.24				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	169.56					
Operating	Mode	Mode	NA	THI-B	THI-B				
Control	Focus	Focus	(cm)	3	3				
Conditions	Power	Power	(%)	100	100				

Transducer Model: <u>L7R-E</u> Operating Mode: <u>B+C</u>

						TIS		TIB	
	Inde	ex Label		MI		non-	-scan		TIC
	muc	A Lubei		1411	Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Maxi	mum Index Va	alue		0.5	0.8				
	p _{r.3}	$p_{r,^{lpha}}$	(MPa)	1.25					
	W_{o}	P	(mW)		105.62				
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	$\begin{aligned} & \text{min of} \\ & & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)						
Associated	z_1	Z_s	(cm)						
Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	Z_{sp}	Z_b	(cm)						
	Z@PII _{.3max}	Z at max $I_{pi\alpha}$	(cm)	1.6					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	f_{awf}	(MHz)	6.36	6.35				
	Dim of	Dim of A _{aprt}	X (cm)		2.05				
	A _{aprt}	Dilli Of Aaprt	Y (cm)		0.45				
	PD	t_d	(µsec)	0.75					
	PRF	prr	(Hz)	6855.2					
	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	1.85					
Other	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)						
Information	Focal	Focal Length	FL_{x} (cm)		1.46				
	Length	1 ocai Lengui	FLy (cm)		1.52				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	88.5					
Operating	Mode	Mode	NA	С	С				
Control	Focus	Focus	(cm)	2	2.5				
Conditions	Power	Power	(%)	100	100				

Transducer Model: <u>L7R-E</u> Operating Mode: <u>B+C+PW</u>

	isducci ivio	uci. <u>L/K-L</u>			Mode. DT	TIS		TIB	
	Inde	ex Label		MI		non-	-scan		TIC
	mac	LA Lubei		1711	Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	110
Global Maxi	mum Index Va	alue		0.6		2.2		1.8	
	$p_{r.3}$	$p_{r,^{lpha}}$	(MPa)	1.39					
	W_{o}	P	(mW)			73.72		73.72	
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	$\begin{aligned} & \text{min of} \\ & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)						
Associated	z_1	Z_{s}	(cm)						
Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	Z_{sp}	Z_b	(cm)					1.6	
	Z@PII _{.3max}	Z at max $I_{pi\alpha}$	(cm)	1.6					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)					0.45	
	f_c	f_{awf}	(MHz)	6.32		6.32		6.33	
	Dim of	Dim of A _{aprt}	X (cm)			2.05		2.05	
	A _{aprt}	Dilli Of Aaprt	Y (cm)			0.45		0.45	
	PD	$t_{\rm d}$	(µsec)	0.62					
	PRF	prr	(Hz)	2798.5					
	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	1.86					
Other	d _{eq} @PII _{max}	d _{eq} at max I _{pi}	(cm)					0.45	
Information	Focal	Focal Length	FL_{x} (cm)			1.25			
	Length	1 ocai Lengui	FLy (cm)			1.32			
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	100.41					
Operating	Mode	Mode	NA	PW		PW		PW	
Control	Focus	Focus	(cm)	2		2		3	
Conditions	Power	Power	(%)	100		100		100	

Transducer Model: <u>L7R-E</u> Operating Mode: <u>M</u>

		<u> </u>	-		<u> </u>	TIS		TIB	
	Inde	ex Label		MI		non	-scan		TIC
	muc	A Lubei		1711	Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	110
Global Maxi	mum Index Va	alue		0.7		4.1		1.5	
	p _{r.3}	$p_{r,^{lpha}}$	(MPa)	1.71					
	\mathbf{W}_{o}	P	(mW)			136.51		139.30	
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	$\begin{aligned} & \text{min of} \\ & & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)						
Associated	z_1	Z_{s}	(cm)						
Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	Z_{sp}	Z_b	(cm)					1.8	
	Z@PII.3max	Z at max $I_{pi\alpha}$	(cm)	2.6					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)					0.95	
	f_c	f_{awf}	(MHz)	6.05		6.18		6.05	
	Dim of	Dim of A _{aprt}	X (cm)			2.05		2.05	
	A _{aprt}	Dilli Of Aaprt	Y (cm)			0.45		0.45	
	PD	t_d	(µsec)	0.22					
	PRF	prr	(Hz)	2655.3					
	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	2.52					
Other	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)					0.89	
Information	Focal	Focal Length	FL_{x} (cm)			1.25			
	Length	1 ocai Lengui	FLy (cm)			1.31			
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	134.51					
Operating	Mode	Mode	NA	M		M		M	
Control	Focus	Focus	(cm)	2		2		2	
Conditions	Power	Power	(%)	100		100		100	

Transducer Model: <u>V6-EV</u> Operating Mode: <u>B</u>

		<u> </u>	_	l l l l l l l l l l l l l l l l l l l		TIS		TIB	
	Inde	ex Label		MI		non-	scan		TIC
	mu	ex Euser		1711	Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	110
Global Maxi	mum Index Va	alue		0.7	0.4				
	$p_{r.3}$	$p_{r,^{\scriptscriptstyle{lpha}}}$	(MPa)	1.47					
	W_{o}	P	(mW)		43.65				
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	$\begin{aligned} & \text{min of} \\ & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)						
Associated	z_1	$Z_{\rm s}$	(cm)						
Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	Z_{sp}	Z_b	(cm)						
	z@PII _{.3max}	Z at max $I_{pi\alpha}$	(cm)	2.5					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	f_{awf}	(MHz)	4.98	5.14				
	Dim of	Dim of A _{aprt}	X (cm)		1.22				
	A_{aprt}	Dilli Of Aaprt	Y (cm)		0.90				
	PD	t _d	(µsec)	0.32					
	PRF	prr	(Hz)	7122.5					
	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	1.96					
Other	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)						
Information	Focal	Focal Length	FL_{x} (cm)		2.26				
	Length	Total Ethgui	FLy (cm)		2.13				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	62.32					
Operating	Mode	Mode	NA	В	В				
Control	Focus	Focus	(cm)	3	2				
Conditions	Power	Power	(%)	100	100				

Transducer Model: <u>V6-EV</u> Operating Mode: <u>THI-B</u>

	squeer wio	ici. <u>V 0-12 V</u>		Ü	vioue. <u>111.</u>	TIS		TIB	
	Inde	x Label		MI		non-	scan		TIC
	Thuc	A Dubei		1711	Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	110
Global Maxi	mum Index Va	alue		0.6	0.3				
	$p_{r.3}$	$p_{r,^{lpha}}$	(MPa)	1.26					
	W_{o}	P	(mW)		43.55				
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	$\begin{aligned} & \text{min of} \\ & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)						
Associated	\mathbf{z}_1	$Z_{\rm s}$	(cm)						
Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	Z_{sp}	Z_b	(cm)						
	Z@PII _{.3max}	Z at max $I_{pi\alpha}$	(cm)	2.5					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	f_{awf}	(MHz)	4.84	5.02				
	Dim of	Dim of A _{aprt}	X (cm)		1.22				
	A_{aprt}	Dilli Of A _{aprt}	Y (cm)		0.90				
	PD	$t_{\rm d}$	(µsec)	0.28					
	PRF	prr	(Hz)	7098.56					
	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	1.94					
Other	d _{eq} @PII _{max}	d _{eq} at max I _{pi}	(cm)						
Information	Focal	Focal Length	FL _x (cm)		2.20				
	Length	rocai Lengui	FLy (cm)		2.11				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	55.96					
Operating	Mode	Mode	NA	THI-B	THI-B				
Control	Focus	Focus	(cm)	3	2				
Conditions	Power	Power	(%)	100	100				

Transducer Model: <u>V6-EV</u> Operating Mode: <u>B+C</u>

			_		vioue. <u>Di</u>	TIS		TIB	
	Inde	ex Label		MI		non-	scan		TIC
	muc	A Lauci		1711	Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Maxi	mum Index Va	alue		0.4	0.8				
	$p_{r.3}$	$p_{r,^{\alpha}}$	(MPa)	0.87					
	W_{o}	P	(mW)		77.62				
	min of [W _{.3} (z ₁), I _{TA.3} (z ₁)]	$\begin{aligned} & \text{min of} \\ & & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)						
Associated	z_1	Z_{s}	(cm)						
Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	z_{sp}	Z_b	(cm)						
	Z@PII _{.3max}	Z at max $I_{pi \alpha}$	(cm)	3.5					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	$ m f_{awf}$	(MHz)	4.03	5.24				
	Dim of	Dim of A _{aprt}	X (cm)		1.22				
	A _{aprt}	Dilli Of Aaprt	Y (cm)		0.90				
	PD	t _d	(µsec)	1.18					
	PRF	prr	(Hz)	5003.2					
	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	1.26					
Other	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)						
Information	Focal	Focal Length	FL_{x} (cm)		2.36				
	Length	1 ocai Length	FLy (cm)		2.24				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	35.46					
Operating	Mode	Mode	NA	С	C				
Control	Focus	Focus	(cm)	4	3				
Conditions	Power	Power	(%)	100	100				

Transducer Model: <u>V6-EV</u> Operating Mode: <u>B+C+PW</u>

	squeer wio	iei. <u>vo-Ev</u>	-		vioue. <u>D+</u>	TIS		TIB	
	Inde	ex Label		MI		non-	scan		TIC
	muc	ALAUCI		1711	Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	110
Global Maxin	mum Index Va	alue		0.5			0.9	1.9	
	$p_{r.3}$	$p_{r,^{lpha}}$	(MPa)	1.12					
	W_{o}	P	(mW)					72.86	
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	$\begin{aligned} & \text{min of} \\ & & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)				38.26		
Associated	\mathbf{z}_1	Z_{s}	(cm)				1.8		
Acoustic	Z _{bp}	Z_{bp}	(cm)				1.8		
Parameter	Z_{sp}	Z_b	(cm)					1.9	
	Z@PII _{.3max}	Z at max $I_{pi \alpha}$	(cm)	4.5					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)					0.44	
	f_c	$ m f_{awf}$	(MHz)	5.16			5.16	5.18	
	Dim of	Dim of A _{aprt}	X (cm)				1.22	1.22	
	A _{aprt}	Dilli Of Aaprt	Y (cm)				0.90	0.90	
	PD	t _d	(µsec)	0.68					
	PRF	prr	(Hz)	7133.5					
	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	1.62					
Other	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)					0.44	
Information	Focal	Focal Length	FL_{x} (cm)				1.45		
	Length	1 ocai Length	FLy (cm)				1.36		
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	36.7					
Operating	Mode	Mode	NA	PW			PW	PW	
Control	Focus	Focus	(cm)	4			4	4	
Conditions	Power	Power	(%)	100			100	100	

Transducer Model: <u>V6-EV</u> Operating Mode: <u>M</u>

	squeer wioc	ici. <u>v 0-12 v</u>		crating 1		TIS		TIB	
	Inde	ex Label		MI		non-	scan		TIC
	muc	Zalavci		1711	Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Maxi	mum Index Va	ılue		0.8			0.3	1.2	
	$p_{r.3}$	$p_{r,^{\scriptscriptstyle{lpha}}}$	(MPa)	1.74					
	W_{o}	P	(mW)					23.32	
	min of [W _{.3} (z ₁), I _{TA.3} (z ₁)]	$\begin{aligned} & \text{min of} \\ & & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)				13.32		
Associated	z_1	$Z_{\rm s}$	(cm)				1.8		
Acoustic	Z _{bp}	Z_{bp}	(cm)				1.7		
Parameter	Z_{sp}	Z_b	(cm)					2.0	
	z@PII _{.3max}	Z at max $I_{pi \alpha}$	(cm)	3.0					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)					0.19	
	f_c	f_{awf}	(MHz)	4.86			4.84	4.84	
	Dim of	Dim of A _{aprt}	X (cm)				1.22	1.22	
	A _{aprt}	Dilli Of Aaprt	Y (cm)				0.90	0.90	
	PD	t_d	(µsec)	0.31					
	PRF	prr	(Hz)	6899.5					
	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	2.38					
Other	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)					0.22	
Information	Focal	Focal Length	FL_{x} (cm)				1.17		
	Length	Total Length	FLy (cm)				1.25		
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	118.95					
Operating	Mode	Mode	NA	M			M	M	
Control	Focus	Focus	(cm)	3			3	3	
Conditions	Power	Power	(%)	100			100	100	

Transducer Model: <u>CW2-E</u> Operating Mode: <u>B+C+CW</u>

				1	9	TIS		TIB	
	Index	k Label		MI		non-	scan		TIC
	Index	Lubei		1711	Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Max	i mum Index V	alue		0.5			0.5	0.8	0.9
	p _{r.3}	р _{г, а}	(MPa)	0.66					
	\mathbf{W}_{o}	P	(mW)					78.81	78.52
	min of [W _{.3} (z ₁), I _{TA.3} (z ₁)]	$\begin{aligned} & \text{min of} \\ & & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)				36.09		
Associated	z_1	Z_{s}	(cm)				3.9		
Acoustic	Z _{bp}	Z_{bp}	(cm)				2.8		
Parameter	Z _{sp}	Z_b	(cm)					3.5	
	Z@PII.3max	Z at max $I_{pi \alpha}$	(cm)	4.3					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)					1.13	
	f_c	$f_{ m awf}$	(MHz)	1.8			2.81	2.89	2.85
	Dim of	Dim of A _{aprt}	X (cm)				1.22	1.22	1.22
	A _{aprt}	Dim Of Aaprt	Y (cm)				0.90	0.90	0.90
	PD	t _d	(µsec)	0.85					
	PRF	prr	(Hz)	0					
	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	0.75					
	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)					1.07	
Other Information	Focal	Focal Length	FL _x (cm)				2.32		2.22
	Length	rocai Length	FLy (cm)				2.16		2.19
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	9.22					
Operating	Mode	Mode	NA	CW			CW	CW	CW
Control	Focus	Focus	(cm)	3			3	3	3
Conditions	Power	Power	(%)	100			100	100	100

Transducer Model: <u>T5-E</u> Operating Mode: <u>B</u>

	iisuucei ivic	ntei. <u>13-E</u>		<u> </u>	g 100de. <u>D</u>	TIS		TIB	
	Inde	x Label		MI		non-	scan		TIC
	muez	A Labei		IVII	Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	TIC
Global Max	imum Index V	'alue		1.4	1.6				
	p _{r.3}	$p_{r,^{lpha}}$	(MPa)	1.38					
	W _o	P	(mW)		246.51				
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	$\begin{aligned} & \text{min of} \\ & & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)						
	z_1	Z_{s}	(cm)						
Associated	z _{bp}	Z_{bp}	(cm)						
Acoustic	z_{sp}	Z_{b}	(cm)						
Parameter	z@PII _{.3max}	Z at max $I_{pi\alpha}$	(cm)	4.6					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	$ m f_{awf}$	(MHz)	3.49	3.62				
	Dim of	Dim of A _{aprt}	X (cm)		1.92				
	A _{aprt}	Dilli Of Aaprt	Y (cm)		1.40				
	PD	t _d	(µsec)	0.95					
	PRF	prr	(Hz)	3122.6					
	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	3.25					
Other	d _{eq} @PII _{max}	d _{eq} at max I _{pi}	(cm)						
Information			FL_x		1.25				
	Focal	Focal Length	(cm)		1.23				
	Length		FLy (cm)		1.26				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	189.7					
Operating	Mode	Mode	NA	В	В				
Control	Focus	Focus	(cm)	9	4				
Conditions	Power	Power	(%)	100	100				

Transducer Model: <u>T5-E</u> Operating Mode: <u>THI-B</u>

		70 L		<u> </u>	, would <u>r</u>	TIS		TIB	
	Inde	x Label		MI		non-	scan		TIC
	muc	24001		1122	Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	110
Global Max	imum Index V	alue alue		1.2	1.1				
	$p_{r.3}$	$p_{r,^{lpha}}$	(MPa)	1.26					
	W_{o}	P	(mW)		246.52				
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	$\begin{aligned} & \text{min of} \\ & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)						
	z_1	$Z_{\rm s}$	(cm)						
Associated	Z _{bp}	Z_{bp}	(cm)						
Acoustic Parameter	Z_{sp}	Z_b	(cm)						
Parameter	z@PII _{.3max}	Z at max $I_{pi\alpha}$	(cm)	4.5					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	f_{awf}	(MHz)	3.35	3.39				
	Dim of	Dim of A _{aprt}	X (cm)		1.92				
	A _{aprt}	Dilli Of Aaprt	Y (cm)		1.40				
	PD	t _d	(µsec)	0.85					
	PRF	prr	(Hz)	3116.2					
	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	3.15					
Other	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)						
Information			FL_x		1.16				
imormation	Focal	Focal Length	(cm)		1.10				
	Length	Total Length	FLy (cm)		1.15				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	172.65					
Operating	Mode	Mode	NA	THI-B	THI-B				
Control	Focus	Focus	(cm)	9	4				
Conditions	Power	Power	(%)	100	100				

Transducer Model: <u>T5-E</u> Operating Mode: <u>B+C</u>

	iisuucei ivic	nuel. <u>13-E</u>			1000e. <u>D+</u>	TIS		TIB	
	Indo	x Label		MI		non-	scan		TIC
	muc	x Label		1711	Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	ne
Global Max	imum Index V	alue		0.7	0.7				
	p _{r.3}	$p_{r,^{lpha}}$	(MPa)	0.88					
	Wo	P	(mW)		78.56				
	min of [W _{.3} (z ₁), I _{TA.3} (z ₁)]	$\begin{aligned} & \text{min of} \\ & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)						
	\mathbf{z}_1	Z_{s}	(cm)						
Associated	Z _{bp}	$Z_{ m bp}$	(cm)						
Acoustic	Z_{sp}	Z_b	(cm)						
Parameter	z@PII _{.3max}	Z at max $I_{pi\alpha}$	(cm)	4.2					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	f_{awf}	(MHz)	3.98	3.65				
	Dim of	Dim of A _{aprt}	X (cm)		1.92				
	A_{aprt}	Dilli Of A _{aprt}	Y (cm)		1.40				
	PD	$t_{ m d}$	(µsec)	1.2					
	PRF	prr	(Hz)	5122.6					
	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	1.04					
Other	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)						
Information			FL _x		2.45				
	Focal Length	Focal Length	(cm) FLy						
			(cm)		2.36				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	26.04					
Operating	Mode	Mode	NA	С	С				
Control	Focus	Focus	(cm)	4	3				
Conditions	Power	Power	(%)	100	100				

Transducer Model: <u>T5-E</u> Operating Mode: <u>B+C+PW</u>

	iisuucei ivio	uci. <u>13-E</u>		, · · · · · · · · · · · · · · · · · · ·	110ue. <u>D+</u>	TIS		TIB	
	Indo	r I obol		MT		non-	scan		TIC
	inde	x Label		MI	Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	пс
Global Max	imum Index V	alue		0.7		0.5		2.9	
	p _{r.3}	$p_{r,^{lpha}}$	(MPa)	0.88					
	W_{o}	P	(mW)			69.72		108.62	
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	$\begin{aligned} & \text{min of} \\ & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)						
Associated	z_1	$Z_{\rm s}$	(cm)						
Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	z_{sp}	Z_{b}	(cm)					4.2	
	z@PII _{.3max}	Z at max $I_{pi\alpha}$	(cm)	4.7					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)					0.32	
	f_c	f_{awf}	(MHz)	1.75		1.85		1.78	
	Dim of	Dim of A _{aprt}	X (cm)			1.92		1.92	
	A_{aprt}	Diffi Of 7 taprt	Y (cm)			1.40		1.40	
	PD	t _d	(µsec)	1.5					
	PRF	prr	(Hz)	4688.1					
	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	1.52					
Other	d _{eq} @PII _{max}	d _{eq} at max I _{pi}	(cm)					0.32	
Other Information	Focal	Focal Length	FL _x (cm)			1.35			
	Length	Total Length	FLy (cm)			1.42			
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	35.7					
Operating	Mode	Mode	NA	PW		PW		PW	
Control	Focus	Focus	(cm)	1		5		5	
Conditions	Power	Power	(%)	100		100		100	

Transducer Model: <u>T5-E</u> Operating Mode: <u>M</u>

			•		ivioue. <u>ivi</u>	TIS		TIB	
	Inde	x Label		MI		non-	scan		TIC
	muc	A Label		1711	Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	TIC .
Global Max	imum Index V	alue		0.9		0.5		2.1	
	p _{r.3}	$p_{r,^{lpha}}$	(MPa)	1.72					
	\mathbf{W}_{o}	P	(mW)			76.32		76.91	
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	$\begin{aligned} & \text{min of} \\ & & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)						
A	z_1	$Z_{\rm s}$	(cm)						
Associated Acoustic	z _{bp}	Z_{bp}	(cm)						
Parameter	Z _{sp}	Z_b	(cm)					2.9	
Turumeter	Z@PII _{.3max}	Z at max $I_{pi\alpha}$	(cm)	2.5					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)					0.44	
	f_c	$ m f_{awf}$	(MHz)	1.89		1.89		1.88	
	Dim of	Dim of A _{aprt}	X (cm)			1.92		1.92	
	A _{aprt}	Dilli Of A _{aprt}	Y (cm)			1.40		1.40	
	PD	t _d	(µsec)	0.45					
	PRF	prr	(Hz)	5233.6					
	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	1.59					
	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)					0.32	
Other Information	Focal	Focal Length	FL _x (cm)			1.56			
	Length	r ocar Length	FLy (cm)			1.66			
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	89.2					
Operating	Mode	Mode	NA	M		M		M	
Control	Focus	Focus	(cm)	5		5		6	
Conditions	Power	Power	(%)	100		100		100	

Transducer Model: <u>MT5-E</u> Operating Mode: <u>B</u>

		den <u>mis L</u>				TIS		TIB	
	Index	x Label		MI	G	non-	scan		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Max	mum Index V	alue		1.1	1.2				
	p _{r.3}	$p_{r,^{\alpha}}$	(MPa)	1.38					
	W_{o}	P	(mW)		246.50				
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	$\begin{aligned} & \text{min of} \\ & & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)						
	z_1	Z_{s}	(cm)						
Associated	Z _{bp}	Z_{bp}	(cm)						
Acoustic Parameter	Z_{sp}	Z_{b}	(cm)						
Parameter	Z@PII _{.3max}	Z at max $I_{pi\alpha}$	(cm)	4.5					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	$ m f_{awf}$	(MHz)	3.35	3.41				
	Dim of	Dim of A _{aprt}	X (cm)		1.92				
	A_{aprt}	Dilli Of A _{aprt}	Y (cm)		1.40				
	PD	t_d	(µsec)	0.88					
	PRF	prr	(Hz)	3022.5					
	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	3.25					
Other	d _{eq} @PII _{max}	d _{eq} at max I _{pi}	(cm)						
Information	Focal	Focal Length	FL _x (cm)		1.25				
	Length	Pocar Length	FLy (cm)		1.26				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	161.2					
Operating	Mode	Mode	NA	В	В				
Control	Focus	Focus	(cm)	9	4				
Conditions	Power	Power	(%)	100	100				

Transducer Model: <u>MT5-E</u> Operating Mode: <u>THI-B</u>

						TIS		TIB	
	Index	x Label		MI	Coon	non-	scan	non goon	TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Max	imum Index V	alue alue		1.0	1.1				
	p _{r.3}	$p_{r,^{lpha}}$	(MPa)	1.36					
	\mathbf{W}_{o}	P	(mW)		246.49				
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	$\begin{aligned} & \text{min of} \\ & & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)						
Associated	z_1	$Z_{\rm s}$	(cm)						
Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	Z_{sp}	Z_b	(cm)						
	z@PII _{.3max}	Z at max $I_{pi\alpha}$	(cm)	4.6					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	$ m f_{awf}$	(MHz)	3.31	3.36				
	Dim of	Dim of A _{aprt}	X (cm)		1.92				
	A _{aprt}	Dilli Of Aaprt	Y (cm)		1.40				
	PD	t _d	(µsec)	0.85					
	PRF	prr	(Hz)	3018.56					
	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	3.19					
Other	d _{eq} @PII _{max}	d _{eq} at max I _{pi}	(cm)						
Information	Focal	Focal Length	FL _x (cm)		1.21				
	Length	rocai Length	FLy (cm)		1.21				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	154.6					
Operating	Mode	Mode	NA	THI-B	THI-B				
Control	Focus	Focus	(cm)	9	4				
Conditions	Power	Power	(%)	100	100				

Transducer Model: MT5-E Operating Mode: B+C

		den <u>mis L</u>			g Wiode. <u>D</u>	TIS		TIB	
	Index	x Label		MI	C	non-	scan		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Max	imum Index V	alue		0.6	0.5				
	$p_{r.3}$	$p_{r,^{\alpha}}$	(MPa)	0.71					
	\mathbf{W}_{o}	P	(mW)		78.56				
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	$\begin{aligned} & \text{min of} \\ & & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)						
Associated	z_1	Z_{s}	(cm)						
Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	Z_{sp}	Z_b	(cm)						
	Z@PII.3max	Z at max $I_{pi\alpha}$	(cm)	4.3					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	$\mathbf{f}_{\mathrm{awf}}$	(MHz)	3.85	3.68				
	Dim of	Dim of Appet	X (cm)		1.92				
	A_{aprt}	Dilli Of Aaprt	Y (cm)		1.40				
	PD	t_d	(µsec)	1.2					
	PRF	prr	(Hz)	5103.5					
	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	1.04					
Other	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)						
Information	Focal	Focal Length	FL _x (cm)		2.45				
	Length	rocai Length	FLy (cm)		2.36				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	26.04					
Operating	Mode	Mode	NA	С	С				
Control	Focus	Focus	(cm)	4	3				
Conditions	Power	Power	(%)	100	100				

Transducer Model: <u>MT5-E</u> Operating Mode: <u>B+C+PW</u>

		den <u>mile E</u>			g Wloue.	TIS		TIB	
	Index	x Label		MI	G.	non-	scan		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Max	imum Index V	alue		0.5		0.4		2.6	
	$p_{r.3}$	$p_{r,^{\alpha}}$	(MPa)	0.75					
	\mathbf{W}_{o}	P	(mW)			69.70		108.65	
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	$\begin{aligned} & \text{min of} \\ & & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)						
Associated	z_1	Z_{s}	(cm)						
Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	z_{sp}	Z_{b}	(cm)					4.2	
	z@PII _{.3max}	Z at max $I_{pi\alpha}$	(cm)	4.7					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)					0.32	
	f_c	$ m f_{awf}$	(MHz)	1.72		1.82		1.78	
	Dim of	Dim of A _{aprt}	X (cm)			1.92		1.92	
	A _{aprt}	Dilli Of Aaprt	Y (cm)			1.40		1.40	
	PD	t _d	(µsec)	1.5					
	PRF	prr	(Hz)	4563.2					
	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	1.52					
0.1	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)					0.32	
Other Information	Focal	Focal Length	FL _x (cm)			1.32			
	Length	r ocar Length	FLy (cm)			1.42			
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	30.26					
Operating	Mode	Mode	NA	PW		PW		PW	
Control	Focus	Focus	(cm)	1		5		5	
Conditions	Power	Power	(%)	100		100		100	

Transducer Model: <u>MT5-E</u> Operating Mode: <u>M</u>

		den <u>mis E</u>			<u> </u>	TIS		TIB	
	Index	x Label		MI	C	non-	scan		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Max	imum Index V	alue		0.8		0.4		2.1	
	p _{r.3}	$p_{r,^{lpha}}$	(MPa)	1.72					
	W_{o}	P	(mW)			76.32		76.94	
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	$\begin{aligned} & \text{min of} \\ & & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)						
Associated	z_1	$Z_{\rm s}$	(cm)						
Associated	Z _{bp}	Z_{bp}	(cm)						
Parameter	z_{sp}	Z_b	(cm)					2.9	
	Z@PII.3max	Z at max $I_{pi \alpha}$	(cm)	2.7					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)					0.44	
	f_c	$\mathbf{f}_{\mathrm{awf}}$	(MHz)	1.82		1.84		1.85	
	Dim of	Dim of A _{aprt}	X (cm)			1.92		1.92	
	A_{aprt}	Dilli Of A _{aprt}	Y (cm)			1.40		1.40	
	PD	t_d	(µsec)	0.45					
	PRF	prr	(Hz)	5166.6					
	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	1.59					
0.1	d _{eq} @PII _{max}	d _{eq} at max I _{pi}	(cm)					0.32	
Other Information	Focal	Focal Length	FL _x (cm)			1.56			
	Length	Tocal Length	FLy (cm)			1.66			
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	76.3					
Operating	Mode	Mode	NA	M		M		M	
Control	Focus	Focus	(cm)	5		5		6	
Conditions	Power	Power	(%)	100		100		100	

Transducer Model: <u>i7L-E</u> Operating Mode: <u>B</u>

	saucer Moa		•	ing Mode	_	TIS		TIB	
	Inde	ex Label		MI		non-	scan		TIC
				1,22	Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Maxin	mum Index Va	lue		0.8	0.5				
	$p_{r.3}$	$p_{r,\alpha}$	(MPa)	2.08					
	W_{o}	P	(mW)		73.73				
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	$\begin{aligned} & \text{min of} \\ & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)						
Associated	z_1	Z_{s}	(cm)						
Acoustic	z_{bp}	Z_{bp}	(cm)						
Parameter	Z_{sp}	Z_b	(cm)						
	z@PII _{.3max}	Z at max $I_{\text{pi}\alpha}$	(cm)	1.9					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	f_{awf}	(MHz)	6.14	6.13				
	Dim of A _{aprt}	Dim of A _{aprt}	X (cm)		2.048				
	Dilli Of A _{aprt}	Dilli Of Aaprt	Y (cm)		0.65				
	PD	$t_{\rm d}$	(µsec)	0.22					
	PRF	prr	(Hz)	2977.5					
	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	3.08					
Other	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)						
Information	Focal	Focal Length	FL_{x} (cm)		0.21				
	Length	rocai Lengtii	FLy (cm)		0.22				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	178.22					
Operating	Mode	Mode	NA	В	В				
Control	Focus	Focus	(cm)	3	2				
Conditions	Power	Power	(%)	100	100				

Transducer Model: <u>i7L-E</u> Operating Mode: <u>THI-B</u>

	suucei wiou		•			TIS		TIB	
	Inde	ex Label		MI	C	non-	scan		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Maxi	mum Index Va	lue		0.7	0.5				
	p _{r.3}	$p_{r,\alpha}$	(MPa)	2.04					
	W_{o}	P	(mW)		73.73				
	min of [W _{.3} (z ₁), I _{TA.3} (z ₁)]	$\begin{aligned} & \text{min of} \\ & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)						
Associated	z_1	Z_{s}	(cm)						
Acoustic	z _{bp}	Z_{bp}	(cm)						
Parameter	z_{sp}	Z_b	(cm)						
	z@PII _{.3max}	Z at max $I_{pi \alpha}$	(cm)	2.0					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	f_{awf}	(MHz)	6.14	6.14				
	Dim of A _{aprt}	Dim of A _{aprt}	X (cm)		2.048				
	Dilli Of A _{aprt}	Dilli Of Aaprt	Y (cm)		0.65				
	PD	t _d	(µsec)	0.22					
	PRF	prr	(Hz)	2958					
	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	3.08					
Other	d _{eq} @PII _{max}	d _{eq} at max I _{pi}	(cm)						
Information	Focal	Focal Length	FL _x (cm)		0.18				
	Length	Total Length	FLy (cm)		0.21				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	175.22					
Operating	Mode	Mode	NA	THI-B	THI-B				
Control	Focus	Focus	(cm)	3	2				
Conditions	Power	Power	(%)	100	100				

Transducer Model: <u>i7L-E</u> Operating Mode: <u>B+C</u>

	suucei wiou		•			TIS		TIB	
	Inde	ex Label		MI	G	non-	scan		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Maxi	mum Index Va	lue		0.5	0.8				
	p _{r.3}	$p_{r,\alpha}$	(MPa)	1.34					
	W_{o}	P	(mW)		105.66				
	min of [W _{.3} (z ₁), I _{TA.3} (z ₁)]	$\begin{aligned} & \text{min of} \\ & & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)						
Associated	z_1	Z_{s}	(cm)						
Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	Z_{sp}	Z_b	(cm)						
	z@PII _{.3max}	Z at max $I_{pi \alpha}$	(cm)	1.8					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	f_{awf}	(MHz)	6.34	6.36				
	Dim of A _{aprt}	Dim of A _{aprt}	X (cm)		2.048				
	Dilli Of A _{aprt}	Dilli Of A _{aprt}	Y (cm)		0.65				
	PD	$t_{\rm d}$	(µsec)	0.78					
	PRF	prr	(Hz)	7025.4					
	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	2.03					
Other	d _{eq} @PII _{max}	d _{eq} at max I _{pi}	(cm)						
Information	Focal	Focal Length	FL_{x} (cm)		0.18				
	Length	1 ocai Lengui	FLy (cm)		0.25				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	73.47					
Operating	Mode	Mode	NA	С	С				
Control	Focus	Focus	(cm)	3	2				
Conditions	Power	Power	(%)	100	100				

Transducer Model: <u>i7L-E</u> Operating Mode: <u>B+C+PW</u>

	Sudeel Wiod		_			TIS		TIB	
	Inde	ex Label		MI	Scan	non-	scan	non coon	TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Maxii	mum Index Va	lue		0.6		2.2		1.9	
	$p_{r.3}$	$p_{r,\alpha}$	(MPa)	1.58					
	W_{o}	P	(mW)			73.73		73.73	
	min of [W _{.3} (z ₁), I _{TA.3} (z ₁)]	$\begin{aligned} & \text{min of} \\ & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)						
Associated	z_1	Z_{s}	(cm)						
Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	Z_{sp}	Z_b	(cm)					1.94	
	z@PII _{.3max}	Z at max $I_{\text{pi}\alpha}$	(cm)	1.8					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)					0.86	
	f_c	f_{awf}	(MHz)	6.31		6.35		6.36	
	Dim of A _{aprt}	Dim of A _{aprt}	X (cm)			2.048		2.048	
	Dilli Of Aaprt	Diffi of Aaprt	Y (cm)			0.65		0.65	
	PD	t _d	(µsec)	0.59					
	PRF	prr	(Hz)	2894.5					
	p _r @PII _{max}	p _r at max I _{pi}	(MPa)	2.27					
Other	d _{eq} @PII _{max}	d _{eq} at max I _{pi}	(cm)					0.45	
Information	Focal	Focal Length	FL_{x} (cm)			0.34			
	Length	Total Bengin	FLy (cm)			0.32			
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	134.23					
Operating	Mode	Mode	NA	PW		PW		PW	
Control	Focus	Focus	(cm)	3		2		3.5	
Conditions	Power	Power	(%)	100		100		100	

Transducer Model: <u>i7L-E</u> Operating Mode: <u>M</u>

			_			TIS		TIB	
	Inde	ex Label		MI	G	non	scan		TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Maxin	mum Index Va	lue		0.7		4.1		1.6	
	$p_{r.3}$	$p_{r,\alpha}$	(MPa)	1.82					
	W_{o}	P	(mW)			139.60		138.50	
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	$\begin{aligned} & \text{min of} \\ & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)						
	z_1	$Z_{\rm s}$	(cm)						
Associated Acoustic	Z _{bp}	Z_{bp}	(cm)						
Parameter	z_{sp}	Z_{b}	(cm)					2.0	
Tarameter	Z@PII _{.3max}	Z at max $I_{pi \alpha}$	(cm)	2.0					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)					0.88	
	f_c	$f_{ m awf}$	(MHz)	6.11		6.18		6.07	
	Dim of A _{aprt}	Dim of A _{aprt}	X (cm)			2.048		2.048	
	Dilli Of A _{aprt}	Dim Of Aaprt	Y (cm)			0.65		0.65	
	PD	t_d	(µsec)	0.21					
	PRF	prr	(Hz)	2905.3					
	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	2.66					
Other Information	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)					0.87	
Illiormation	Focal	Es sal I an ath	FL _x (cm)			0.12			
	Length	Focal Length	FLy (cm)			0.21			
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	156.89					
Operating	Mode	Mode	NA	M		M		M	
Control	Focus	Focus	(cm)	2		2		2	
Conditions	Power	Power	(%)	100		100		100	

Transducer Model: <u>L18-E</u> Operating Mode: <u>B</u>

	isuucei Mio		•	amig Mo		TIS		TIB	
	Ind	ex Label		MI		non-	scan		TIC
	IIIu	CA DUDCI		1411	Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	110
Global Maxi	mum Index V	alue		0.6	0.1				
	$p_{r.3}$	$p_{\mathrm{r},\alpha}$	(MPa)	1.39					
	W_{o}	P	(mW)		8.19				
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	$\begin{aligned} & \text{min of} \\ & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)						
	\mathbf{z}_1	Z_{s}	(cm)						
Associated	Z _{bp}	Z_{bp}	(cm)						
Acoustic Parameter	z_{sp}	Z_b	(cm)						
Tarameter	Z@PII.3max	Z at max $I_{pi \alpha}$	(cm)	1.8					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	f_{awf}	(MHz)	15.62	15.32				
	Dim of	Dim of A _{aprt}	X (cm)		2.048				
	A_{aprt}	Dilli Of A _{aprt}	Y (cm)		0.45				
	PD	$t_{\rm d}$	(µsec)	0.23					
	PRF	prr	(Hz)	5319.1					
	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	2.03					
Other Information	d _{eq} @PII _{max}	d _{eq} at max I _{pi}	(cm)						
IIIIOIIIIatioii	Focal	Food Longth	FL_{x} (cm)		0.24				
	Length	Focal Length	FLy (cm)		0.26				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	124.55					
Operating	Mode	Mode	NA	В	В				
Control	Focus	Focus	(cm)	2.5	2.5				
Conditions	Power	Power	(%)	100	100				

Transducer Model: <u>L18-E</u> Operating Mode: <u>THI-B</u>

					uc. <u>1111 1</u>	TIS		TIB	
	Ind	ex Label		MI		non-s	scan		TIC
	Inu	CA DUDCI		1411	Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Maxi	mum Index V	alue		0.5	0.1				
	p _{r.3}	$p_{r,\alpha}$	(MPa)	1.36					
	\mathbf{W}_{o}	P	(mW)		8.19				
	min of [W _{.3} (z ₁), I _{TA.3} (z ₁)]	$\begin{aligned} & \text{min of} \\ & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)						
	z_1	Z_{s}	(cm)						
Associated	Z _{bp}	Z_{bp}	(cm)						
Acoustic Parameter	Z_{sp}	Z_b	(cm)						
1 arameter	Z@PII.3max	Z at max $I_{pi \alpha}$	(cm)	1.9					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	f_{awf}	(MHz)	15.44	15.36				
	Dim of	Dim of A	X (cm)		2.048				
	A _{aprt}	Dim of A _{aprt}	Y (cm)		0.45				
	PD	$t_{\rm d}$	(µsec)	0.23					
	PRF	prr	(Hz)	5206.2					
	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	2.03					
Other Information	d _{eq} @PII _{max}	d _{eq} at max I _{pi}	(cm)						
mormation	Focal	Essal Laurath	FL _x (cm)		0.24				
	Length	Focal Length	FLy (cm)		0.21				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	122					
Operating	Mode	Mode	NA	THI-B	THI-B				
Control	Focus	Focus	(cm)	2.5	2.5				
Conditions	Power	Power	(%)	100	100				

Transducer Model: <u>L18-E</u> Operating Mode: <u>B+C</u>

						TIS		TIB	
	Ind	ex Label		MI		non-s	scan		TIC
	Inu	CA DUDCI		1411	Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Maxi	mum Index V	alue		0.5	0.4				
	p _{r.3}	$p_{r,\alpha}$	(MPa)	1.18					
	W_{o}	P	(mW)		57.34				
	min of [W _{.3} (z ₁), I _{TA.3} (z ₁)]	$\begin{aligned} & \text{min of} \\ & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)						
	z_1	Z_{s}	(cm)						
Associated	Z _{bp}	Z_{bp}	(cm)						
Acoustic Parameter	Z_{sp}	Z_b	(cm)						
Tarameter	Z@PII.3max	Z at max $I_{pi \alpha}$	(cm)	1.6					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)						
	f_c	f_{awf}	(MHz)	16.25	16.18				
	Dim of	Dim of A	X (cm)		2.048				
	A _{aprt}	Dim of A _{aprt}	Y (cm)		0.45				
	PD	$t_{\rm d}$	(µsec)	0.86					
	PRF	prr	(Hz)	7662.3					
	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	1.51					
Other Information	d _{eq} @PII _{max}	d _{eq} at max I _{pi}	(cm)						
mormation	Focal	Essal Laurath	FL _x (cm)		0.26				
	Length	Focal Length	FLy (cm)		0.19				
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	72.65					
Operating	Mode	Mode	NA	С	С				
Control	Focus	Focus	(cm)	2.5	2.5				
Conditions	Power	Power	(%)	100	100				

Transducer Model: <u>L18-E</u> Operating Mode: <u>B+C+PW</u>

				TIS		TIB			
	Ind	ex Label		MI		non-s	scan	non-scan	TIC
	1114	CA Euroci		1.22	Scan	A _{aprt} ≤1	A _{aprt} >1		
Global Maxi	mum Index V	alue		0.2			1.4	1.9	
	p _{r.3}	$p_{r,\alpha}$	(MPa)	0.54					
	W_{o}	P	(mW)					106.50	
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	$\begin{aligned} & \text{min of} \\ & & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)				54.21		
Associated	z_1	Z_{s}	(cm)				1.8		
Acoustic	Z _{bp}	Z_{bp}	(cm)				1.7		
Parameter	Z_{sp}	Z_b	(cm)					1.8	
	Z@PII _{.3max}	Z at max $I_{pi \alpha}$	(cm)	3.0					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)					0.86	
	f_c	${ m f}_{ m awf}$	(MHz)	16.56			16.42	16.35	
	Dim of	Dim of A _{aprt}	X (cm)				2.048	2.048	
	A_{aprt}	Dilli Of A _{aprt}	Y (cm)				0.45	0.45	
	PD	$t_{\rm d}$	(µsec)	0.83					
	PRF	prr	(Hz)	8051.5					
	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	0.75					
Other	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)					0.86	
Information	Focal	Escal I condi	FL _x (cm)				0.25		
	Length	Focal Length	FLy (cm)				0.42		
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	25.36					
Operating	Mode	Mode	NA	PW			PW	PW	
Control	Focus	Focus	(cm)	2.5			2.5	2.5	
Conditions	Power	Power	(%)	100			100	100	

Transducer Model: <u>L18-E</u> Operating Mode: <u>M</u>

					TIS		TIB		
	Inde	ex Label		MI		non-s	scan]	TIC
					Scan	A _{aprt} ≤1	A _{aprt} >1	non-scan	
Global Maxi	mum Index V	alue		0.5			0.6	1.0	
	p _{r.3}	$p_{r,\alpha}$	(MPa)	1.21					
	W_{o}	P	(mW)					40.98	
	$\begin{aligned} & \text{min of} \\ & [W_{.3}(z_1), \\ & I_{TA.3}(z_1)] \end{aligned}$	$\begin{aligned} & \text{min of} \\ & & [P_{\alpha}(Z_s), I_{ta,\alpha}(Z_s)] \end{aligned}$	(mW)				19.75		
	\mathbf{z}_1	$Z_{\rm s}$	(cm)				1.8		
Associated Acoustic	z_{bp}	Z_{bp}	(cm)				1.8		
Parameter	z_{sp}	Z_b	(cm)					1.8	
Tarameter	Z@PII.3max	Z at max $I_{pi \alpha}$	(cm)	1.8					
	$d_{eq}(z_{sp})$	$d_{eq}(Z_b)$	(cm)					0.67	
	f_c	$ m f_{awf}$	(MHz)	15.85			15.87	15.82	
	Dim of	Dim of A _{aprt}	X (cm)				2.048	2.048	
	A_{aprt}	Dilli Of Aaprt	Y (cm)				0.45	0.45	
	PD	t _d	(µsec)	0.23					
	PRF	prr	(Hz)	5326.8					
	p _r @PII _{max}	p_r at max I_{pi}	(MPa)	1.74					
Other	d _{eq} @PII _{max}	d_{eq} at max I_{pi}	(cm)					0.67	
Information	Focal	Es sal I an ath	FL _x (cm)				0.23		
	Length	Focal Length	FLy (cm)				0.33		
	I _{PA.3} @ MI _{max}	I _{pi} at max MI	(W/cm ²)	82.2					
Operating	Mode	Mode	NA	M			M	M	
Control	Focus	Focus	(cm)	2.5			2.5	2	
Conditions	Power	Power	(%)	100			100	100	

Essential Performance

Patient, operator, and other persons are not exposed to acoustic energy from me equipment in normal use Acoustic output switched off when image freeze facility is enabled

Free from noise on a waveform or artefacts or distortion in an image or error of a displayed numerical value

Probe will output power when diagnosis, value of MI, TI and acoustic power will displayed in the interface of ultrasound diagnostic system correctly

All components are fixed, could not result in unexpectedly movement

Appendix C: Guidance and Manufacturer's Declaration

1. Guidance and manufacturer's declaration – electromagnetic emissions

The EBIT is intended for use in the electromagnetic environment specified below. The customer or the user of the EBIT should assure that it is used in such an environment.

Emissions test	Compliance	Electromagnetic environment –
		guidance
RF emissions	Group 1	The EBIT uses RF energy only for
CISPR 11		its internal function. Therefore, its
		RF emissions are very low and are
		not likely to cause any interference
		in nearby electronic
		equipment.
RF emissions	Class A	The EBIT is suitable for use in all
CISPR 11		establishments, including domestic
		stablishments and those directly
Harmonic emissions	Class A	connected to the public low-voltage
IEC 61000-3-2		power supply network
Voltage fluctuations/	Complies	that supplies buildings used for
flicker emissions		domestic purposes.
IEC 61000-3-3		

2. Guidance and manufacturer's declaration – electromagnetic immunity

The EBIT is intended for use in the electromagnetic environment the EBIT should assure that it is used in such an environment.

Immunity test	IEC 60601 test level	Compliance level	Electromagnetic environment – guidance
Electrostatic discharge (ESD) IEC 61000-4-2	±6 kV contact ±8 kV air	±6 kV contact ±8 kV air	Floors should be wood, concrete or ceramic tile. If floors are covered with synthetic material, the relative humidity should be at least 30 %.
Electrical fast transient/burst IEC 61000-4-4	±2 kV for power supply lines ±1 kV for input/output lines	±2 kV for power supply lines ±1 kV for input/output lines	Mains power quality should be that of a typical commercial or hospital environment.
Surge IEC 61000-4-5	±1 kV line(s) to line(s)	±1 kV line(s) to line(s)	Mains power quality should be that

	±2 kV line(s) to earth	±2 kV line(s) to earth	of a typical commercial or
			hospital
			environment.
interruptions	<5 % UT	<5 % UT	Mains power quality
and	(>95 % dip in UT)	(>95 % dip in UT)	should be that
voltage	for 0,5 cycle	for 0,5 cycle	of a typical commercial or
variations	40 % UT	40 % UT	hospital
on power	(60 % dip in UT)	(60 % dip in UT)	environment. If the user of
supply	for 5 cycles	for 5 cycles	the
input lines	70 % UT	70 % UT	EBIT requires
IEC	(30 % dip in UT)	(30 % dip in UT)	continued operation during
61000-4-11	for 25 cycles	for 25 cycles	power
	<5 % UT	<5 % UT	mains interruptions, it is
	(>95 % dip in UT)	(>95 % dip in UT)	recommended that the
	for 5 sec	for 5 sec	EBIT be powered from an
			uninterruptible power
			supply or a
			battery.
Power	3 A/m	3 A/m	Power frequency magnetic
frequency			fields should be at levels
frequency			characteristic of a typical
(50-60 Hz)			location in a typical
magnetic field			commercial or hospital
IEC 61000-4-8			environment.
NOTE UT is the a.c. ma	ins voltage prior to applic	cation of the test level.	

3 Guidance and ma	3 Guidance and manufacturer's declaration – electromagnetic immunity				
The EBIT is intend	The EBIT is intended for use in the electromagnetic environment specified below. The customer or the				
user of the EBIT sh	ould assure that it i	s used in such an e	environment.		
3.1. Immunity	3.1. Immunity IEC 60601 test IEC 60601 test Electromagnetic environment – guidance				
test	level	level			
Conducted RF	3 Vrms	3 Vrms	Portable and mobile RF communications		
IEC 61000-4-6	150 kHz to 80	3 V/m	equipment should be used no closer to any		
Radiated RF	MHz		part of the EBIT, including cables, than the		
IEC 61000-4-3	3 V/m		recommended separation distance calculated		
	80 MHz to 2,5		from the equation applicable to the		
	GHz frequency of the transmitter.				
			Recommended separation distance		

0 11
$d = 1,2 \sqrt{P}$
$d = 1,2 \sqrt{P} $ 80 MHz to 800 MHz
$d=2,3\sqrt{P} $ 800 MHz to 2,5 GHz
$a = 2.3 \ \sqrt{P}$ 800 MHz to 2,5 GHz
where P is the maximum output power rating o
the transmitter in watts (W) according to the
transmitter manufacturer and d is the
recommended separation distance in metres (ı
Field strengths from fixed RF transmitters, as
determined by an electromagnetic site survey,:
should be less than the compliance level in ea
frequency range.b
Interference may occur in the vicinity of
equipment marked with the following symbol:
(((1)))
- '

NOTE 1 At 80 MHz and 800 MHz, the higher frequency range applies.

NOTE 2 These guidelines may not apply in all situations. Electromagnetic propagation is affected by absorption

and reflection from structures, objects and people.

a Field strengths from fixed transmitters, such as base stations for radio (cellular/cordless) telephones and land mobile radios, amateur radio, AM and FM radio broadcast and TV broadcast cannot be predicted theoretically with accuracy. To assess the electromagnetic environment due to fixed RF transmitters, an electromagnetic site survey should be considered. If the measured field strength in the location in which the EBIT is used exceeds the applicable RF compliance level above, the EBIT should be observed to verify normal operation. If abnormal performance is observed, additional measures may be necessary, such as reorienting or relocating the EBIT.

b Over the frequency range 150 kHz to 80 MHz, field strengths should be less than 3 V/m.

Recommended separation distances between

portable and mobile RF communications equipment and the EBIT

The EBIT is intended for use in an electromagnetic environment in which radiated RF disturbances are controlled. The customer or the user of the EBIT can help prevent electromagnetic interference by maintaining a minimum distance between portable and mobile RF communications equipment (transmitters) and the EBIT as recommended below, according to the maximum output power of the communications equipment.

Rated maximum	Separation distance according to frequency of transmitter				
output	m				
power of transmitter W	150 kHz to 80 MHz $d = 1.2 \sqrt{P}$	80 MHz to 800 MHz $d = 1.2 \sqrt{P}$	800 MHz to 2,5 GHz $d = 2,3 \sqrt{P}$		
0,01	0,12	0,12	0,23		
0,1	0,38	0,38	0,73		
1	1,2	1,2	2,3		

10	3,8	3,8	7,3
100	12	12	23

For transmitters rated at a maximum output power not listed above, the recommended separation distance d in metres (m) can be estimated using the equation applicable to the frequency of the transmitter, where P is the maximum output power rating of the transmitter in watts (W) according to the transmitter manufacturer.

NOTE 1 At 80 MHz and 800 MHz, the separation distance for the higher frequency range applies.

NOTE 2 These guidelines may not apply in all situations. Electromagnetic propagation is affected by absorption and reflection from structures, objects and people.

Appendix D: Measurement Results Summary

Measurement	Useful Range	Accuracy
Distance	Full Screen	<±5%
Circumference:	Full Screen	<±5%
trace method, ellipse method		
Area:	Full Screen	<±10%
trace method, ellipse method		
Volume	Full screen	<±10%
Angle	Full screen	<±5%
Time	Full Screen	<±5%
Heart rate	Full Screen	<±5%
Velocity	Full Screen	<±10%

Appendix E: Display Accuracy and Acoustic Measurement Uncertainties

According to IEC60601-2-37 and NEMA UD-3 2004, the display accuracy and acoustic measurement uncertainties are summarized in the table below.

Display accuracy of MI is $\pm 20\%$, and TI is $\pm 40\%$ or <0.1, if MI, TI below 0.5.

Item	Measurement Uncertainty (Percentage, 95% Confidence Value
Center Frequency	±15%
Acoustic Power	±30%
Acoustic Intensity	±30%
Peak Rarefactional Pressure	±15%

Appendix F: Transducer Maximum Surface Temperature

According to the requirements of the section 42.3 in the standard IEC 60601-2-37:2007, the transducer surface temperature has been tested in two kinds of conditions: the transducer suspended in still air or transducer contacting human-tissue mimicking material. The calculation of the expanded uncertainty is based on the ISO Guide tout ye Expression of uncertainty in measurement. Three transducer samples have been tested and the confidence coefficient is at 95%, the value of t.975 is 4.30.

Transducer model	Maximum surface temperature(°C) Contacting human-tissue mimicking material	Maximum surface temperature(°C) Suspending in air	Transducer model	Maximum surface temperature(°C) Contacting human-tissue mimicking material	Maximum surface temperature(°C) Suspending in air
С3-Е	41±1	48±1	L12-D	39±1	48±1
C3S-E	40±1	47 ±1	V7-D	39±2	48±1
V4-EV	40±2	38±1	7B8-E	40±1	48±1
МС6-Е	41±1	46±1	L7R-E	38±2	47±2
L7-E	40±1	47 ±1	V6-EV	40±1	48±1
L7W-E	38±1	48±1	CW2-E	39±1	46±1
МС3-Е	38±2	47 ±2	Т5-Е	40±1	48±1
V6-E	41±1	43±1	C3S-D	38±2	48±1
V7W-E	41±1	43±1	МТ5-Е	40±1	46±1
V7-E	41±1	43±2	L18-E	39±1	46±2
МС5-Е	41±1	46±1	C3S-ES	39±2	46±1
Р3-Е	41±2	48±1	L7-ES	39±2	46±2
Р2-Е	41±2	48±1	V7-ES	39±1	46±1
L12-E	39±2	47 ±2	i7L-E	40±1	48±1
Р6-Е	40±1	48±1	P2-ES	39±1	46±2

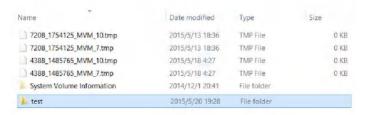
The measurement data were obtained under the test conditions employed at CHISON.

Note: Values following the "±"mark indicate the expanded uncertainty with a confidence lever of 95%, t.975=4.30.

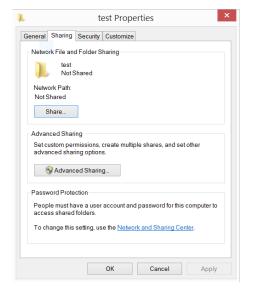
Appendix G: Procedures of set network sharing in EBit series

For Windows set up, set up a shared document

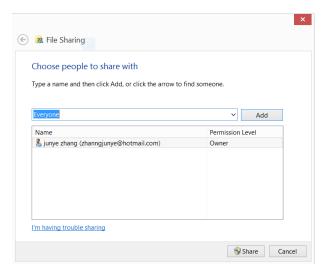
1. Choose the file you want to share, as the "test" file



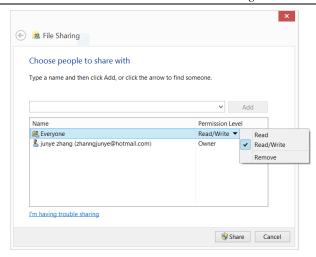
2. Right click this file, choose "properties", and click "share".



3. Then you can see the sharing setting interface, as you can see in the picture, choose "everyone", and click "add".

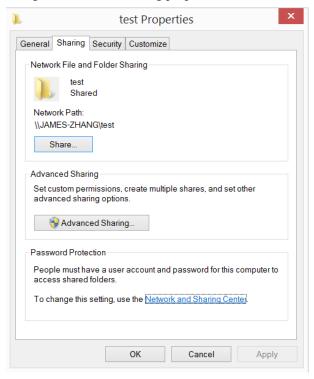


4. Choose "read/write" in the permission level in everyone, then click "share", after that, confirm.

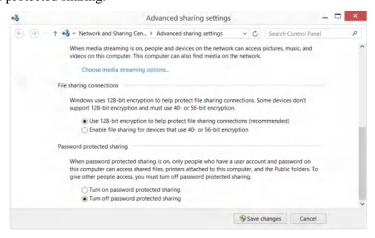


5. If the windows have not set the code, then turn off the password protected sharing is necessary. instructions as the image shows.

a)Click "network and sharing center" in the sharing properties.



b)In the network and sharing center interface, choose "public", in the password protected sharing, choose turn off password protected sharing.



Set up in EBit

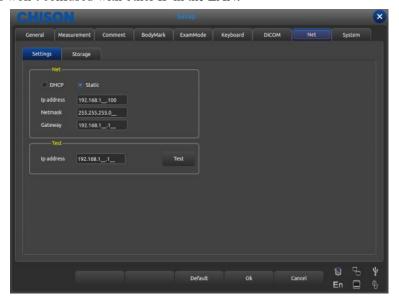
IP set up

1. First confirm the service address of shared files, you can get the IP address in windows interface. In windows "start"-"run" type in "cmd" and enter, then type in "ipconfig" and enter, you can see the IP address of local service.

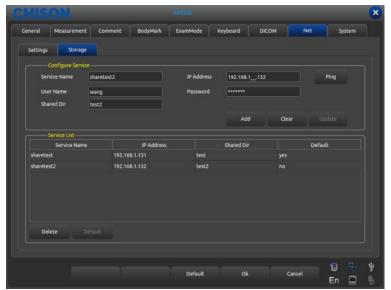
```
Connection=specific DNS Suffix :
LinF=Tocal IFV6 Address : : fe80: d31e:e058:f835:836d83
IFV4 Address : : 192.166.1.131
Subnet Mas : : 255 255 255 0
Default Gateway : : 192.168.1.1
```

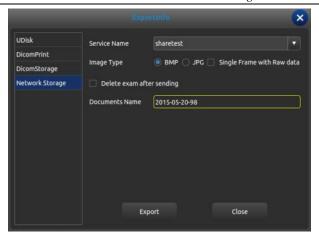
2.Enter into EBit set up interface, choose net. Choose "DHCP" (automatically get the IP address) or "static" (type in IP address manually);

TIP: if you want to type in IP address manually, make sure the IP address is in the same internet section with the service, and won't confused with other IP in the LAN.



3. Choose net "storage" interface, type in service name, IP address, user name, password and the name of shared files, click "add" to add a network storage, you can choose the export route. As shown in the picture.





ACAUTION:

Ping: test if the IP is connected or not.

Clear: clear all the IP address, user name, password and names of shared file

Update: update the content to the chosen item.

Delete: delete the chosen service item.

Default: set the chosen item as the default net route.

Notice: you can add multi-numbers of network storage service to realize the transmission among multi systems.

Notice: If windows turn off password protected sharing, then in EBit set up, you can type in user name and password arbitrarily.